

Depth First Search

- Cost Analysis**

Application of DFS

- Topological Sort**
- Finding Connected Component**
- Connectivity of a Graph**

Depth First Search

A method to traverse all the vertices of a given graph(directed or undirected)

Logic:

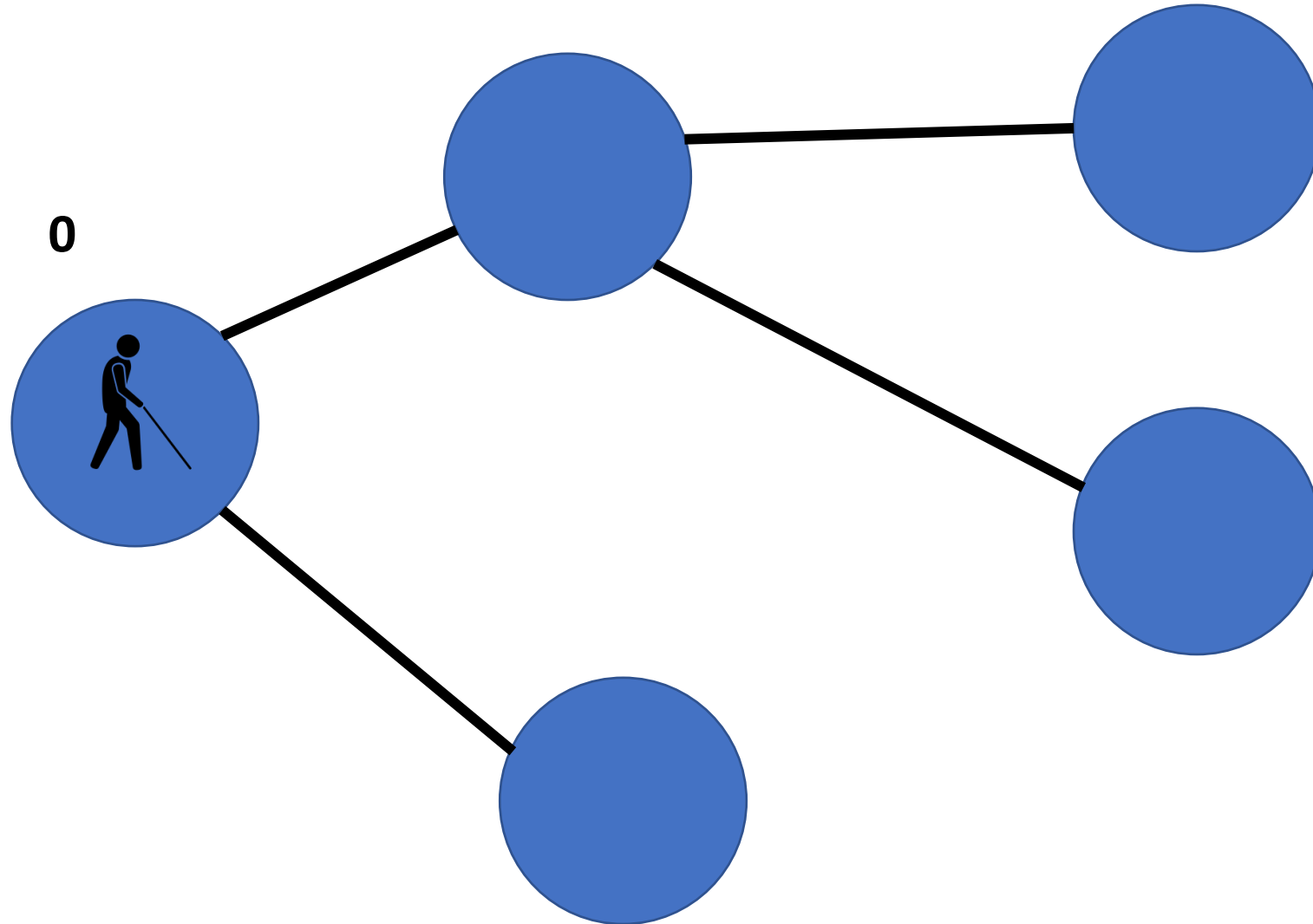
Goes deeper and deeper in one direction until it hits the dead end

Depth First Search

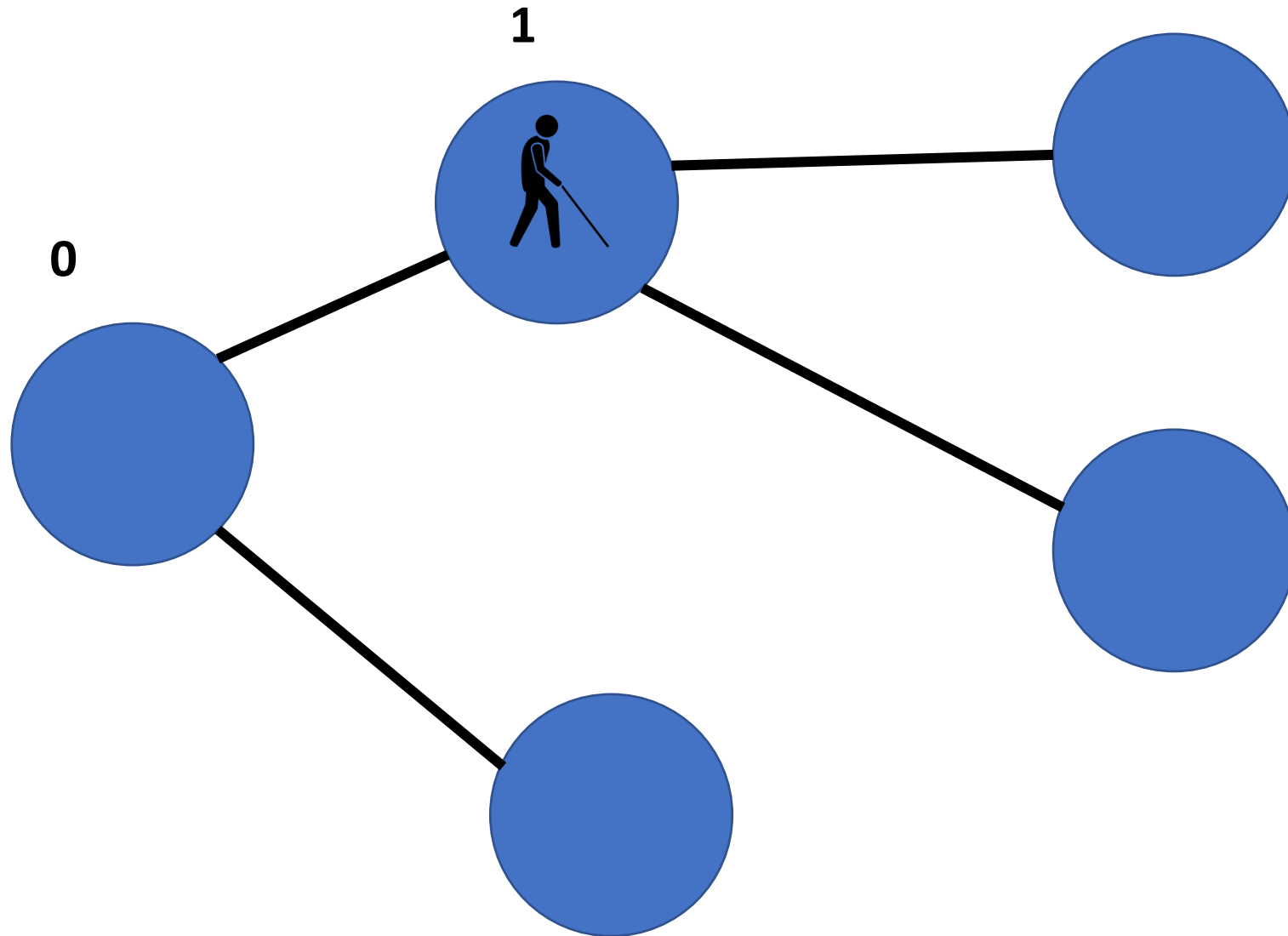
Similar to the way a blind person walk



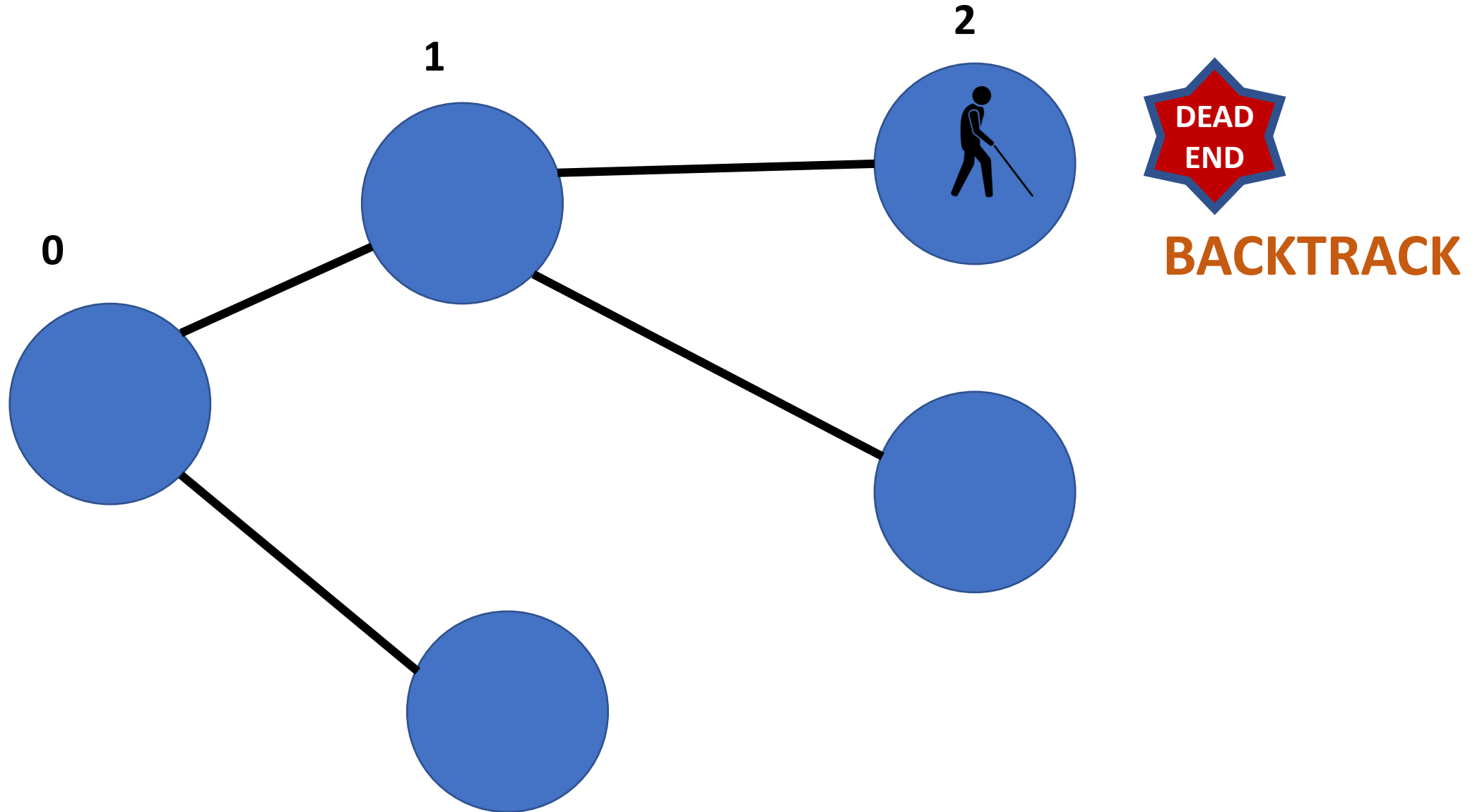
Depth First Search



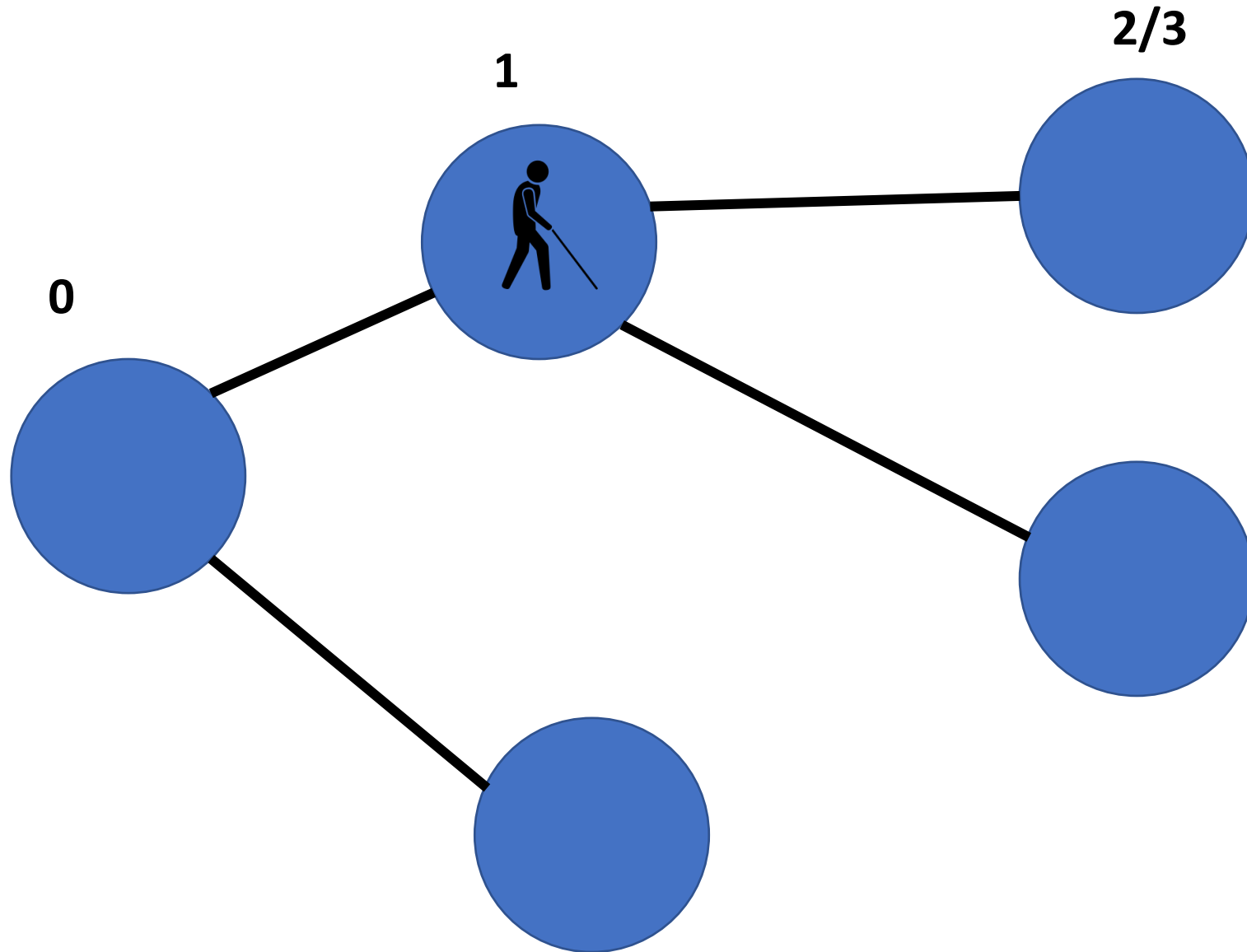
Depth First Search



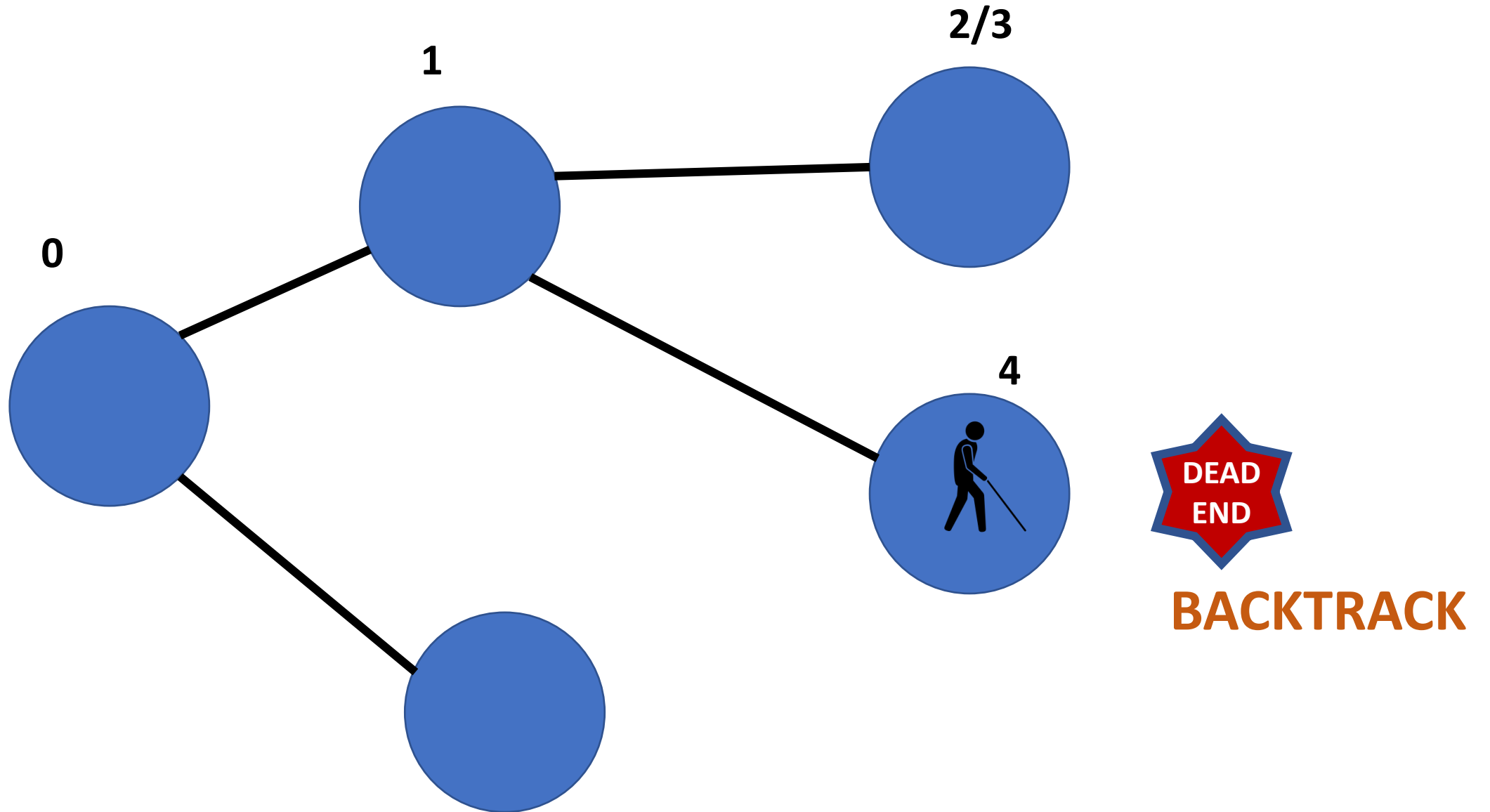
Depth First Search



Depth First Search



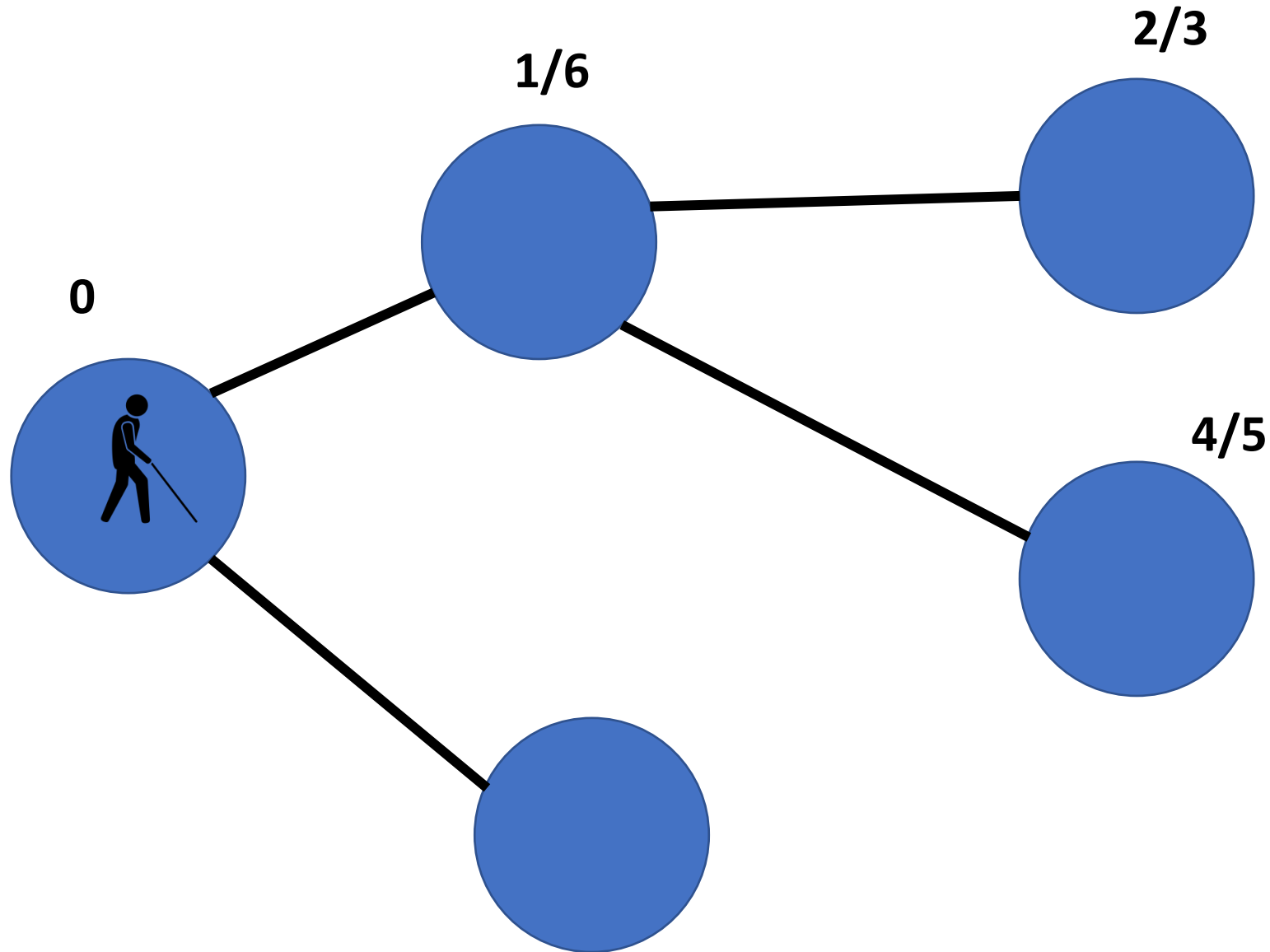
Depth First Search



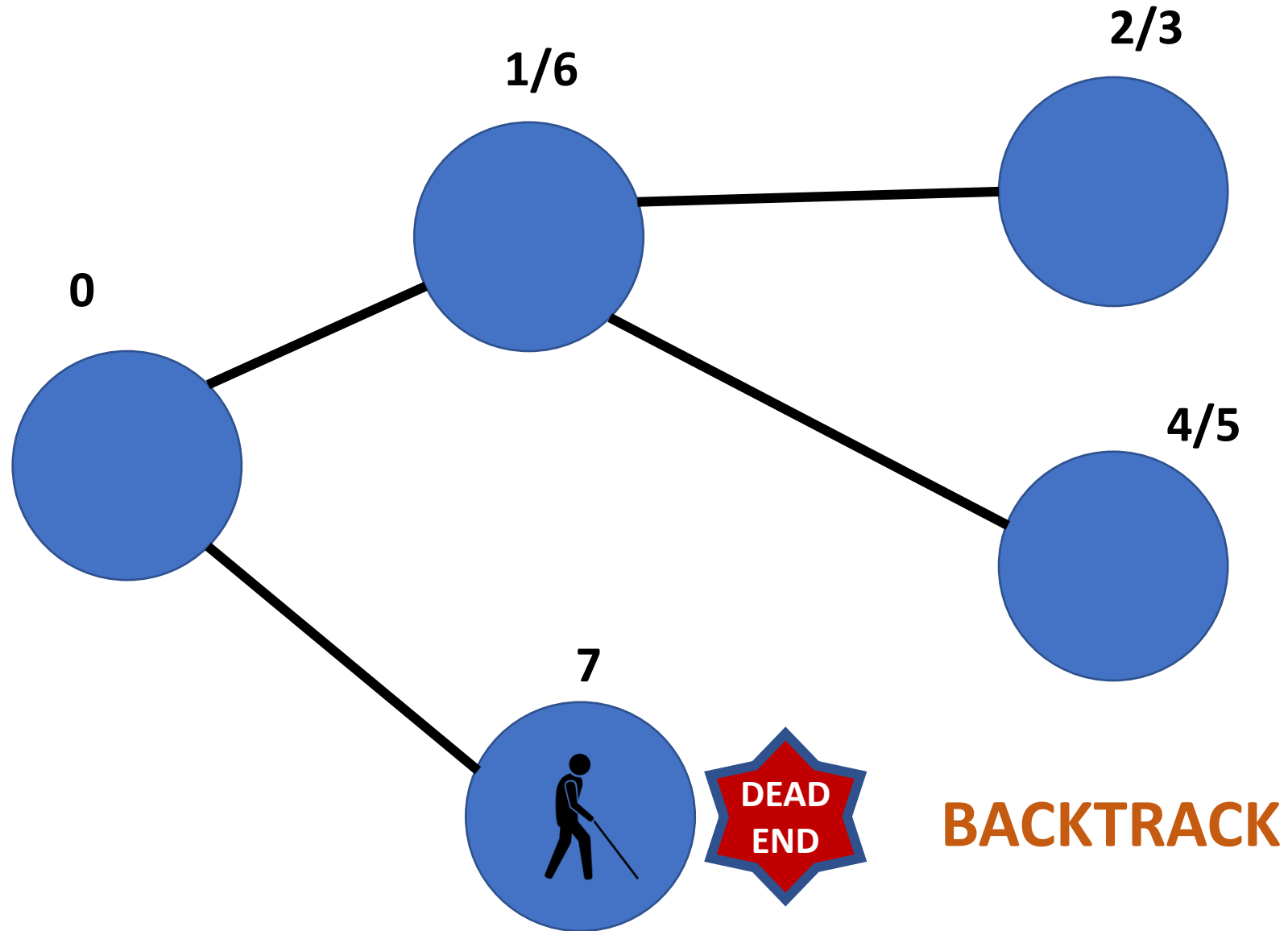
Depth First Search



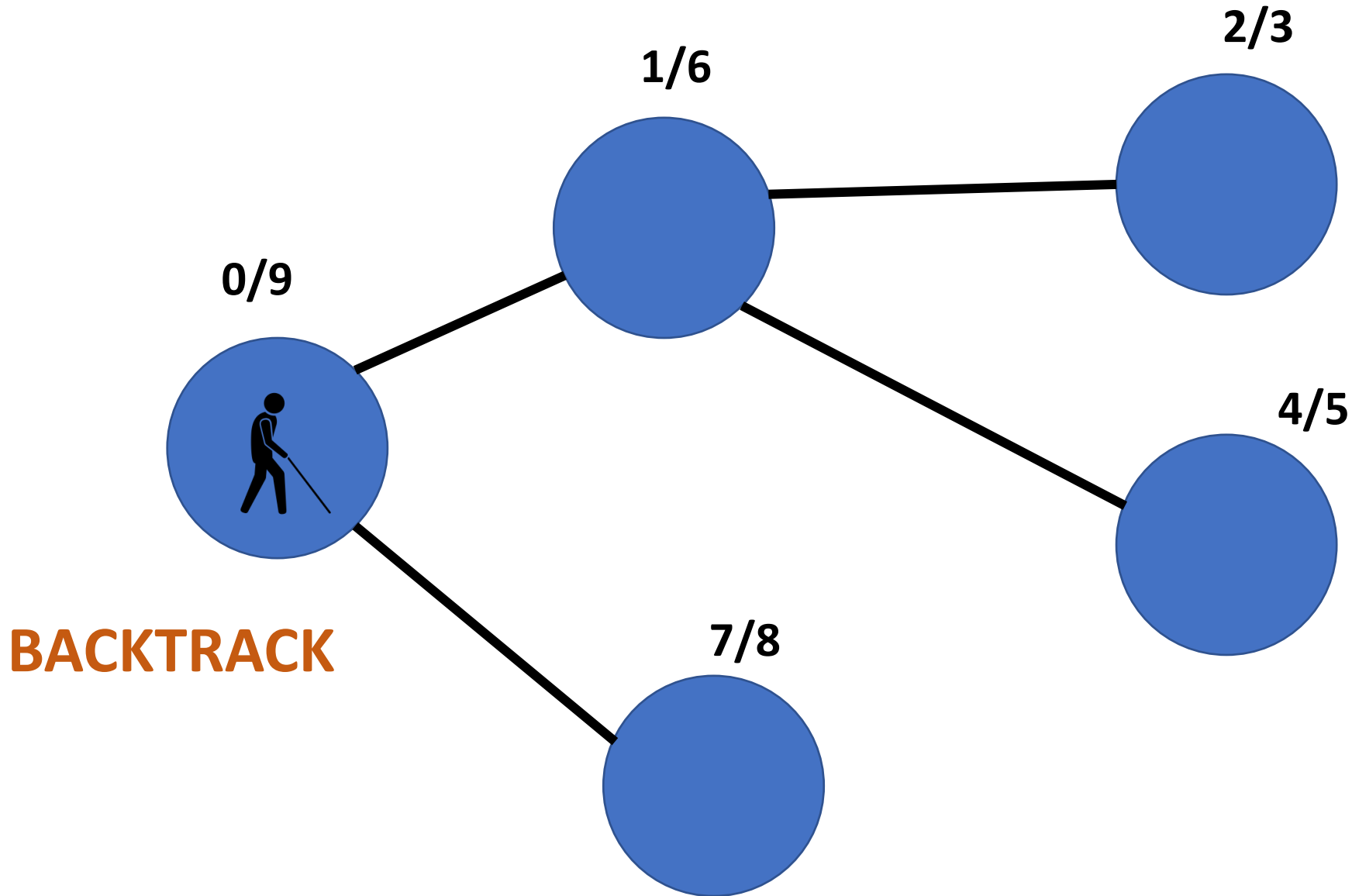
Depth First Search



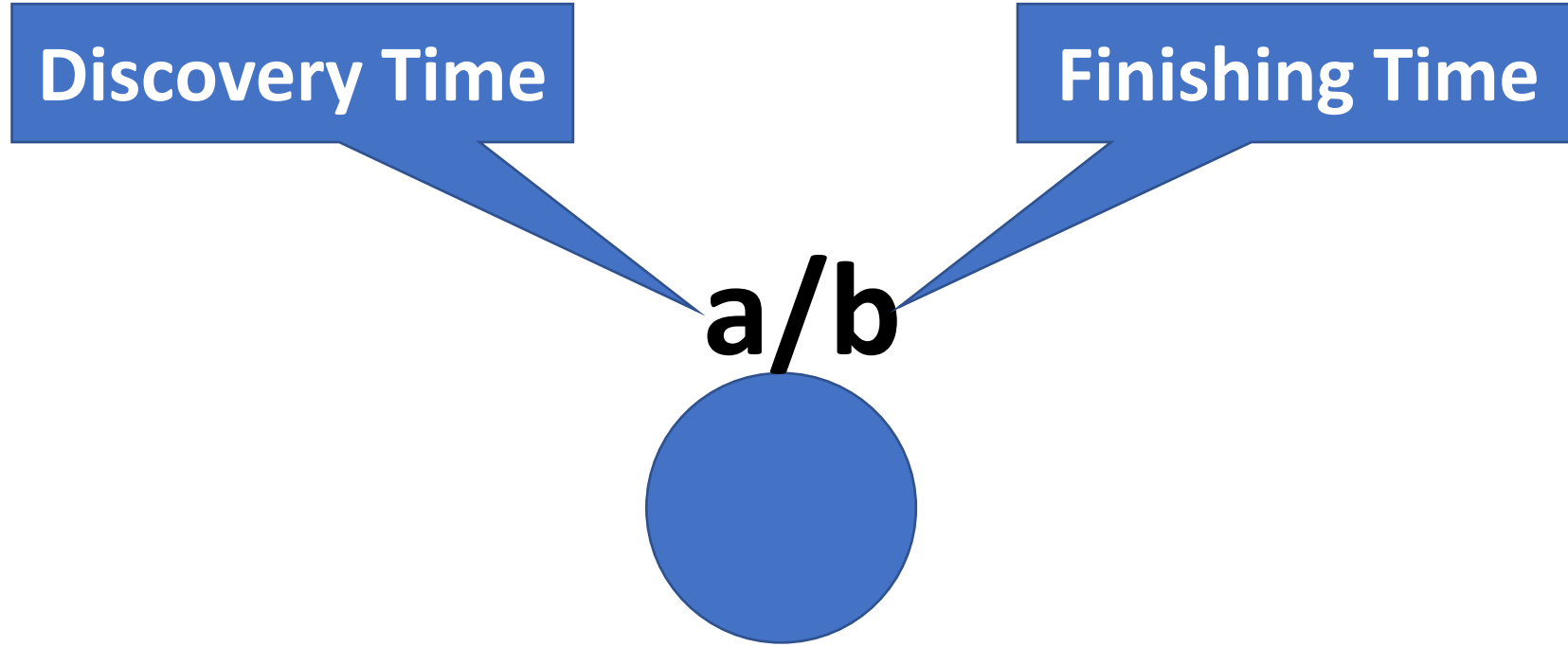
Depth First Search



Depth First Search

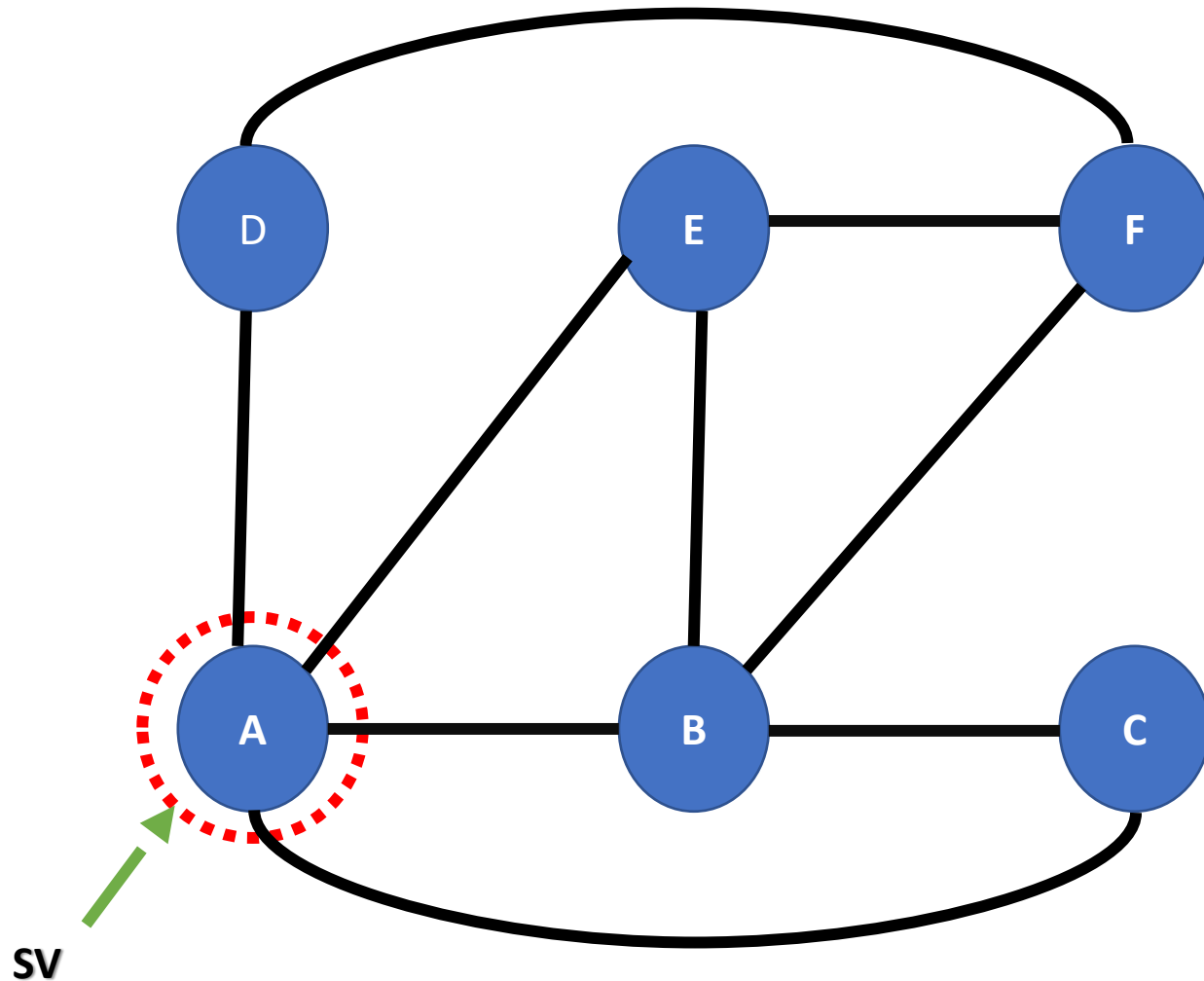


Depth First Search



Depth First Search

Let us consider the following graph

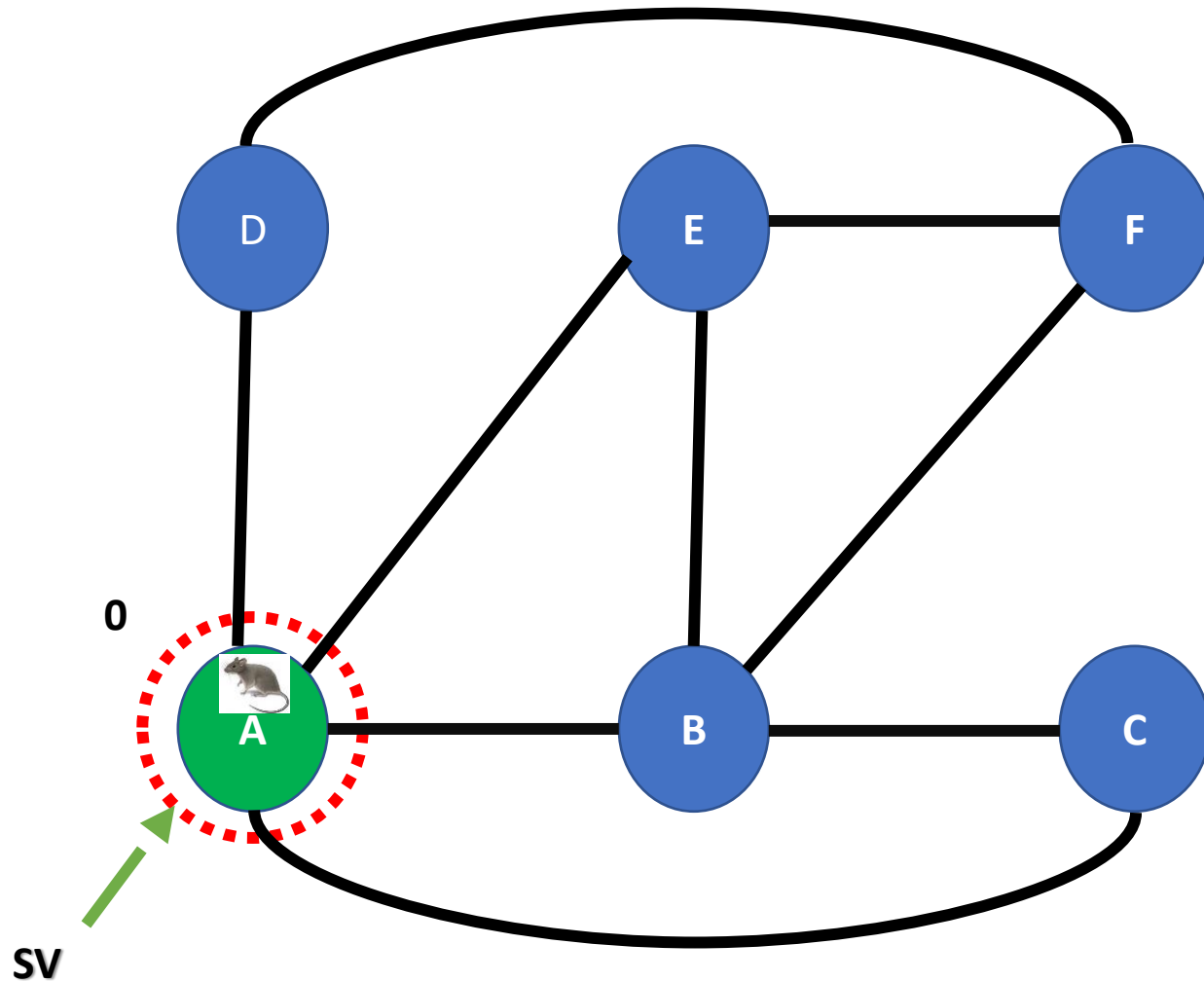


Visited

A	B	C	D	E	F
0	0	0	0	0	0

Depth First Search

Let us consider the following graph



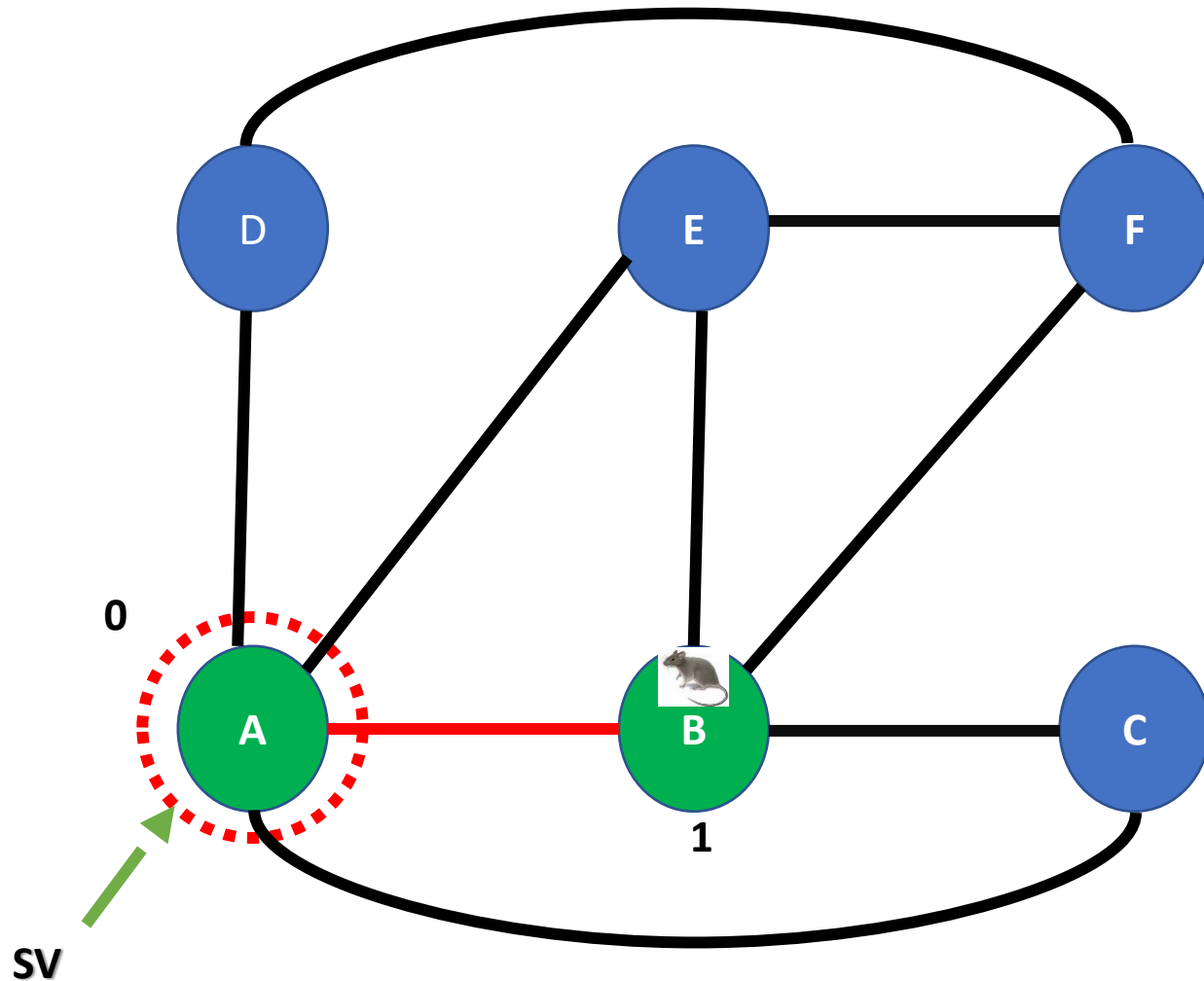
Visited

A	B	C	D	E	F
1	0	0	0	0	0



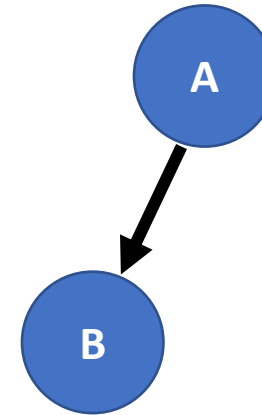
Depth First Search

Let us consider the following graph



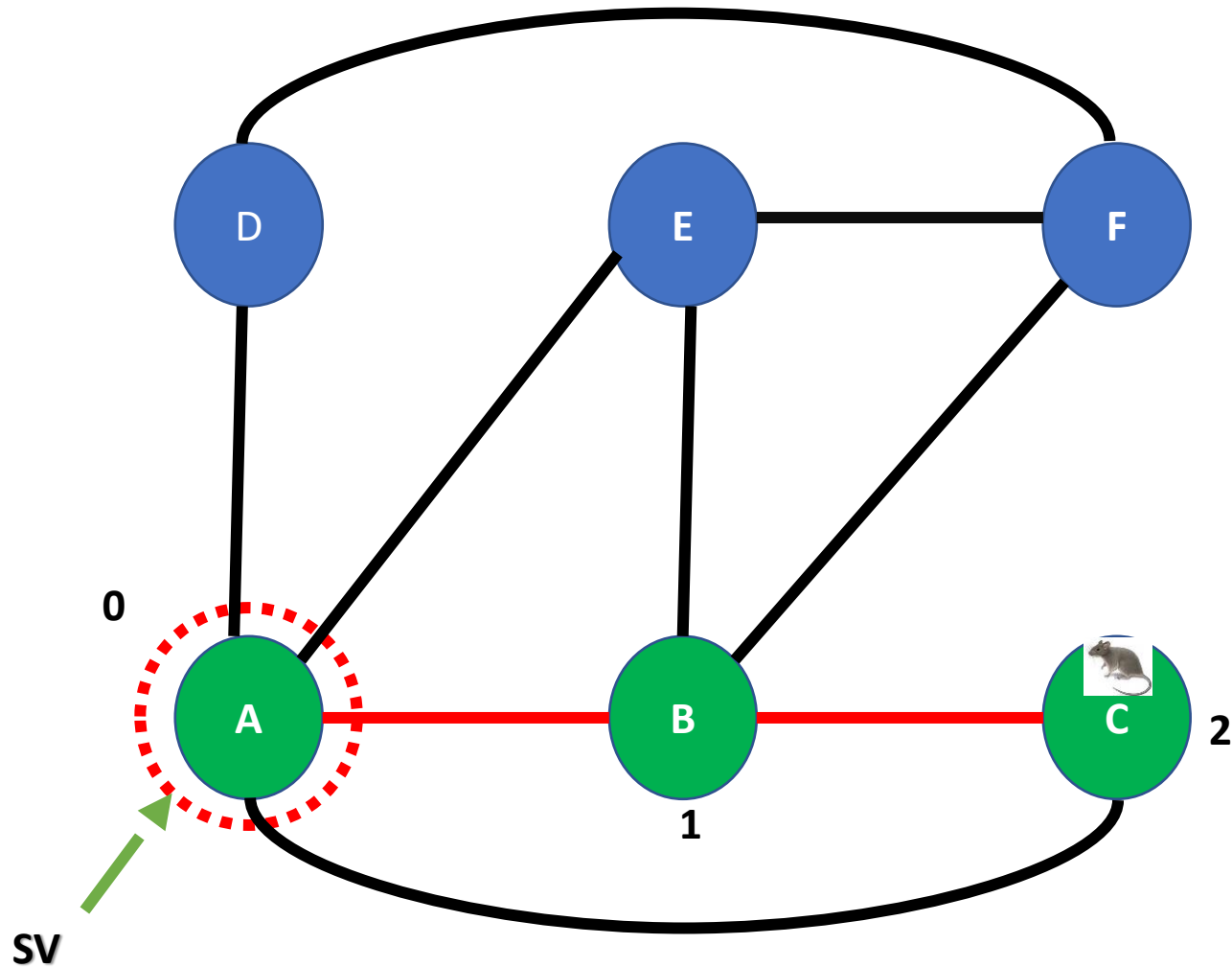
Visited

A	B	C	D	E	F
1	1	0	0	0	0



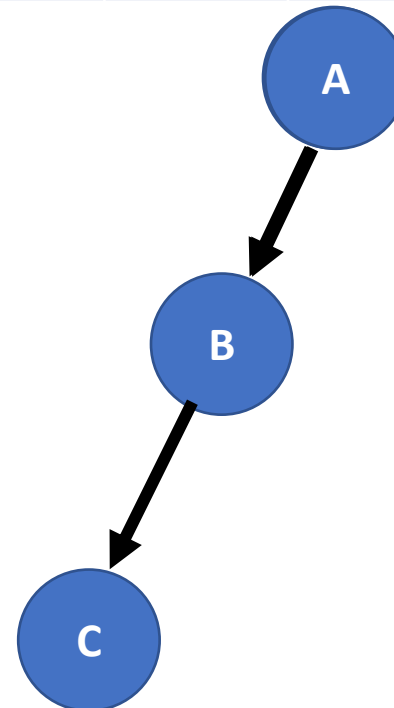
Depth First Search

Let us consider the following graph



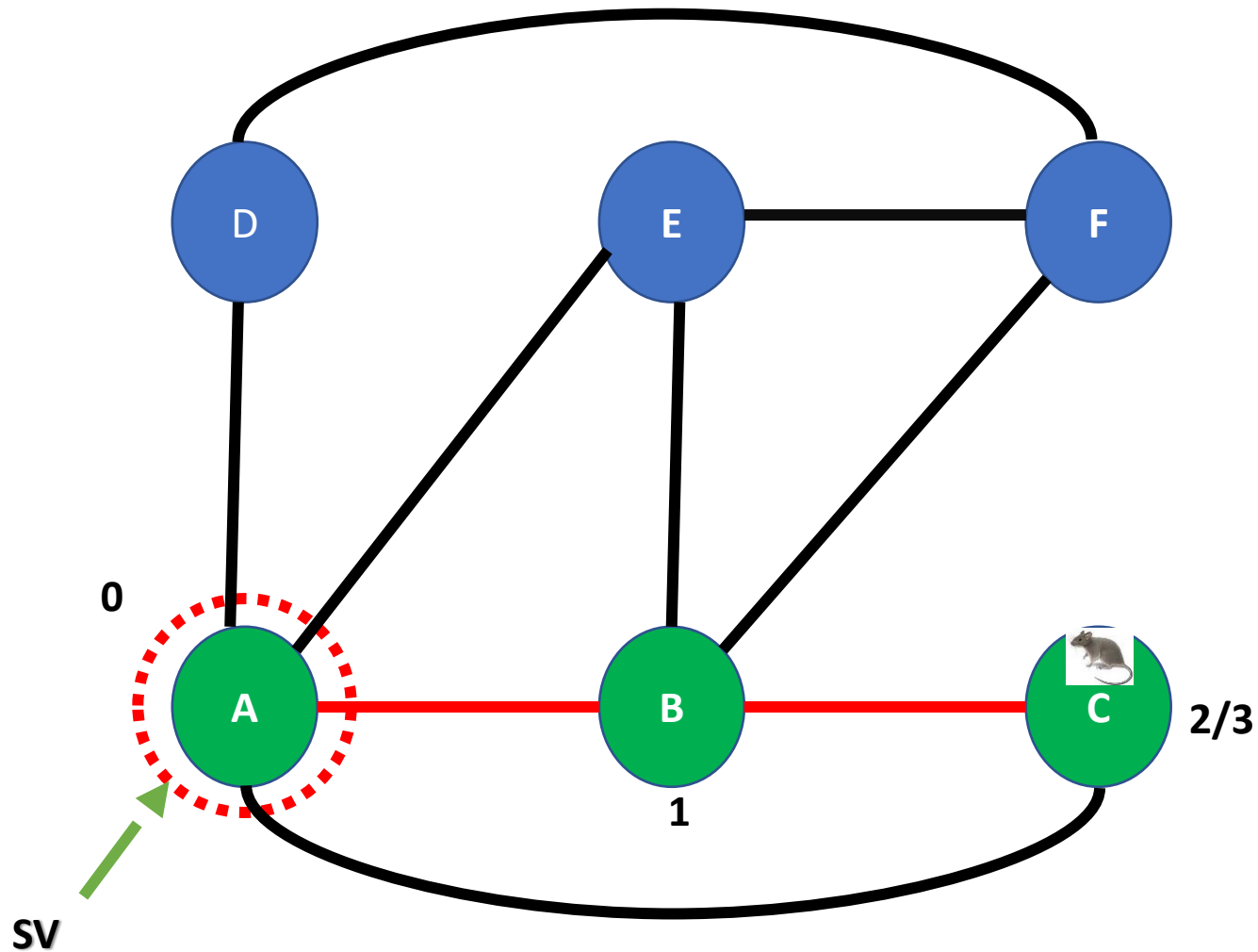
Visited

A	B	C	D	E	F
1	1	1	0	0	0



Depth First Search

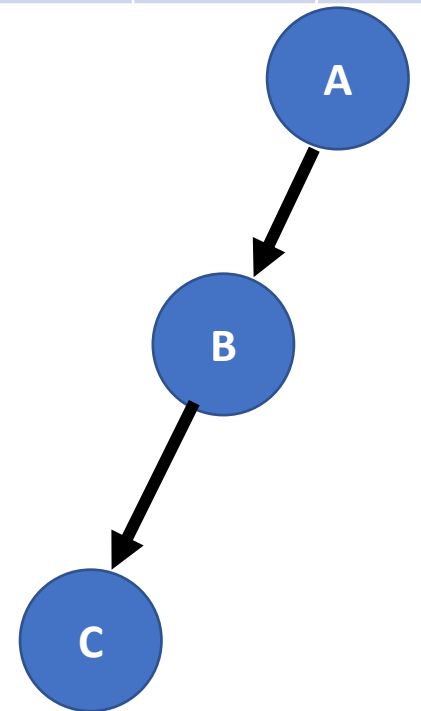
Let us consider the following graph



Visited

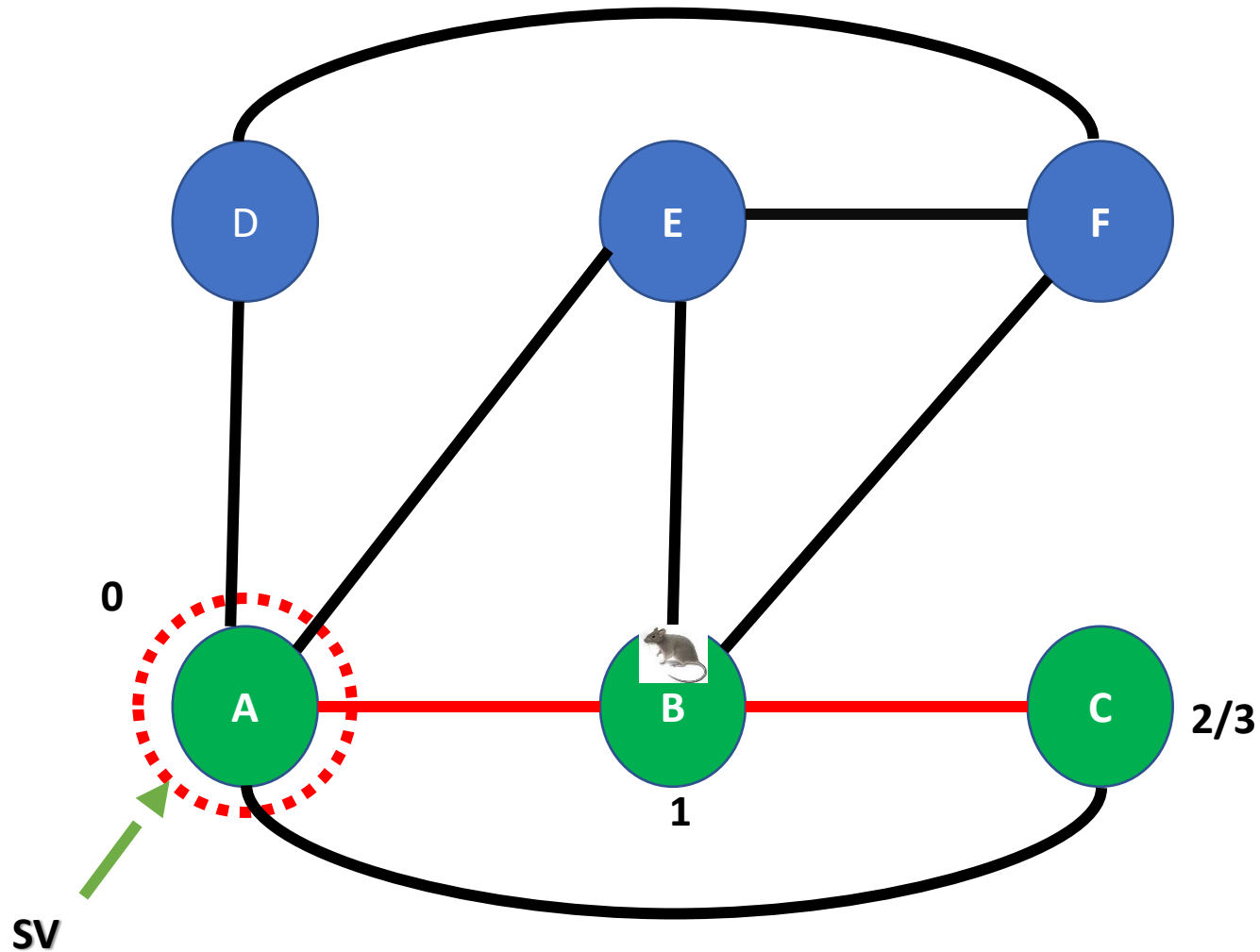
A	B	C	D	E	F
1	1	1	0	0	0

BACKTRACK



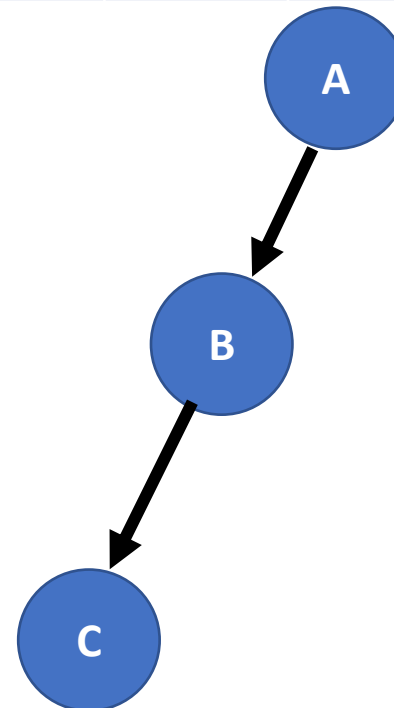
Depth First Search

Let us consider the following graph



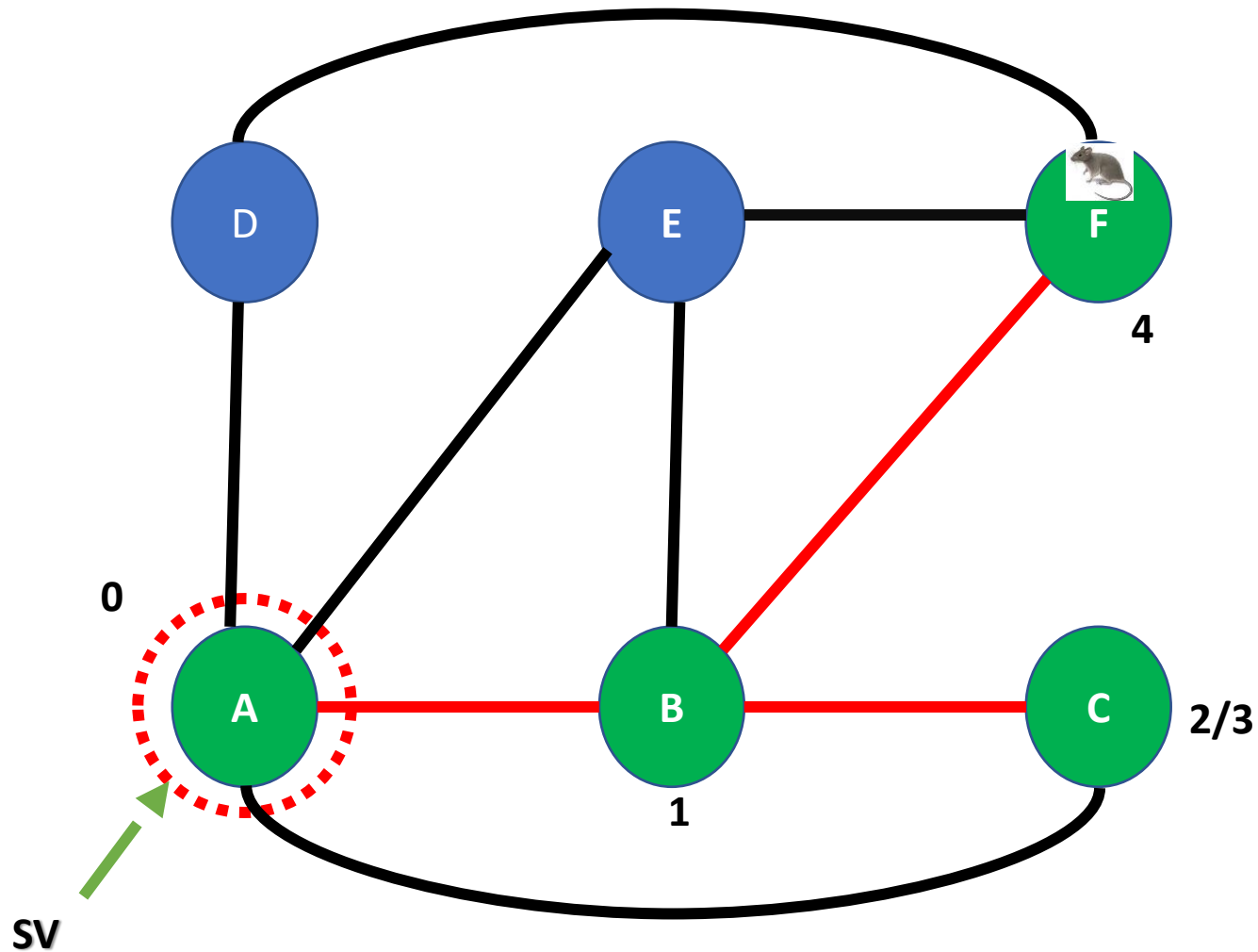
Visited

A	B	C	D	E	F
1	1	1	0	0	0



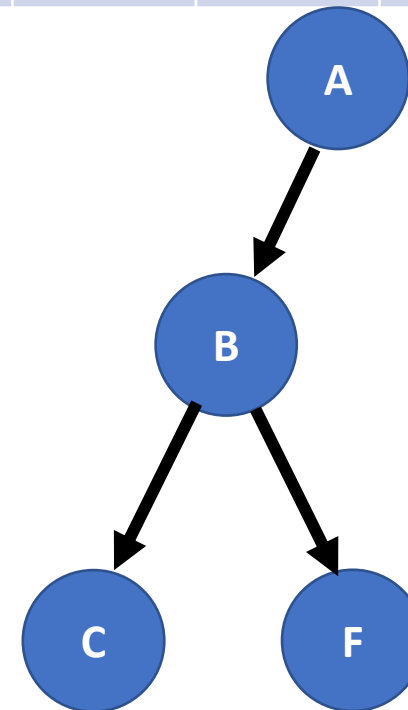
Depth First Search

Let us consider the following graph



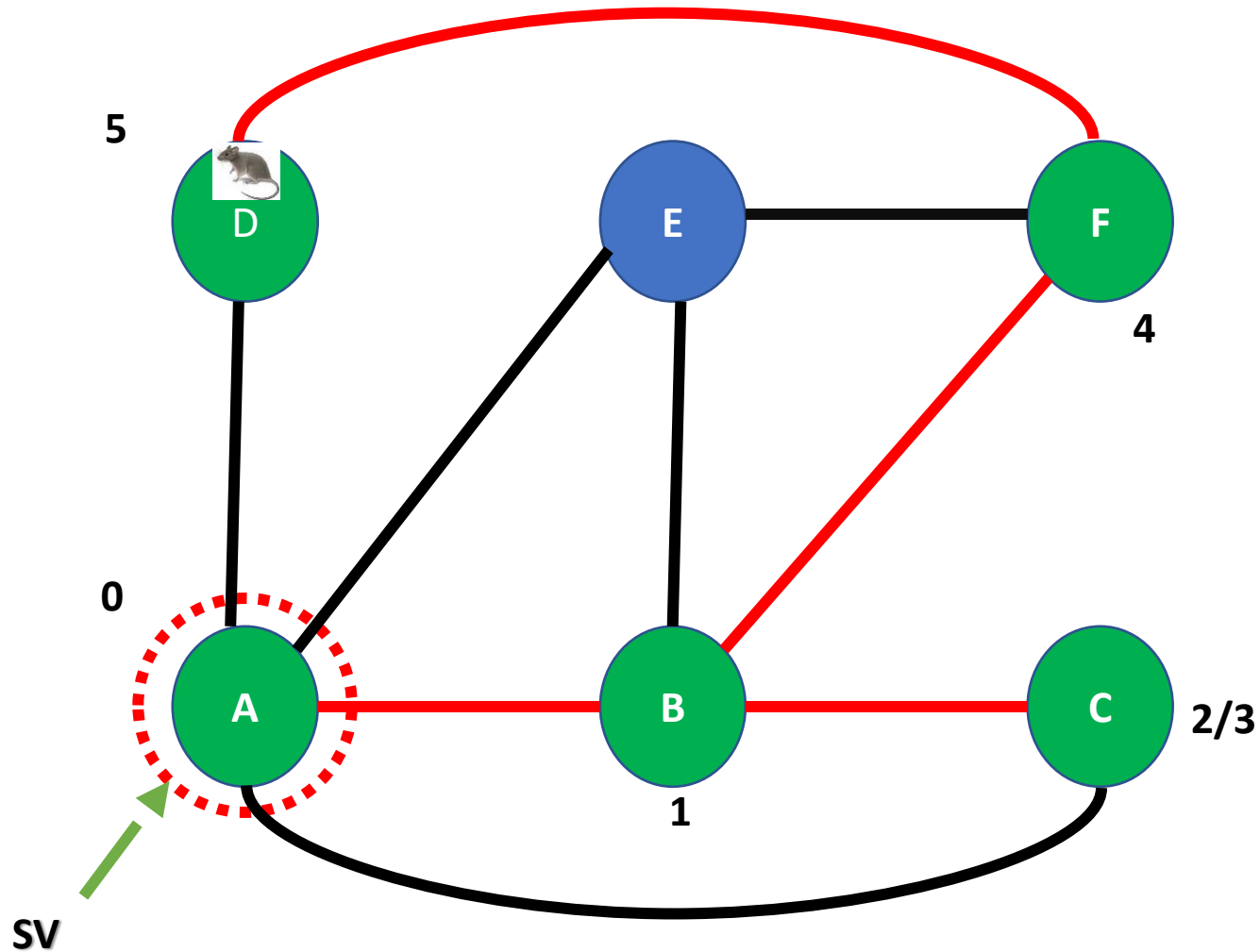
Visited

A	B	C	D	E	F
1	1	1	0	0	1



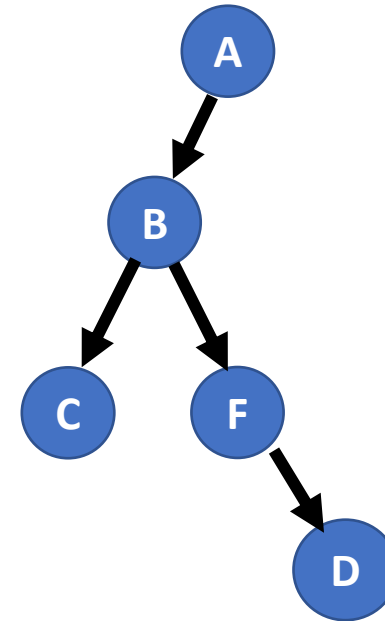
Depth First Search

BACKTRACK

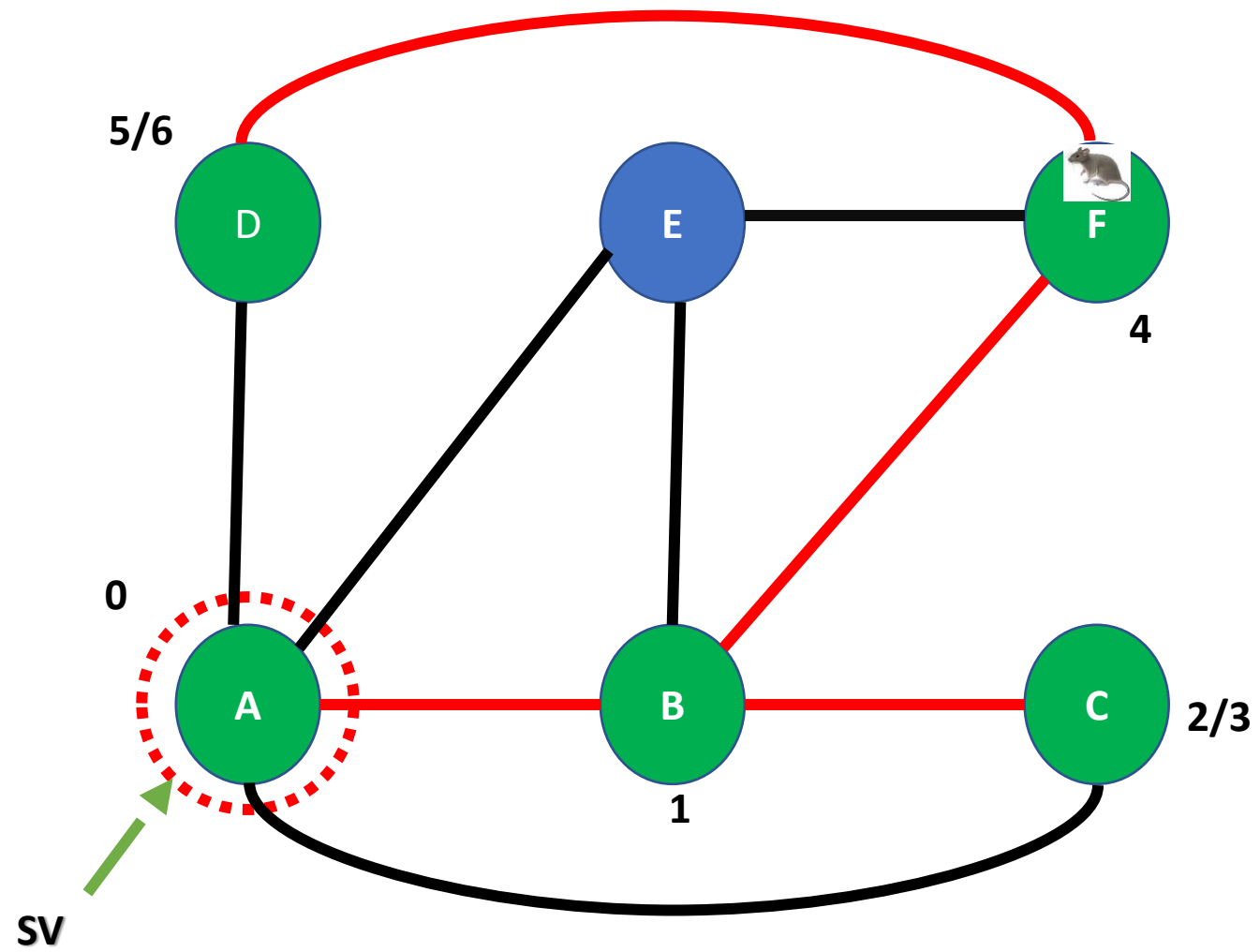


Visited

A	B	C	D	E	F
1	1	1	1	0	1

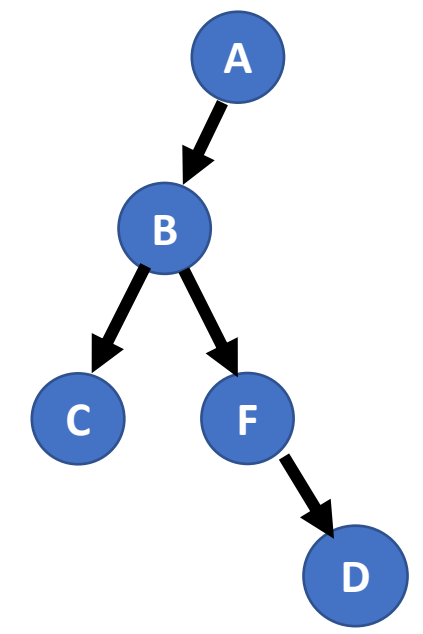


Depth First Search



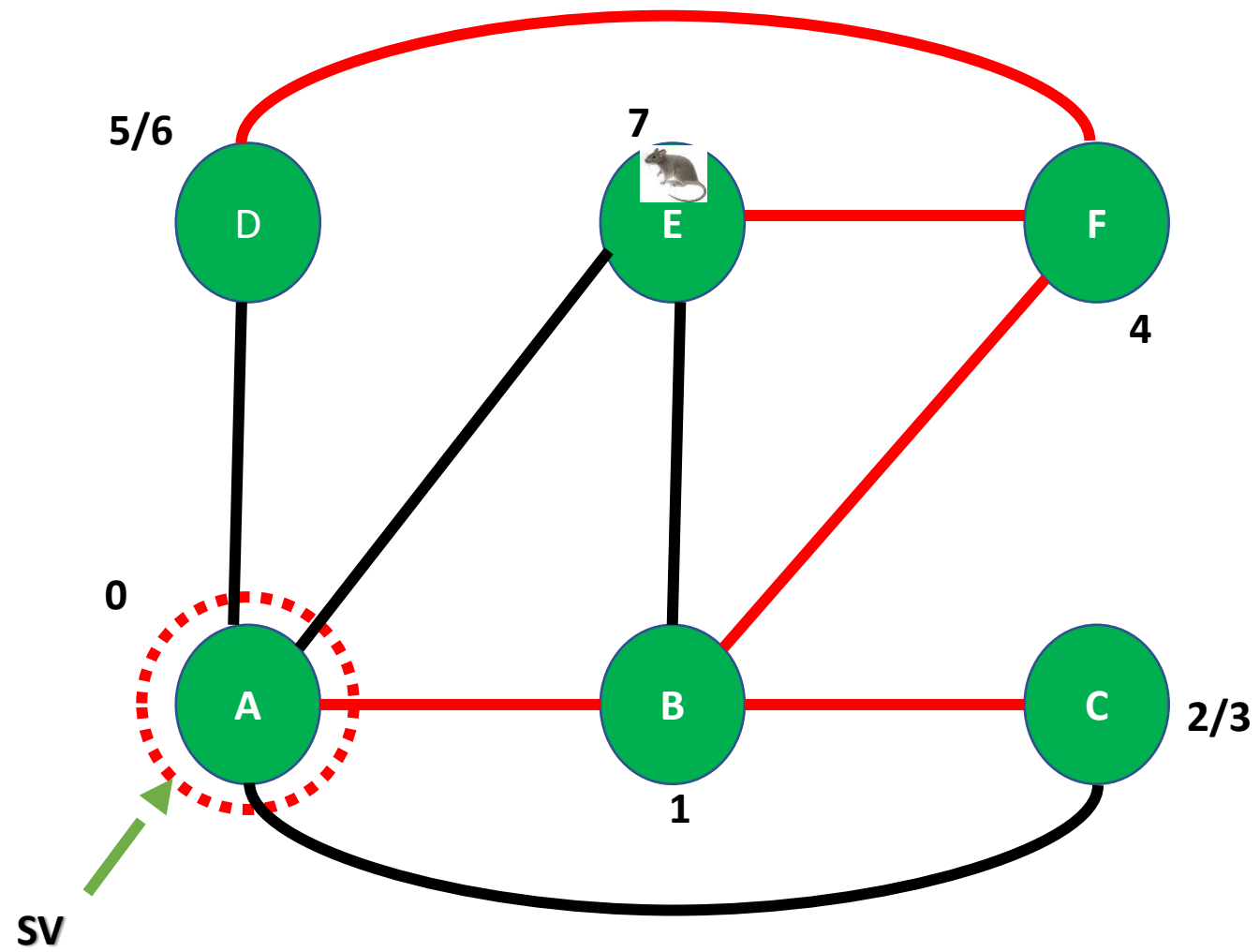
Visited

A	B	C	D	E	F
1	1	1	1	0	1



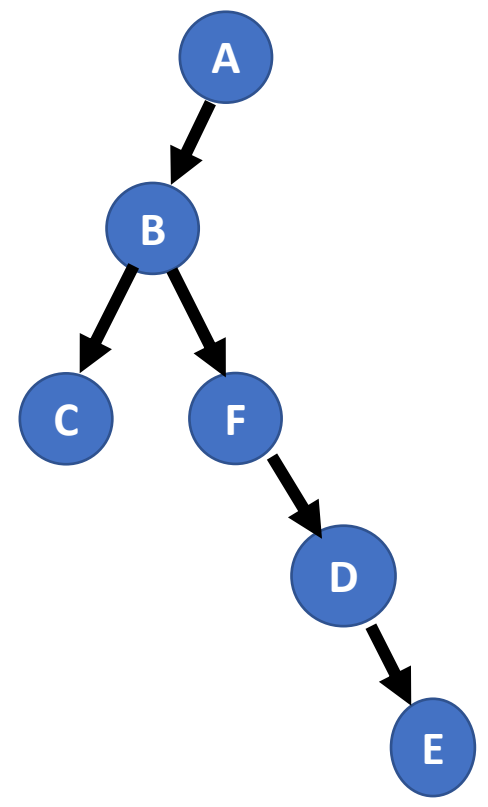
Depth First Search

BACKTRACK



Visited

A	B	C	D	E	F
1	1	1	1	1	1

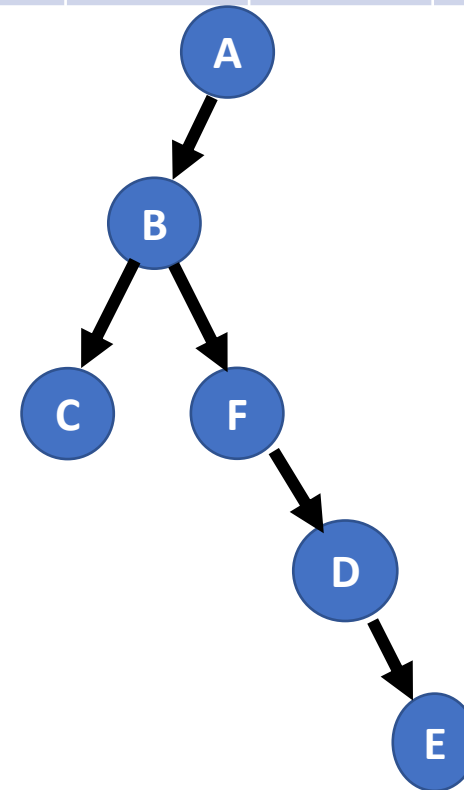
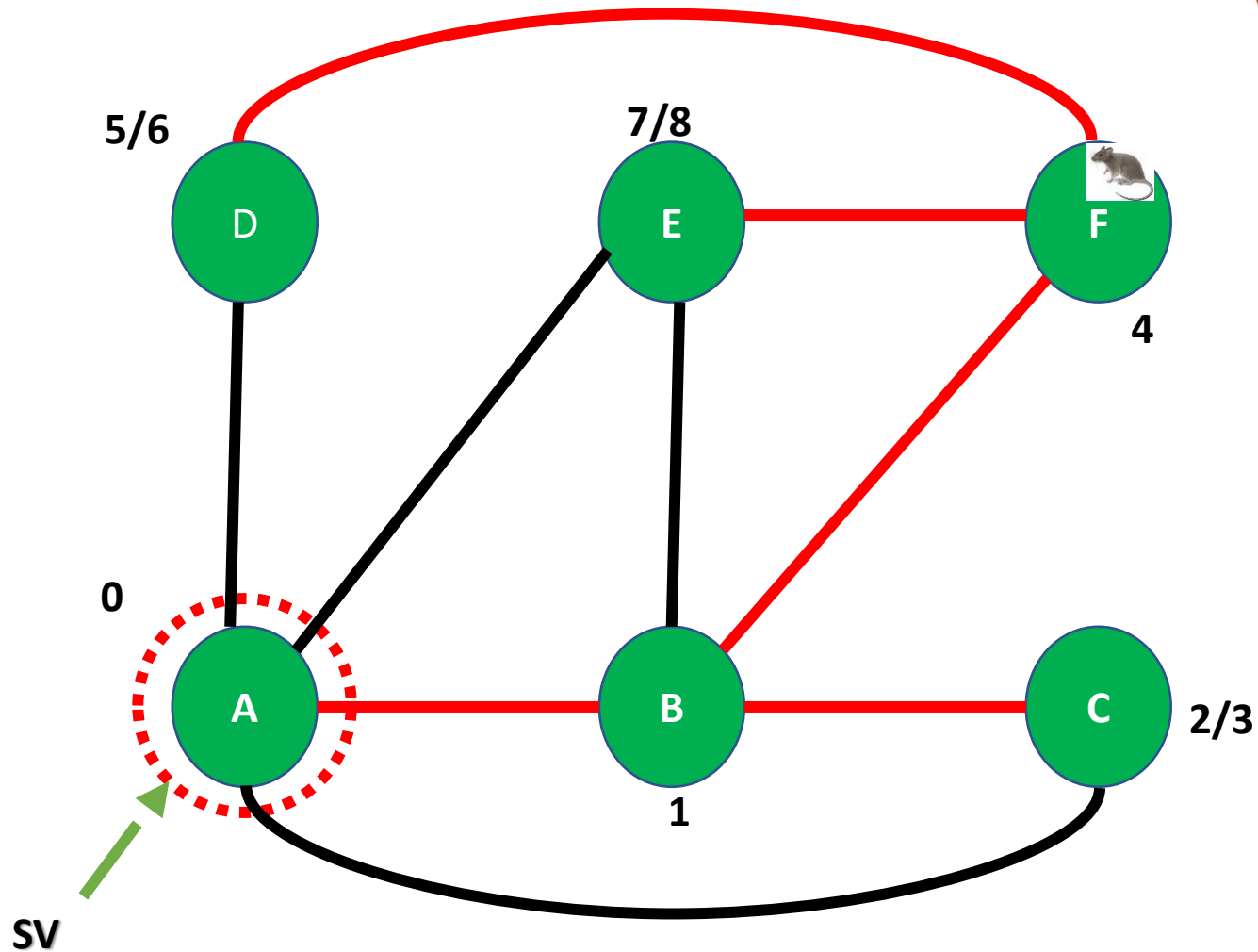


Depth First Search

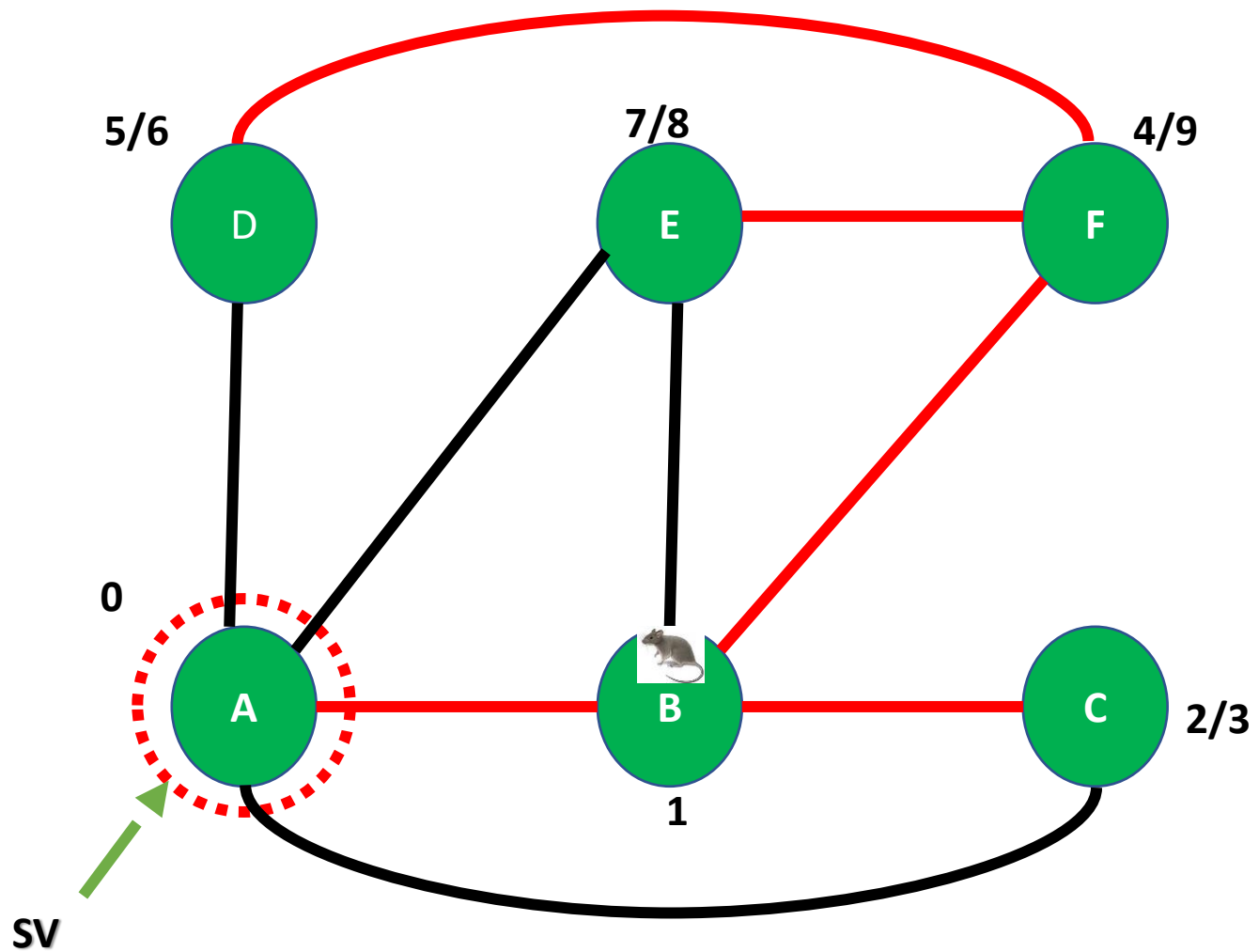
BACKTRACK

Visited

A	B	C	D	E	F
1	1	1	1	1	1



Depth First Search

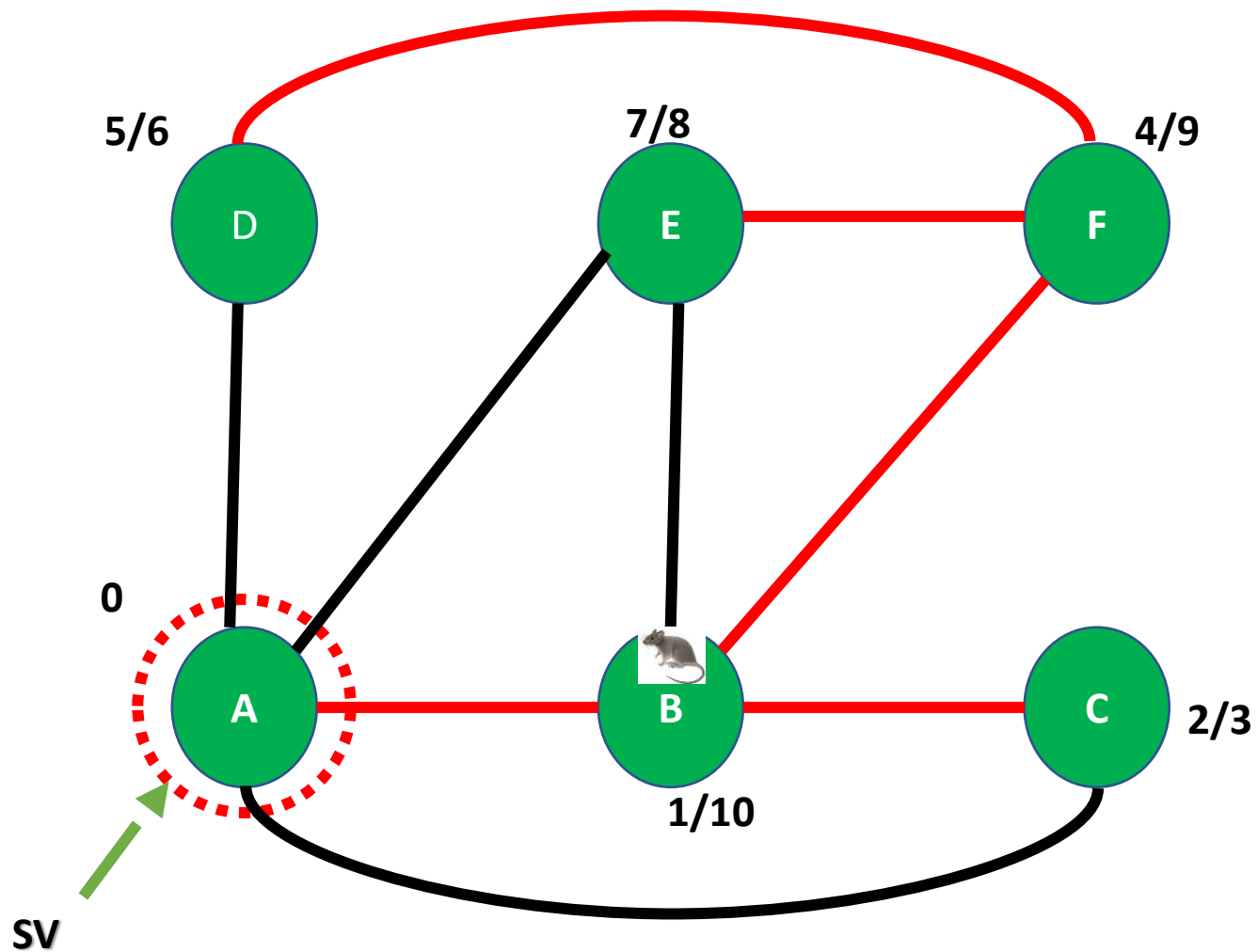


Visited

A	B	C	D	E	F
1	1	1	1	1	1

BACKTRACK

Depth First Search

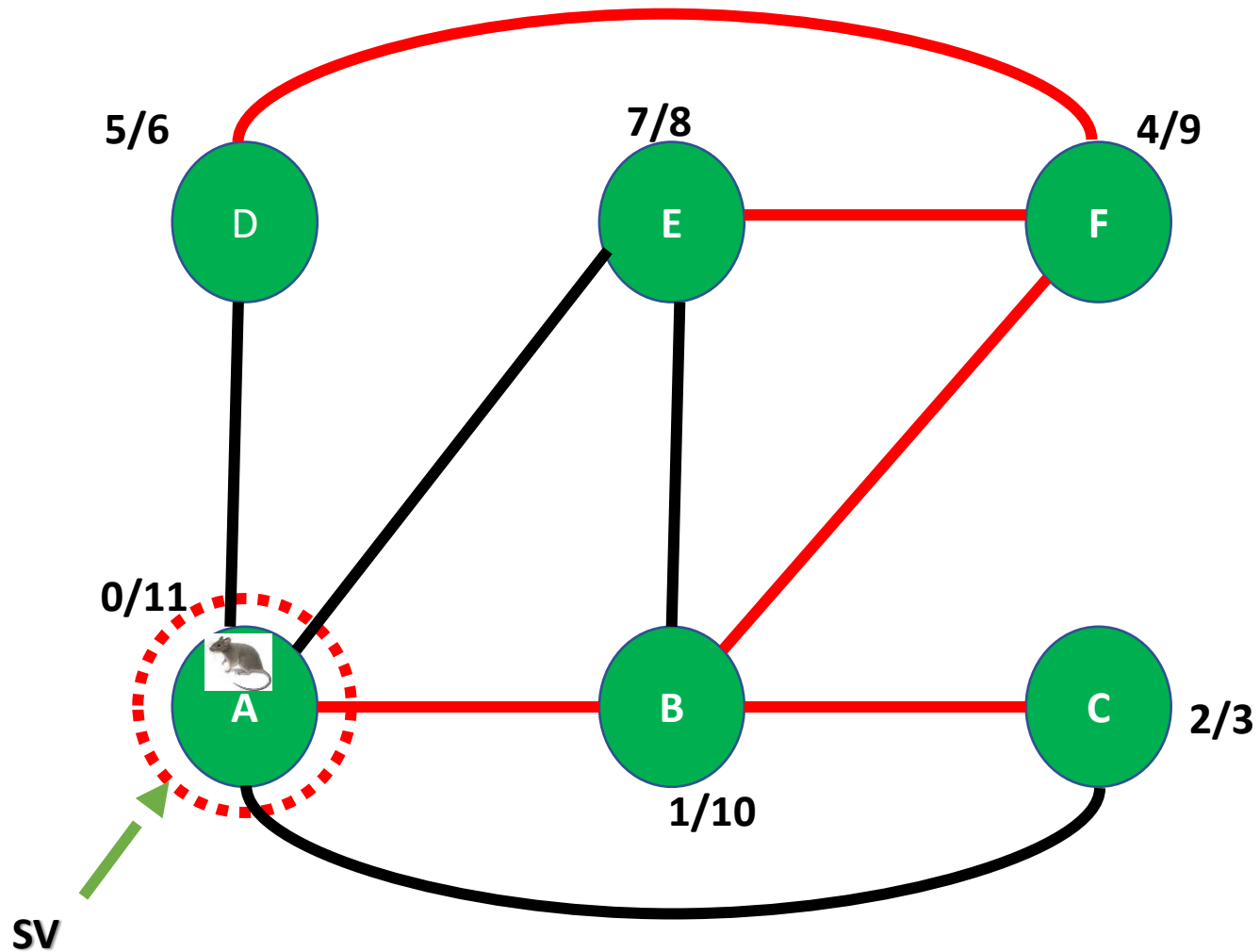


Visited

A	B	C	D	E	F
1	1	1	1	1	1

BACKTRACK

Depth First Search



Visited

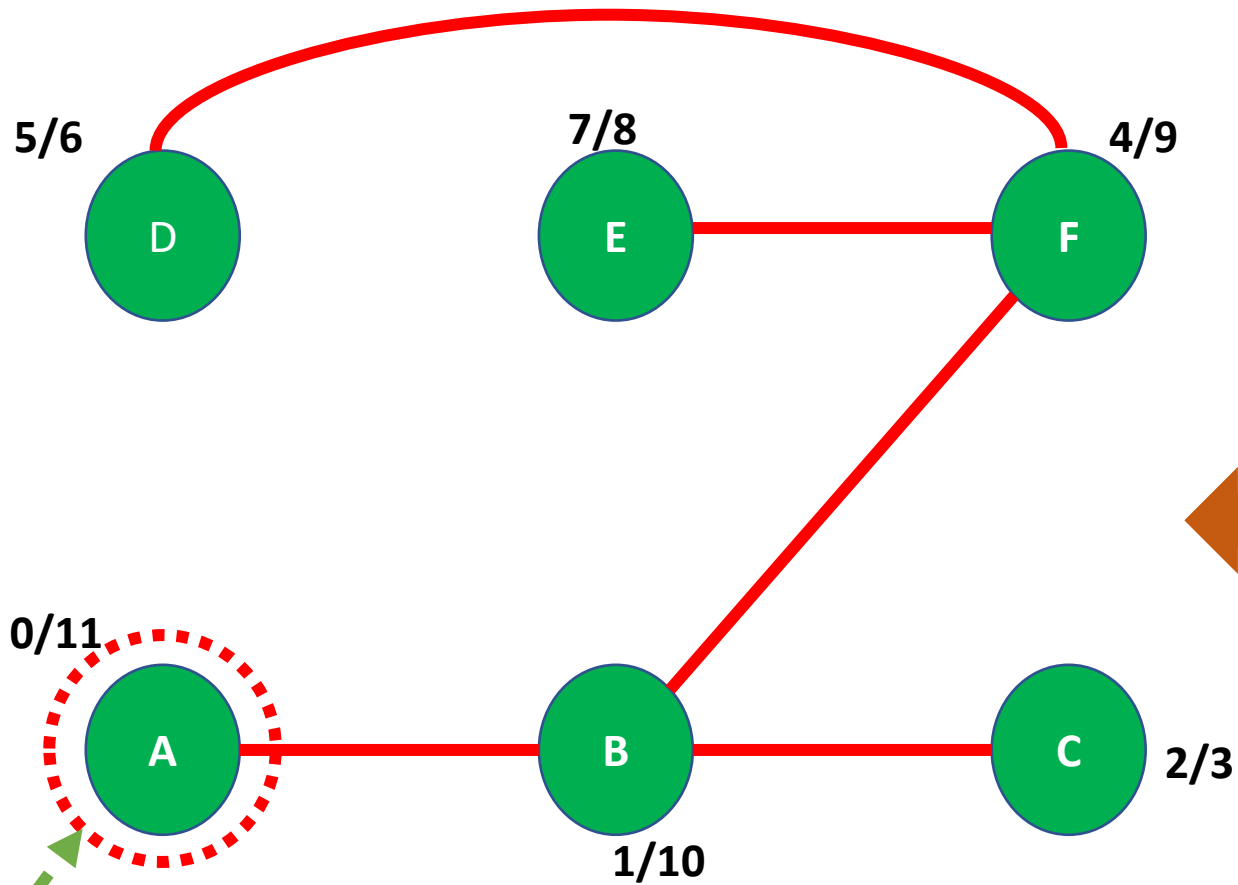
A	B	C	D	E	F
1	1	1	1	1	1

BACKTRACK

Depth First Search

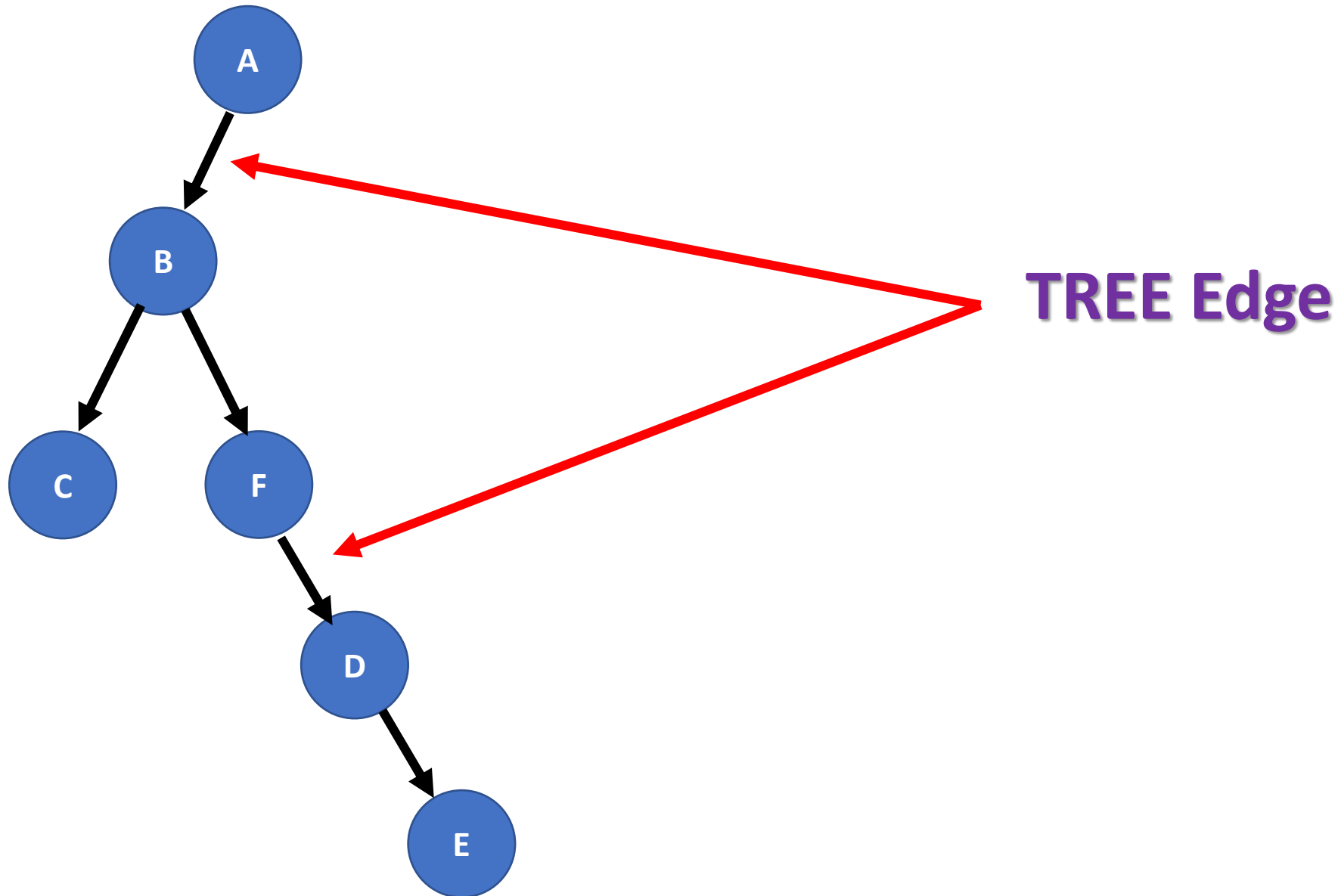
DFS traversal

A, B, C, F, D, E

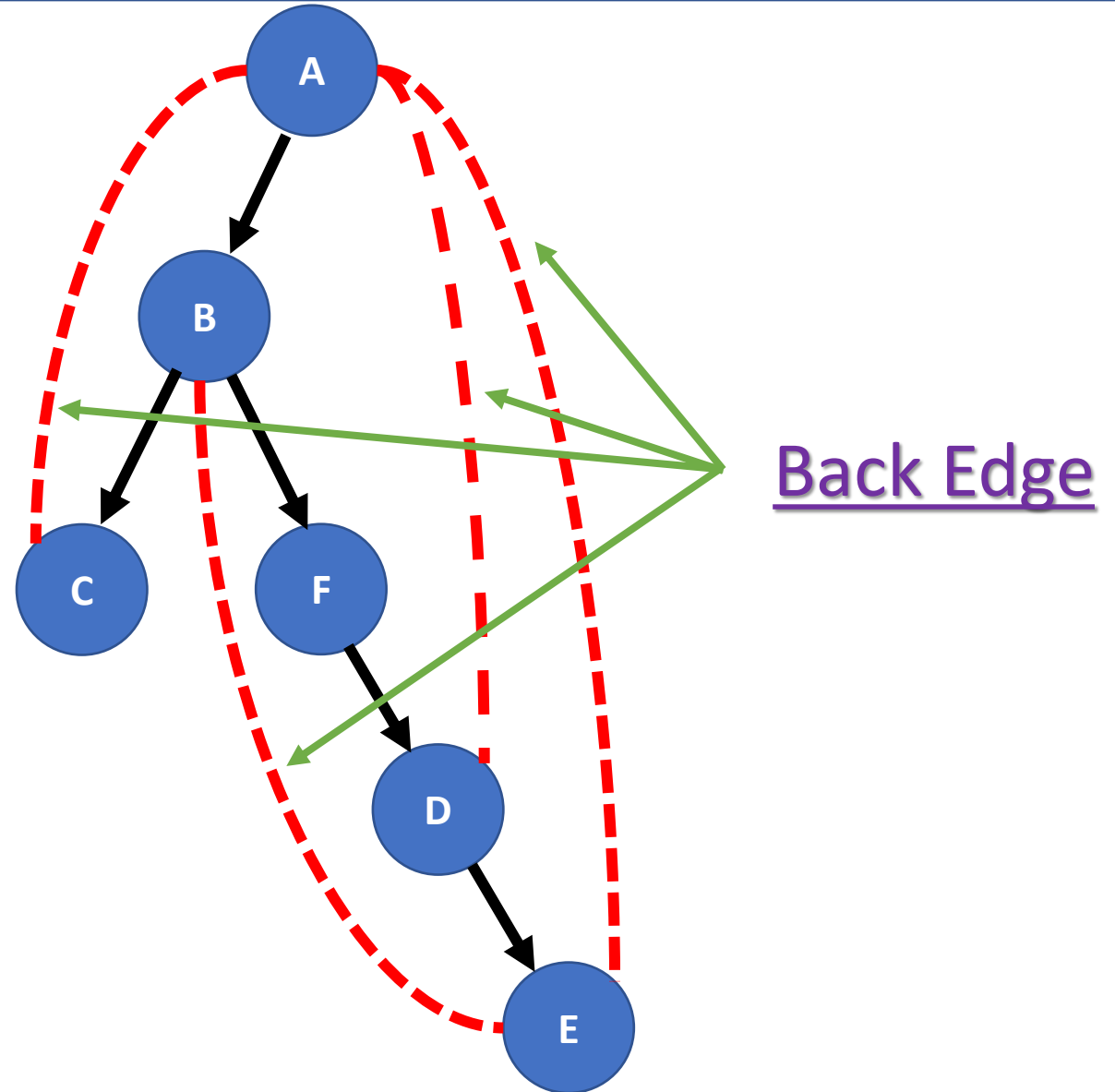
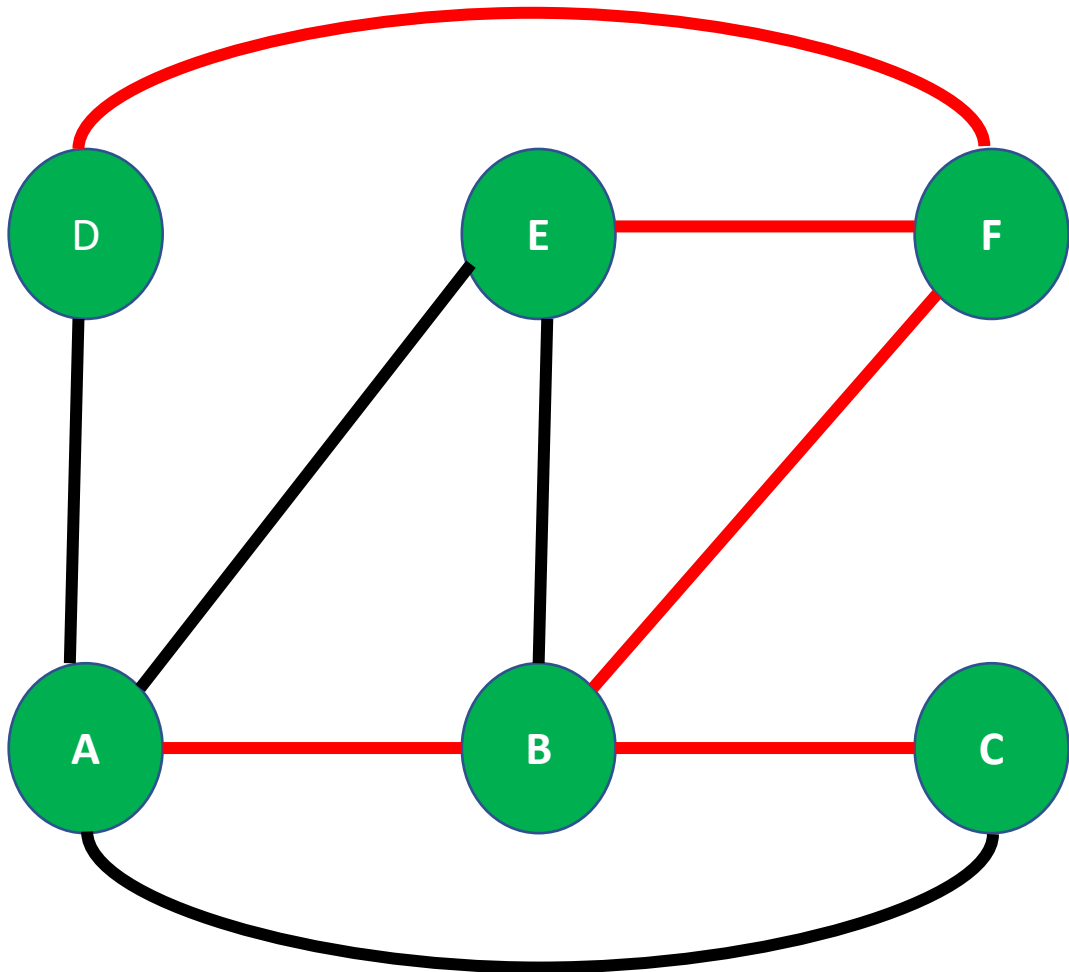


DFS Spanning TREE

Depth First Search



Depth First Search



Depth First Search

Algorithm DFS(v)

// Given undirected(directed) graph $G=(V,E)$ with n vertices and an array
//visited[] initially set to 0 this algorithm visits all vertices reachable
//from v and visited[] are global.

```
{  
    visited[v] = 1  
    for each vertex w adjacent to v do  
        {  
            if ( visited[w] == 0) then DFS(w)  
        }  
}
```

Depth First Search

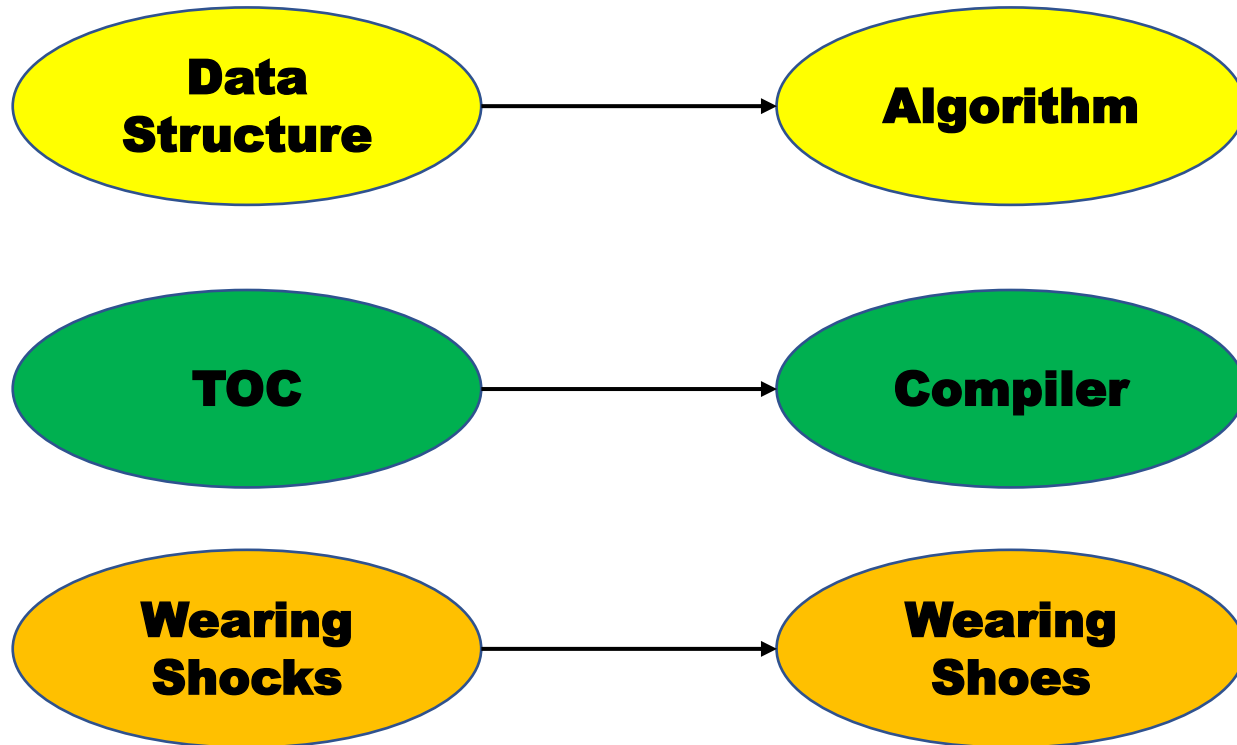
Algorithm DFS(v)

// Given undirected(directed) graph $G=(V,E)$ with n vertices and an array
// visited[] initially set to 0 this algorithm visits all vertices reachable
// from v and visited[] are global.

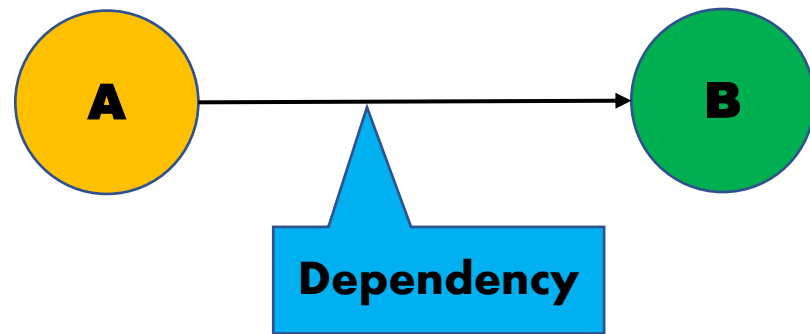
```
{  
    visited[v] = 1  
    for each vertex w adjacent to v do  
        {  
            if ( visited[w] == 0) then DFS(w)  
        }  
}
```

Time Complexity = $O(V + E) = O(E)$

Dependent Event



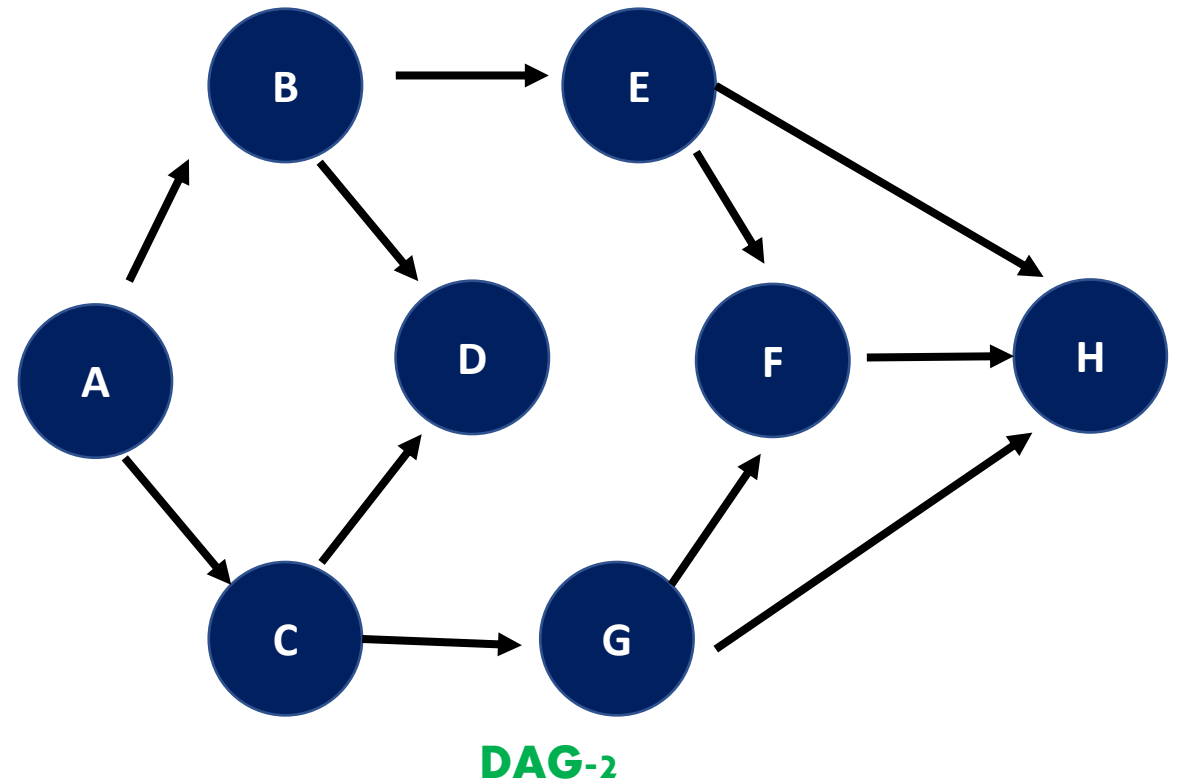
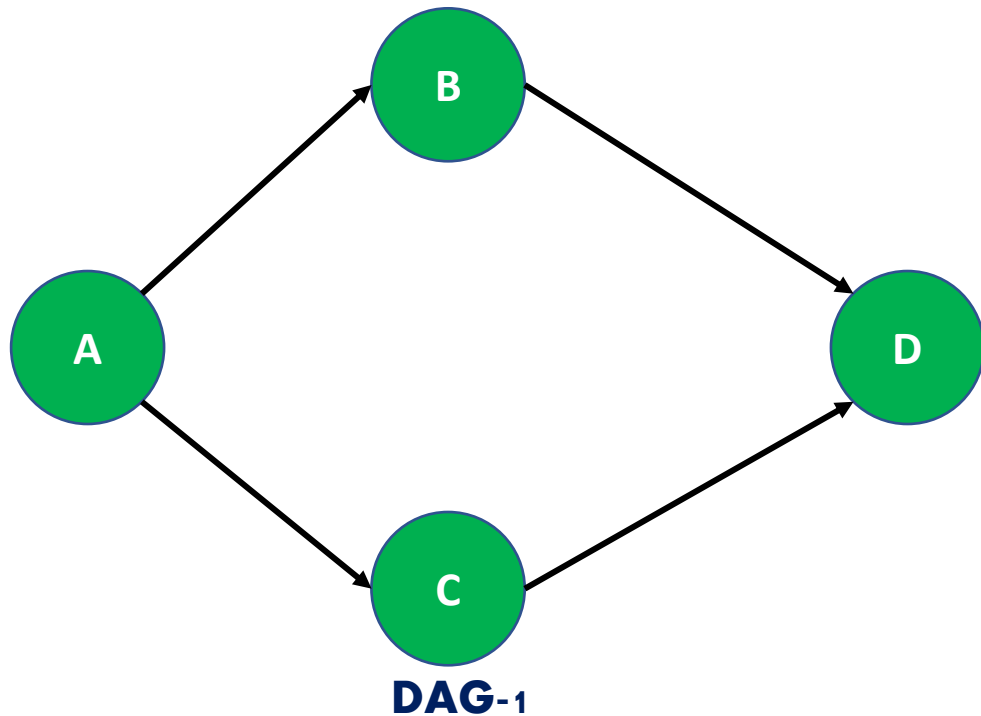
Dependent Event



A must occur before the occurrence of B

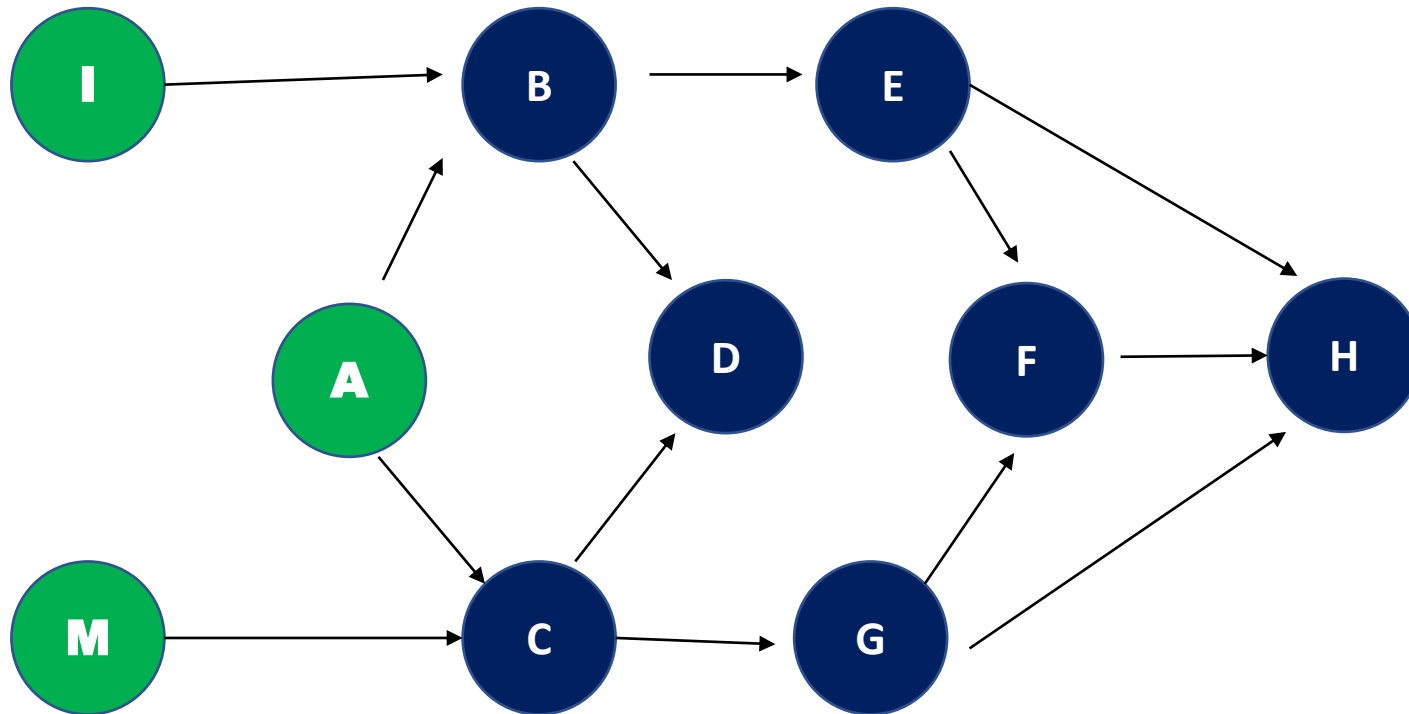
Directed Acyclic Graph(DAG)

A graph is a **DAG** if it is **Directed** and **Acyclic**.



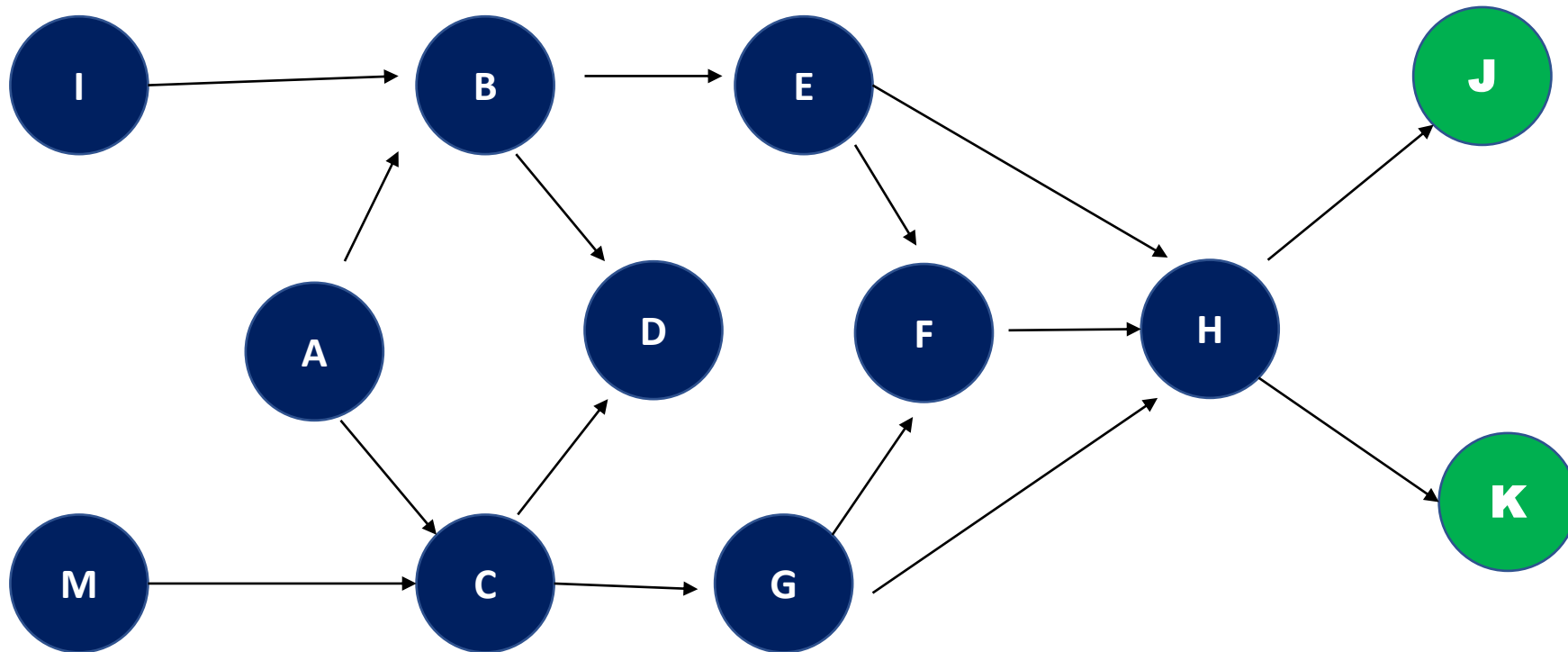
Directed Acyclic Graph(DAG)

Observation1: A DAG has at least one vertex whose indegree is 0



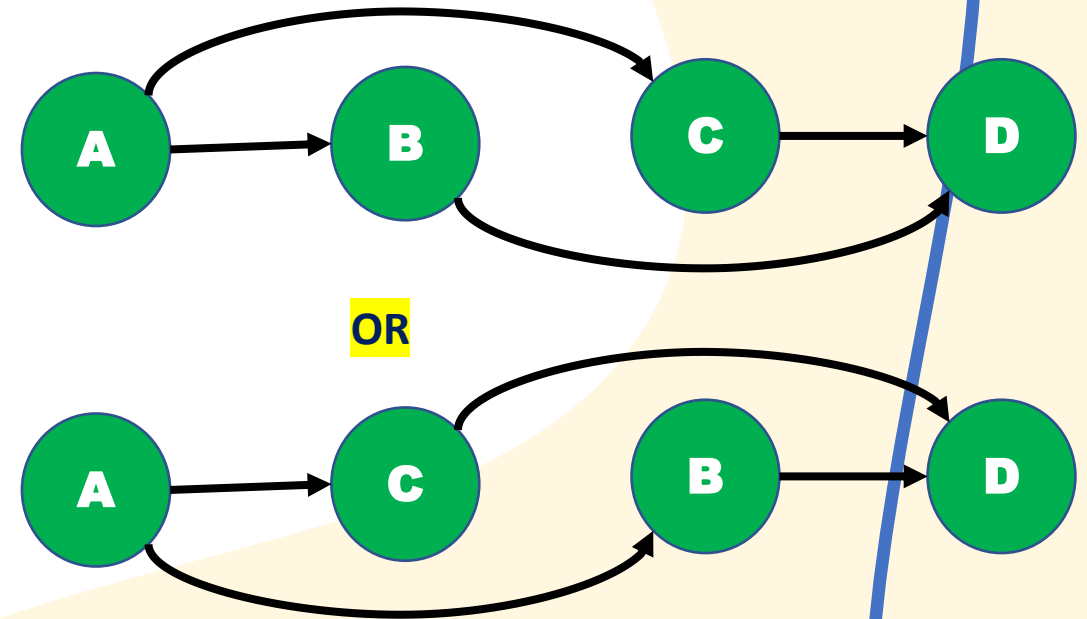
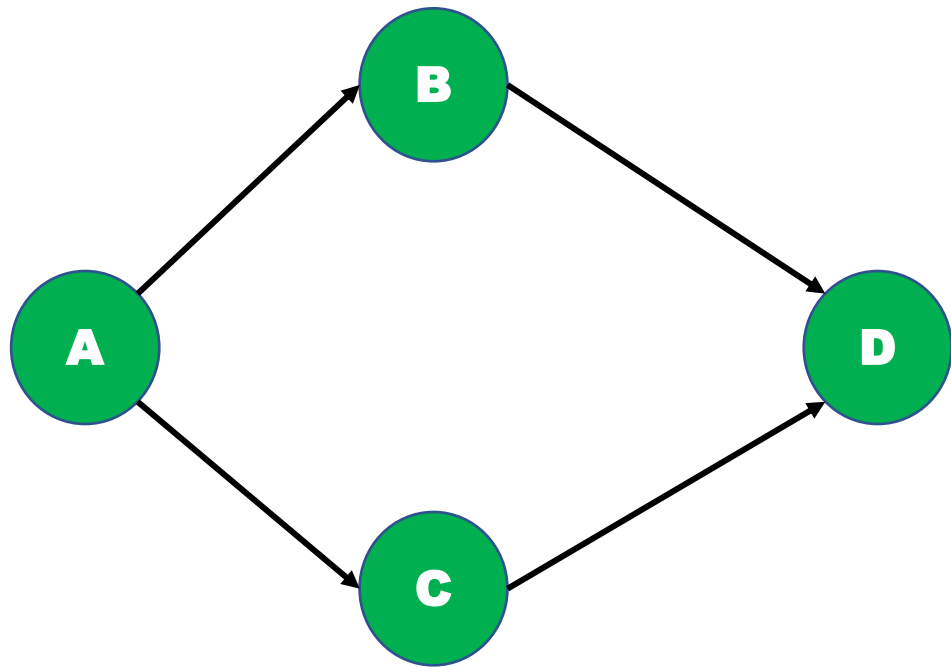
Directed Acyclic Graph(DAG)

Observation2: A DAG has at least one vertex whose outdegree is 0



Topological Sorting or Ordering

Arranging the events/activities in linear/serial order by preserving their dependencies



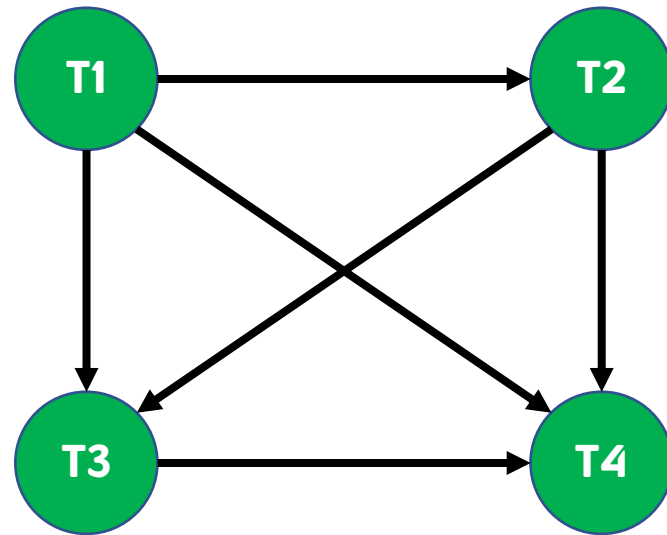
NOTE: Topological sorting is possible only for DAG

Topological Sorting or Ordering

Topological_Sorting(G)

1. Call DFS(G) to compute the **finishing time $f[v]$** for all vertices
2. Output vertices in decreasing order of their finishing time $f[v]$

Topological Sorting using DFS

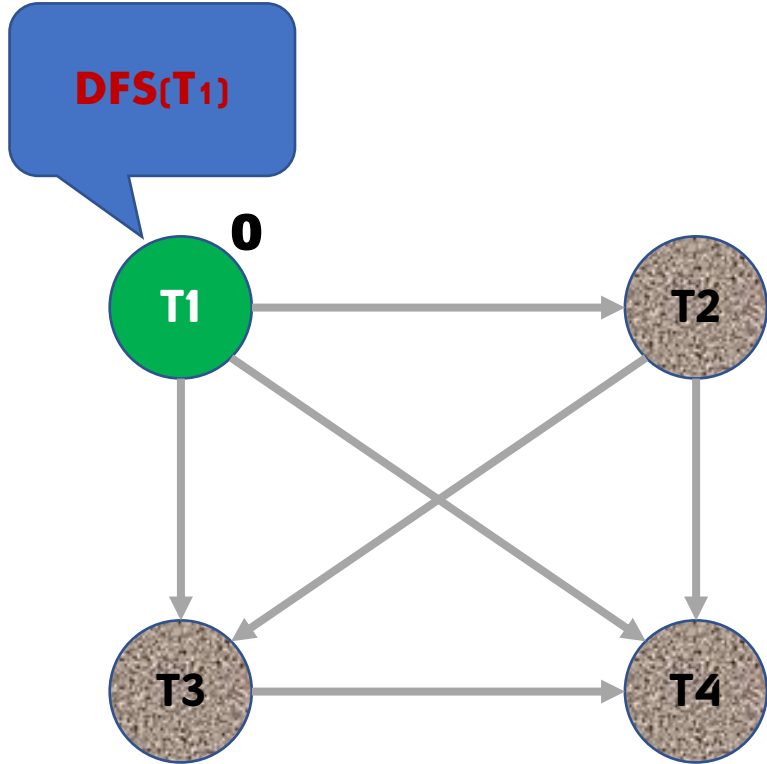


DAG

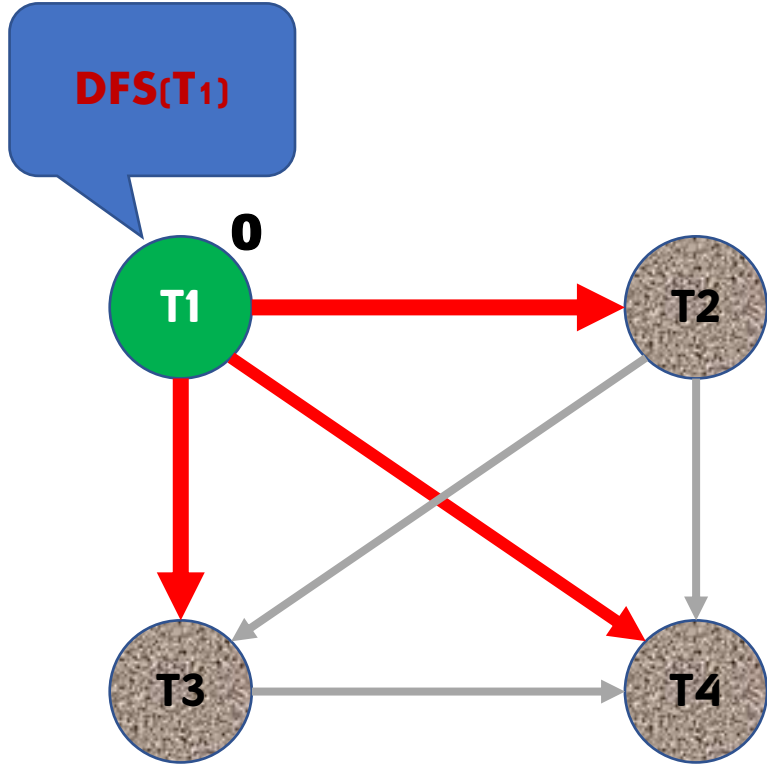
$d[u]$ = discovery time of vertex u (time when we explore u first time)

$f[u]$ = Finishing time of vertex u (time when we backtrack from u)

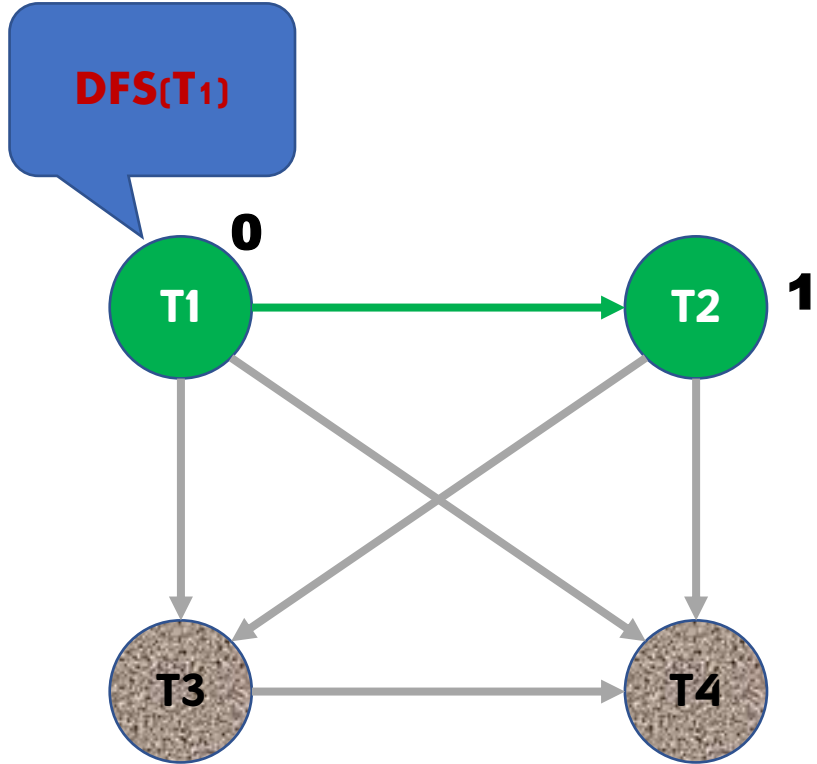
Topological Sorting using DFS



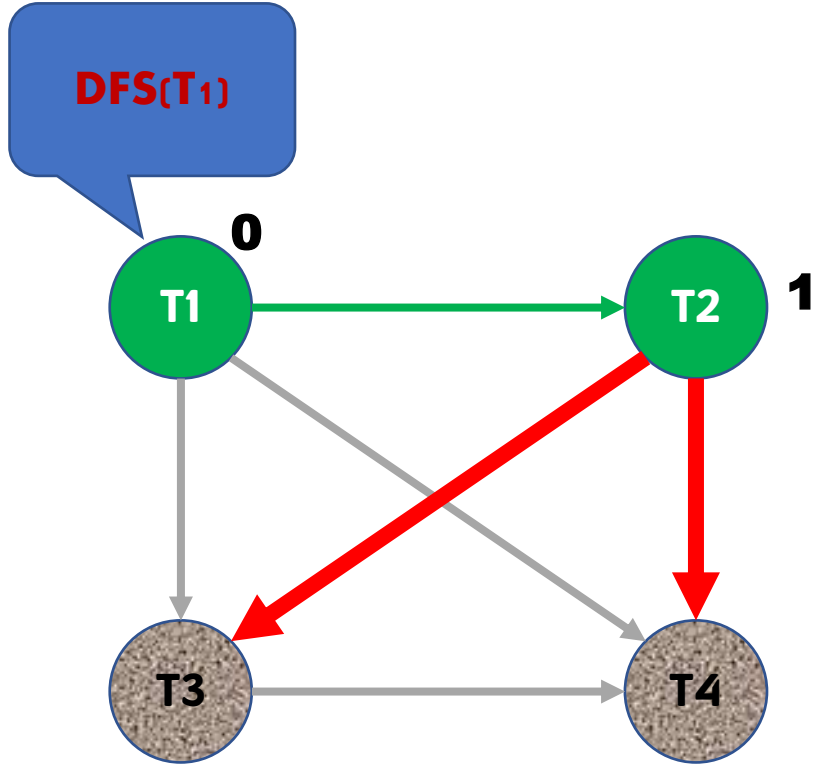
Topological Sorting using DFS



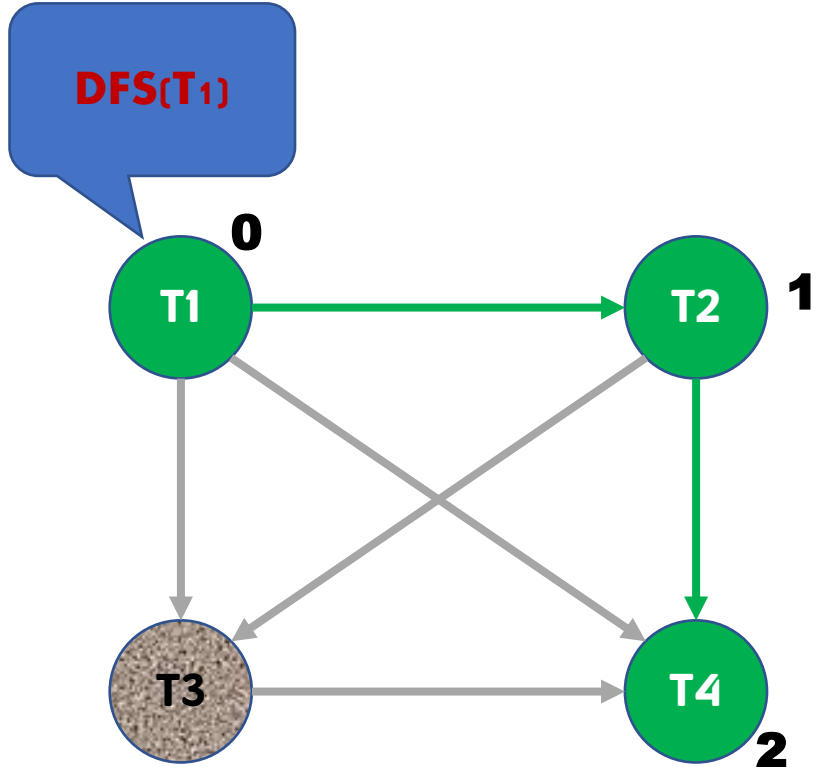
Topological Sorting using DFS



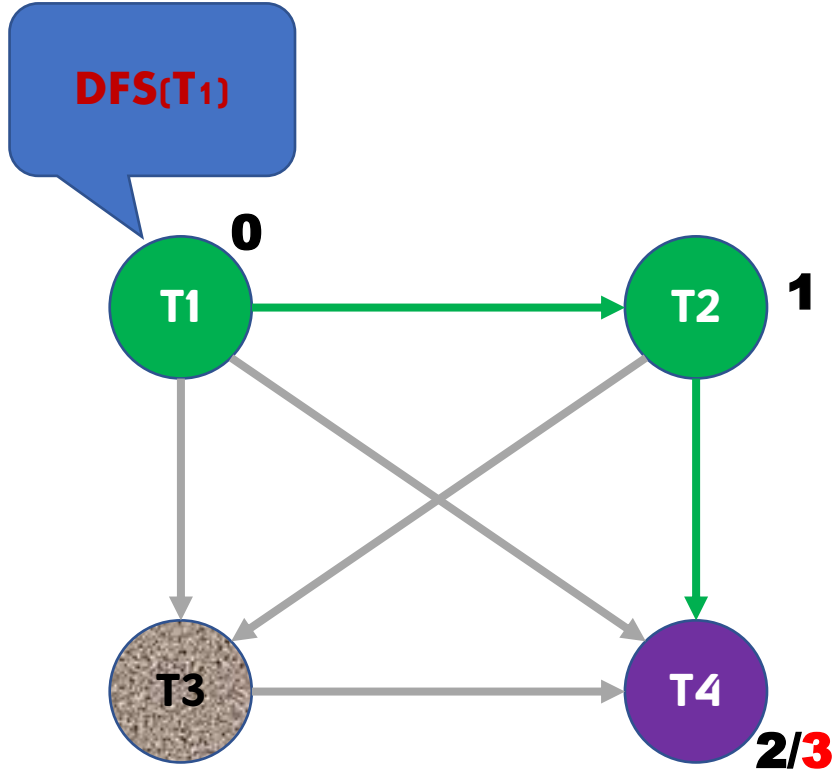
Topological Sorting using DFS



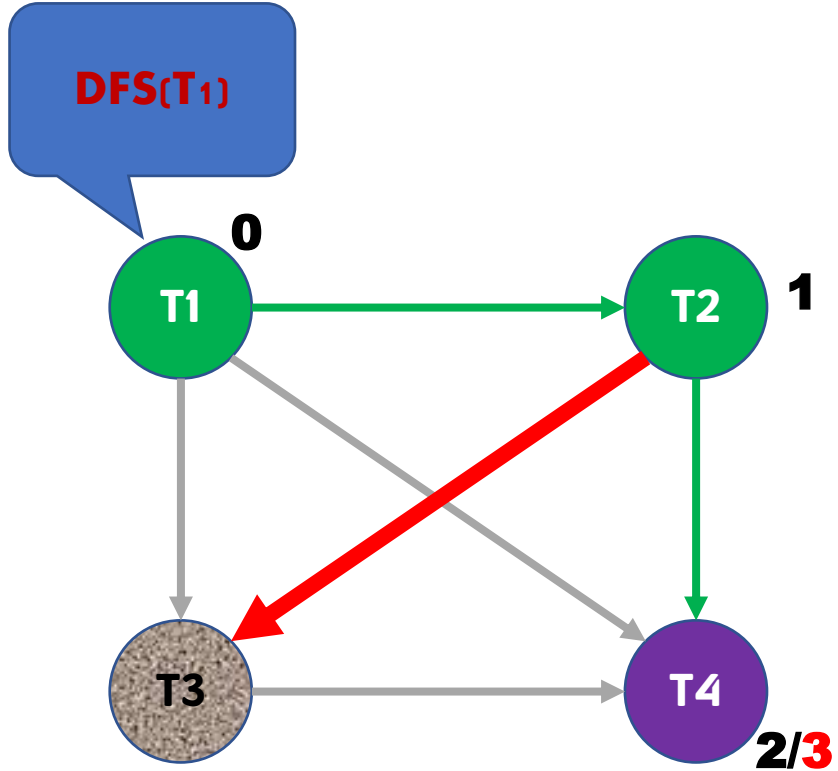
Topological Sorting using DFS



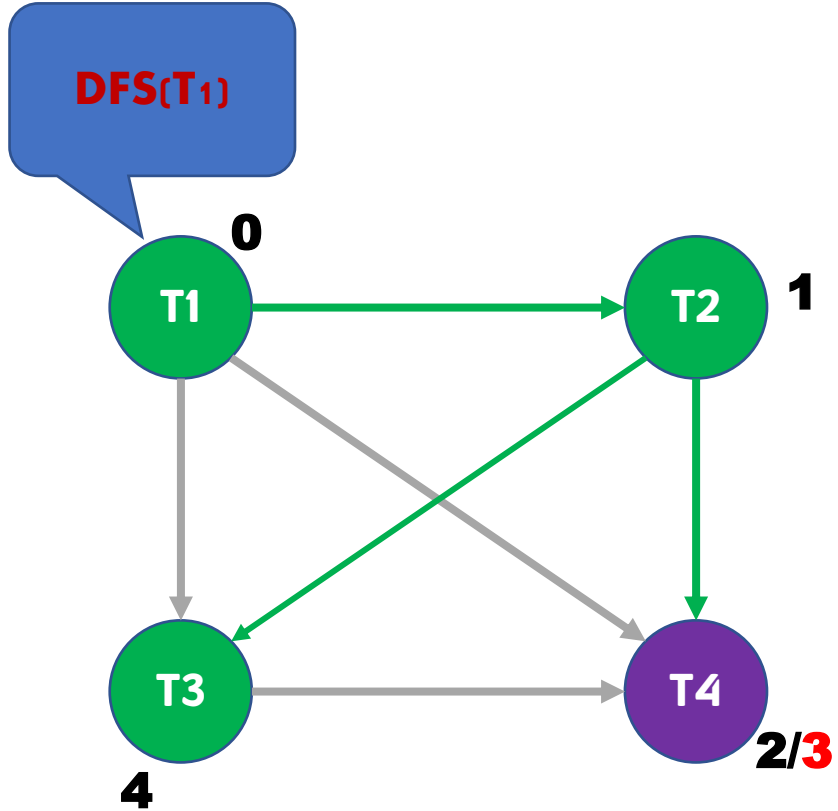
Topological Sorting using DFS



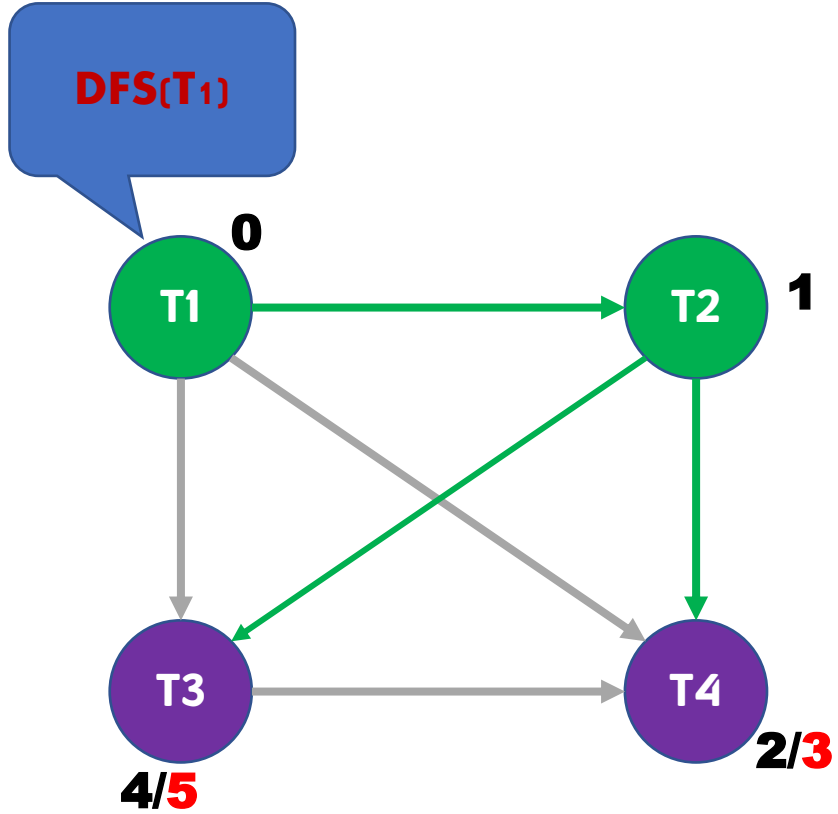
Topological Sorting using DFS



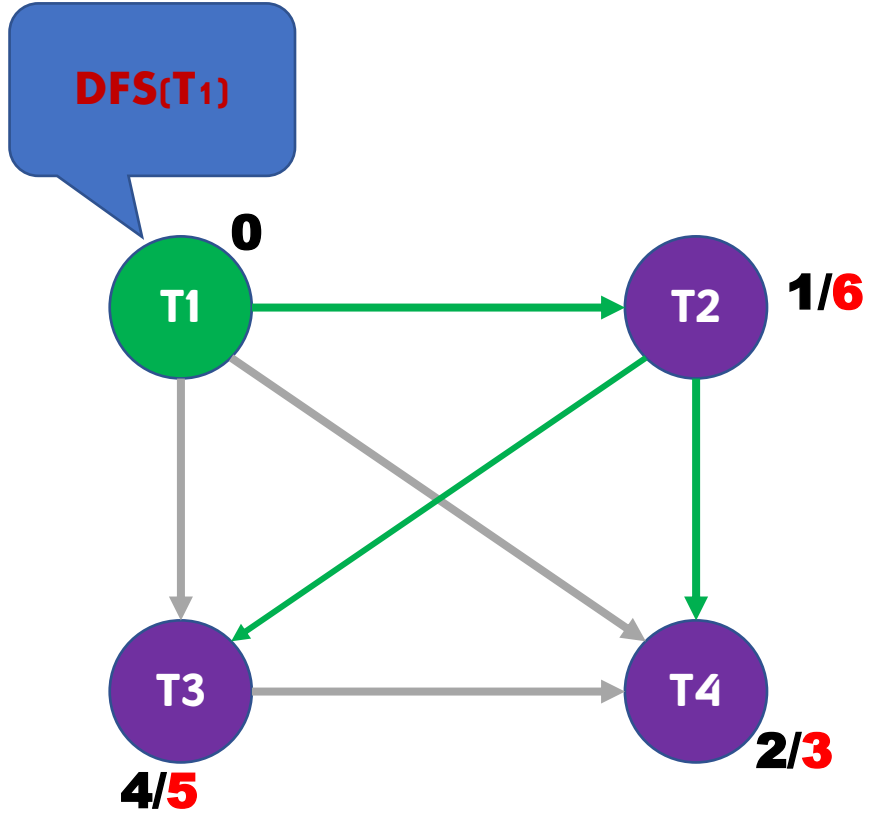
Topological Sorting using DFS



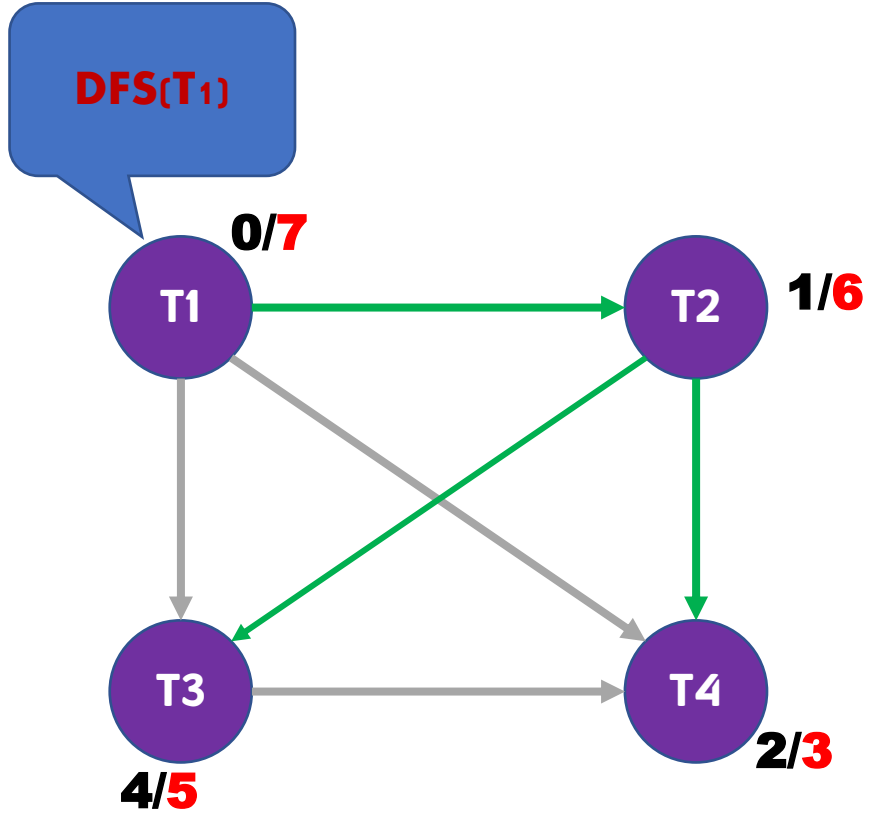
Topological Sorting using DFS



Topological Sorting using DFS



Topological Sorting using DFS



Topological Order is as follows



Topological Sorting using DFS

Cost Analysis

Topological(G)

1. Call $\text{DFS}(G)$ to compute the finishing time $f[v]$ for all vertices
2. Output vertices in decreasing order of their finishing time $f[v]$

Time **C**omplexity = $O(V+E)$

$O(V+E)$

$O(V)$

Topological Sorting using DFS

Cost Analysis

Topological(G)

1. Call DFS(G) to compute the finishing time $f[v]$ for all vertices
2. Output vertices in decreasing order of their finishing time $f[v]$

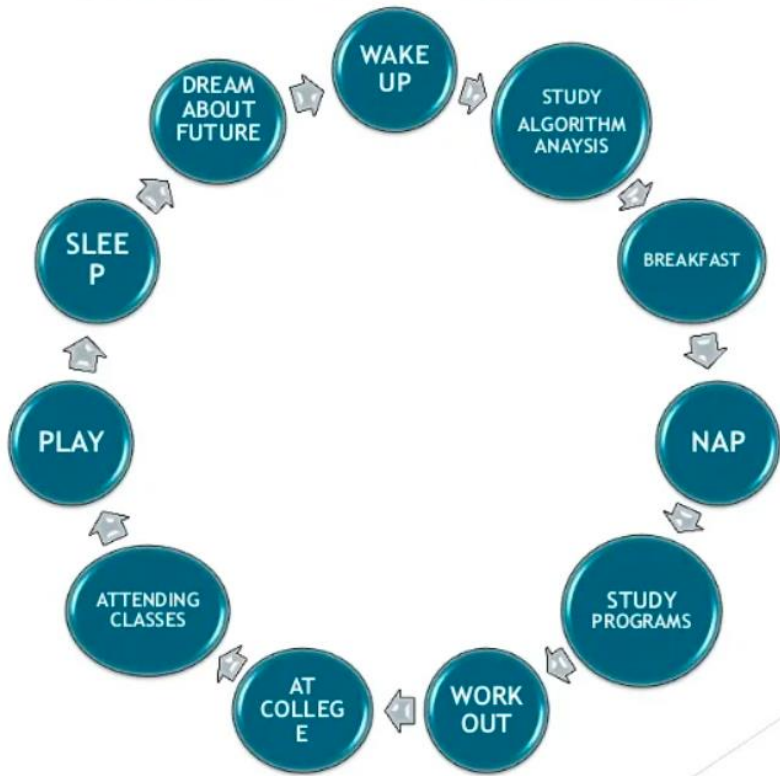
S_{pace} **C**omplexity = **O(V+E)**

Graphs

Topological Sort

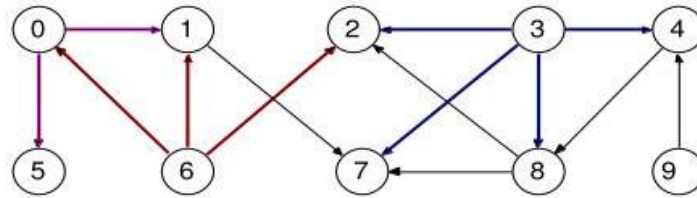
- **Directed Acyclic Graph (dag):** a directed graph which contains no directed cycles.
- **A topological order for a dag G:** a sequential listing of all the vertices of G such that if $(u,v) \in E(G)$ then u precedes v in the listing.
- **Topological Sort:** an algorithm that takes as input a dag G and produces a topological order of the vertices of G
- Example Applications: ·
 - Prerequisites dag for courses at a University
 - Glossary of technical terms: $(t_1,t_2) \in E(G)$ iff t_1 is used in the definition of t_2 .

Graphs

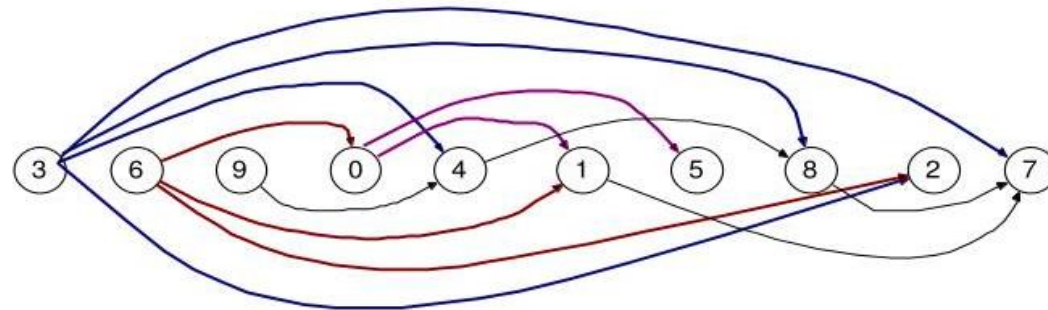
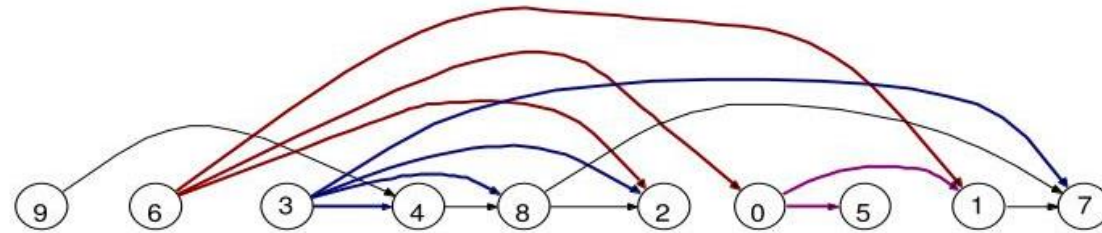


Graphs

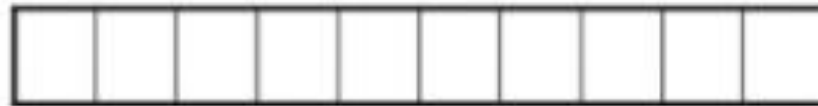
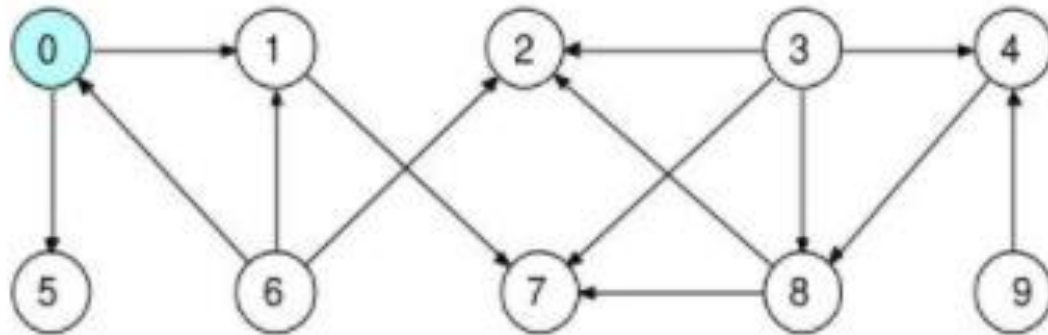
In general, topological order of a dag is not unique.



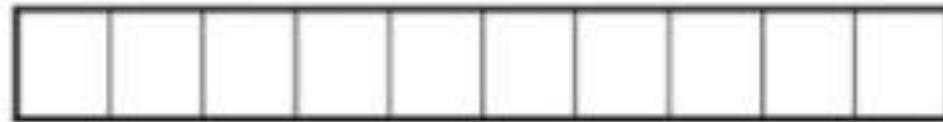
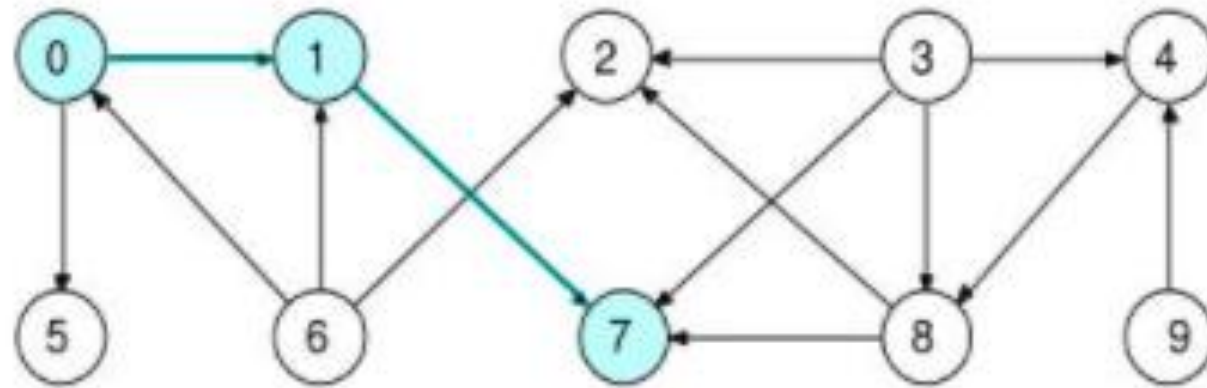
Directed Acyclic Graph G



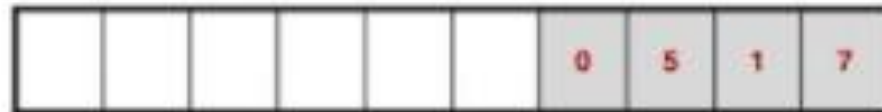
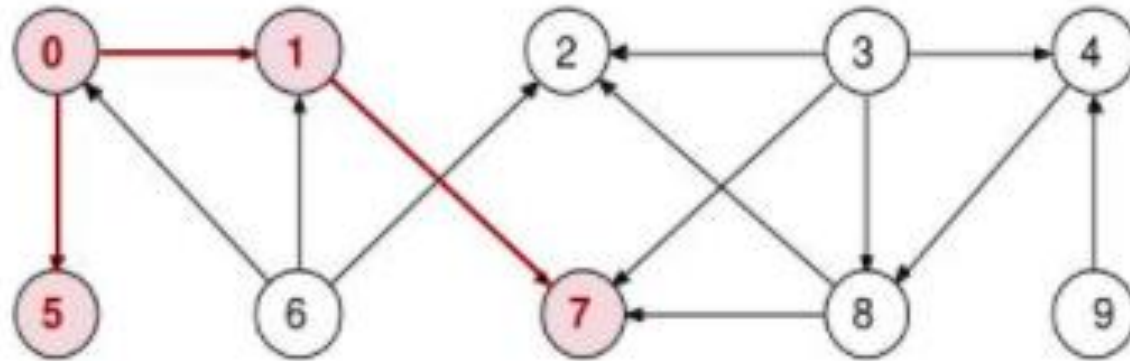
Graphs



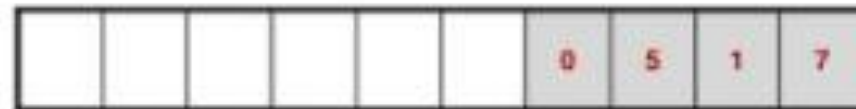
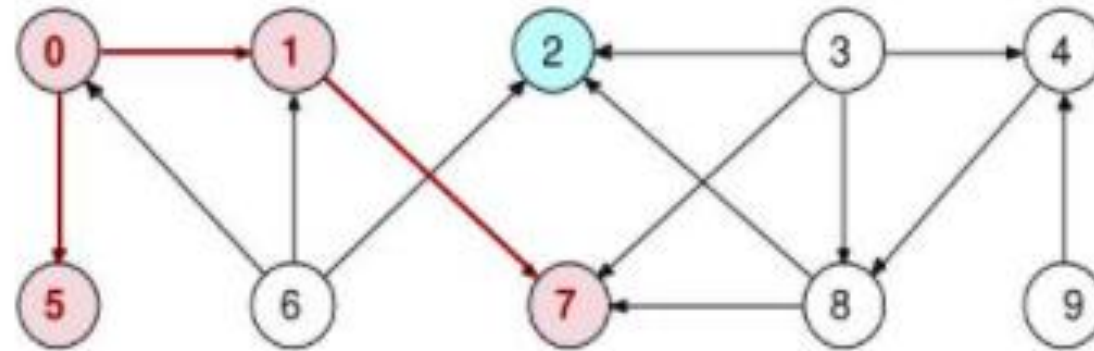
Graphs



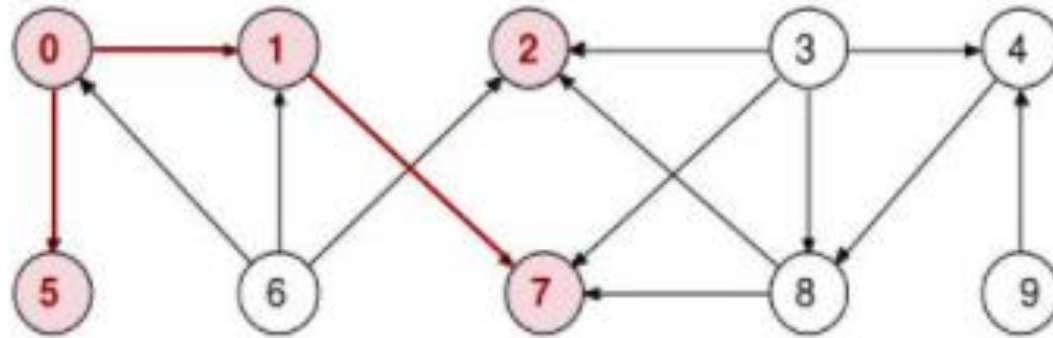
Graphs



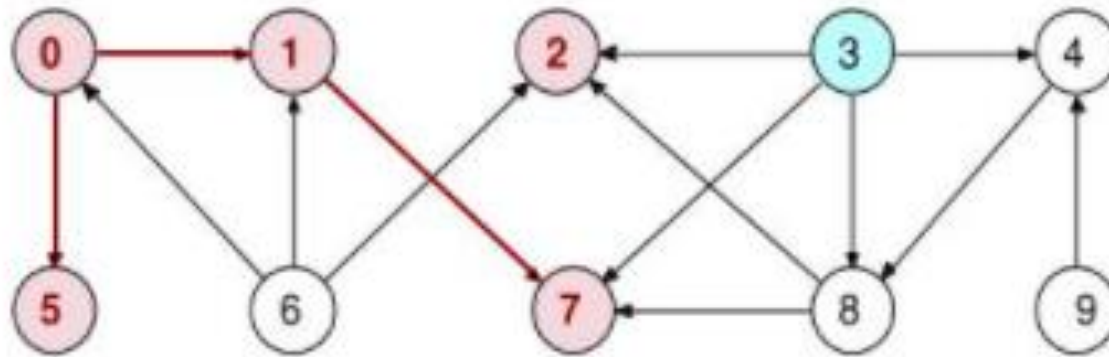
Graphs



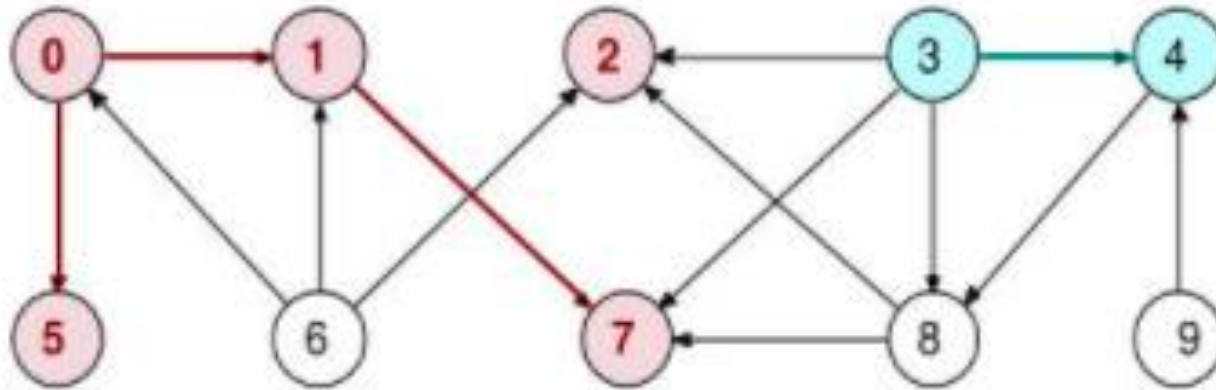
Graphs



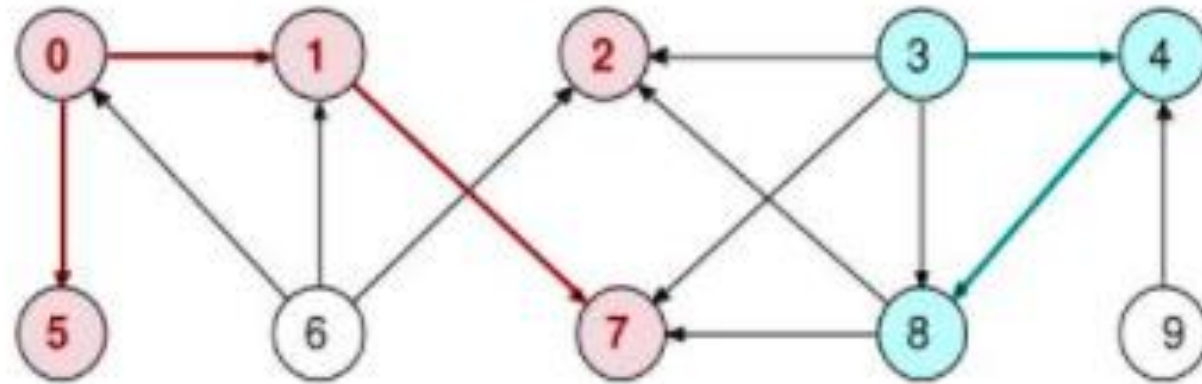
Graphs



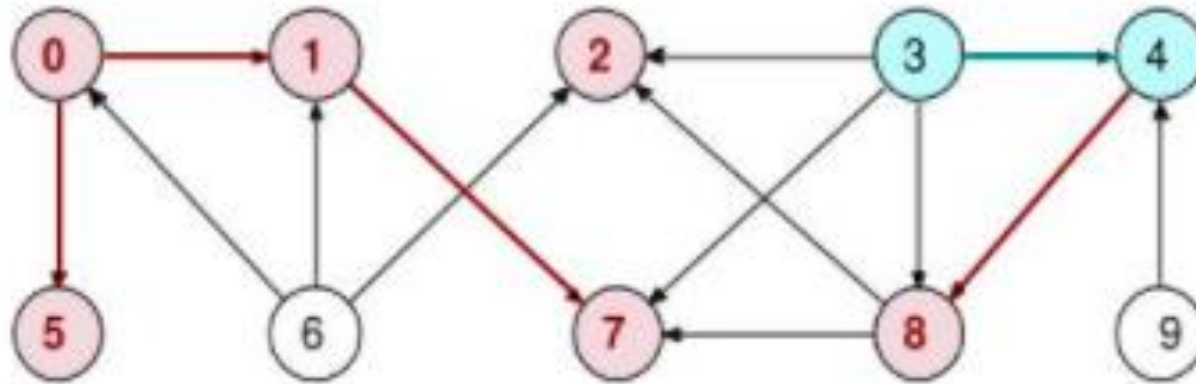
Graphs



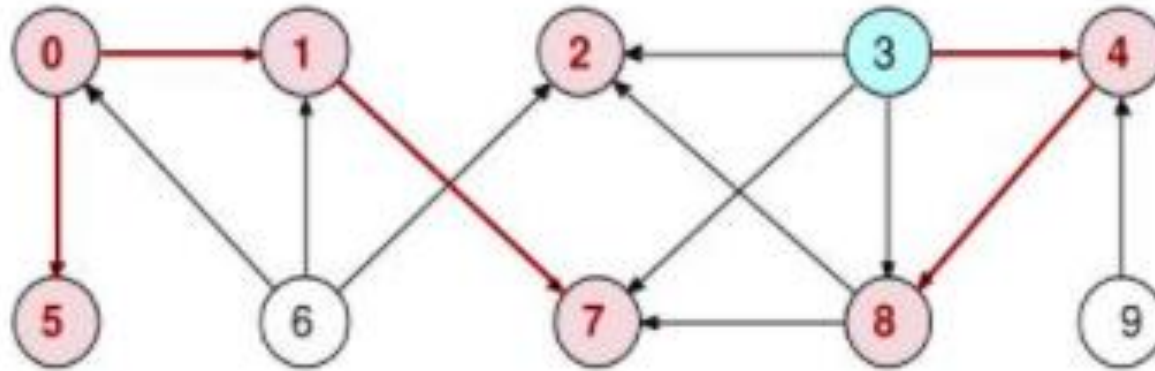
Graphs



Graphs

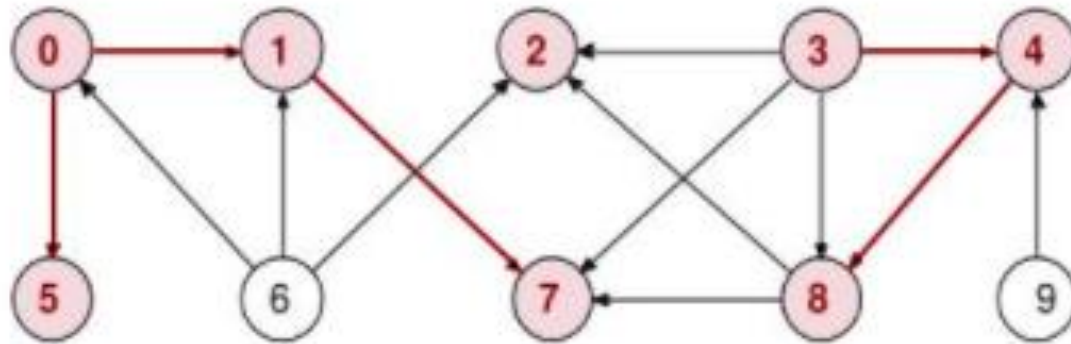


Graphs

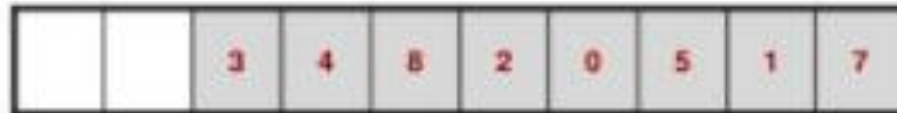
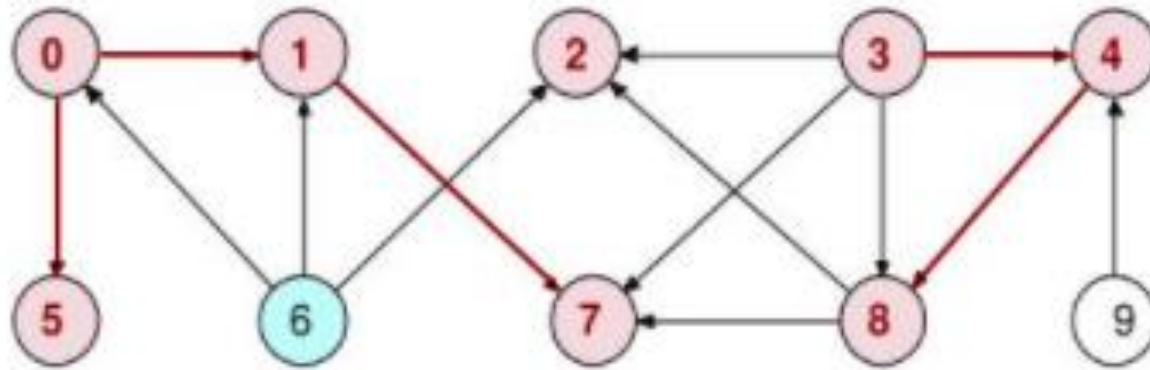


			4	8	2	0	5	1	7
--	--	--	---	---	---	---	---	---	---

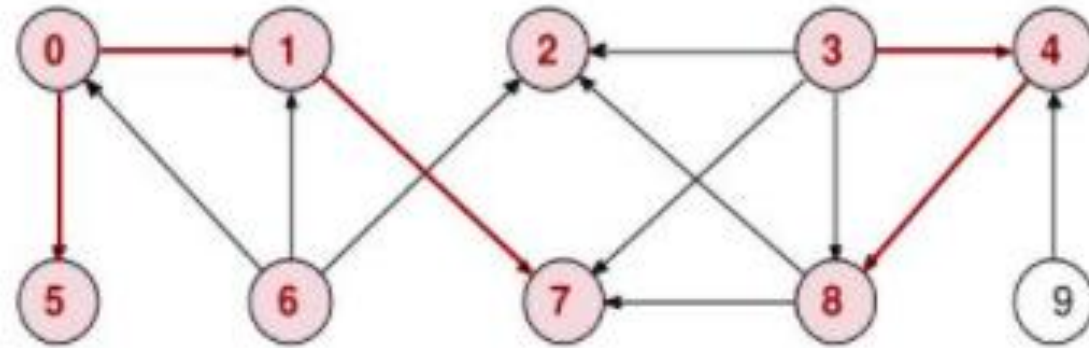
Graphs



Graphs

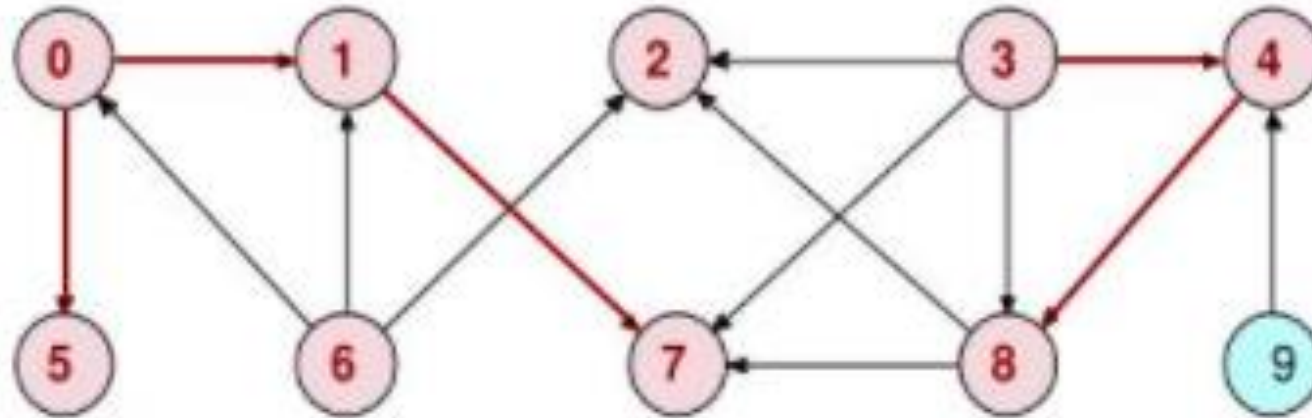


Graphs



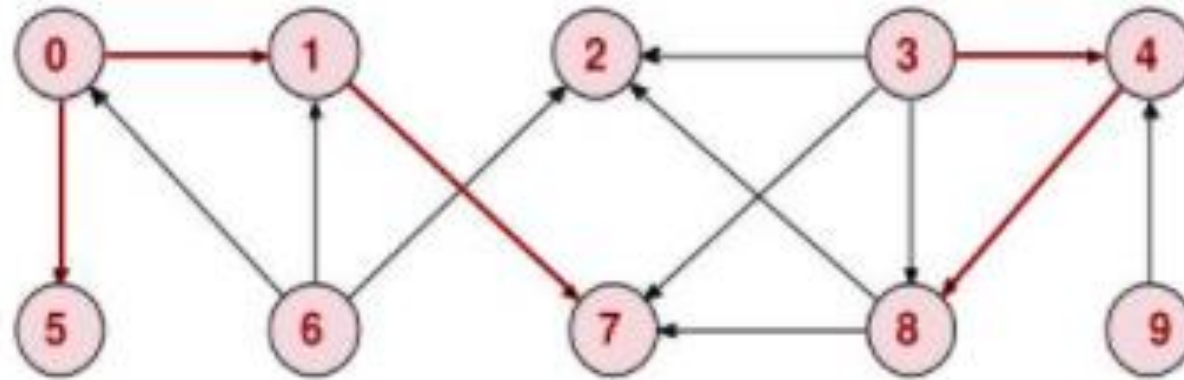
	6	3	4	8	2	0	5	1	7
--	---	---	---	---	---	---	---	---	---

Graphs



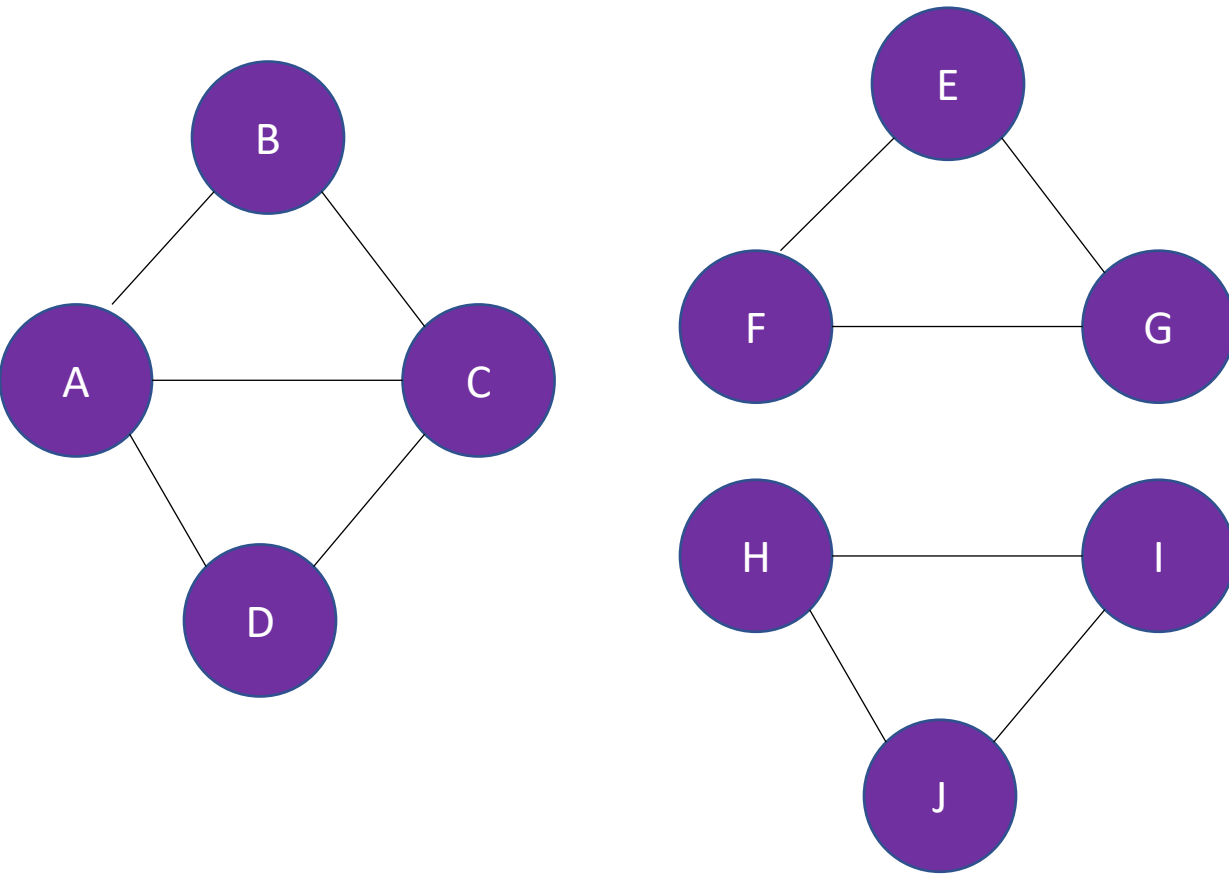
	6	3	4	8	2	0	5	1	7
--	---	---	---	---	---	---	---	---	---

Graphs



9	6	3	4	8	2	0	5	1	7
---	---	---	---	---	---	---	---	---	---

Connected Components using DFS



**No of Connected
Components = 3**

Connected Components using DFS

Algorithm 1: Finding Connected Components using DFS

Data: Given an undirected graph $G(V, E)$

Result: Number of Connected Components

Component_Count = 0;

for *each vertex* $k \in V$ **do**

 | *Visited*[k] = *False*;

end

for *each vertex* $k \in V$ **do**

 | **if** *Visited*[k] == *False* **then**

 | *DFS*(V, k);

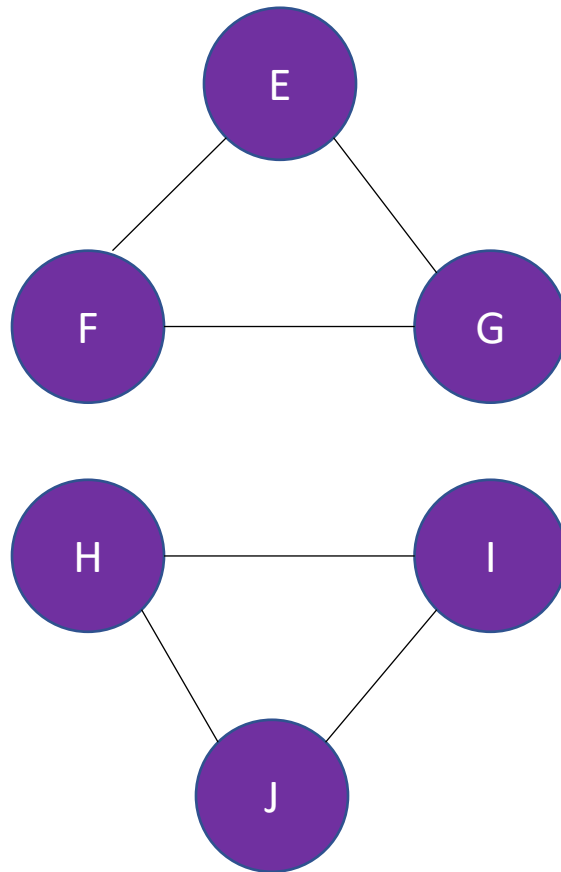
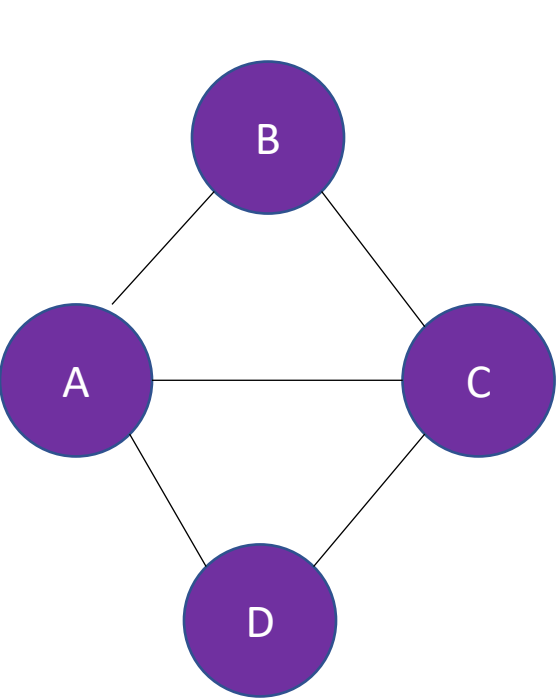
 | *Component_Count* = *Component_Count* + 1;

 | **end**

end

Print Component_Count;

Connected Components using DFS

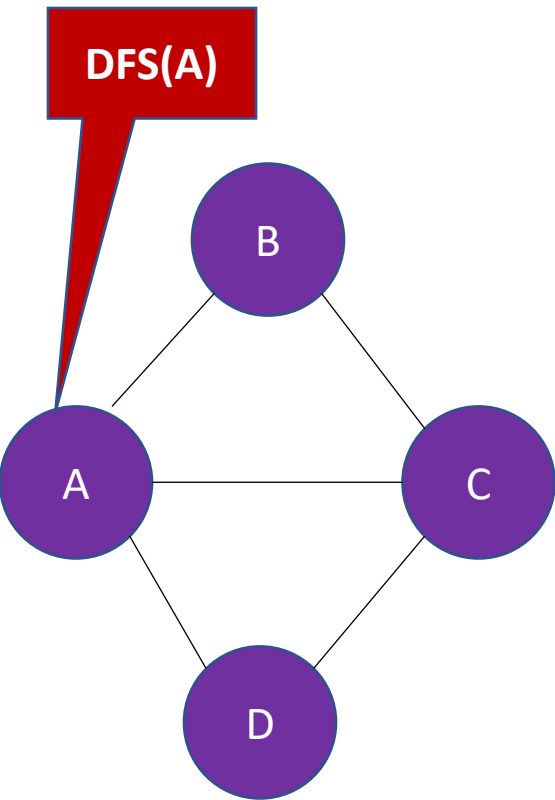


NCC=0

Visited	Vertex
0	A
0	B
0	C
0	D
0	E
0	F
0	G
0	H
0	I
0	J

DFS(A)

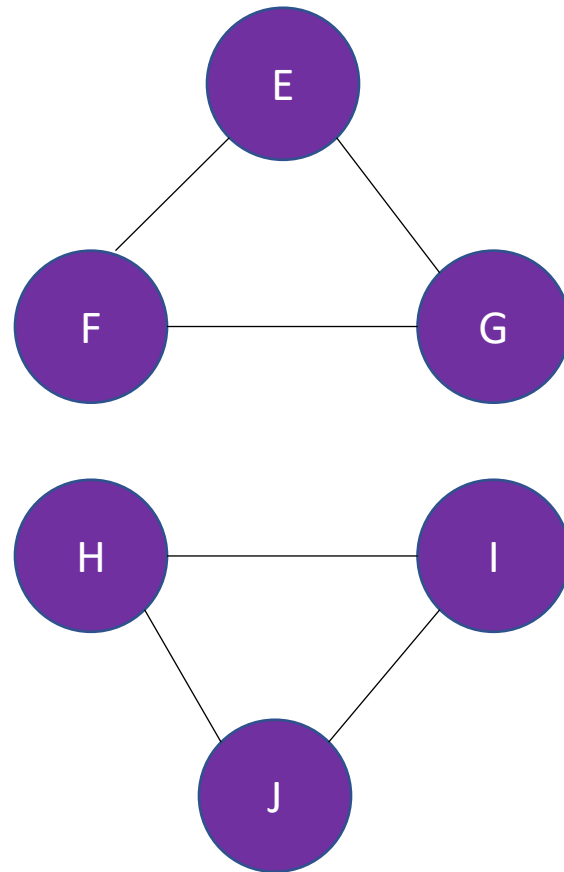
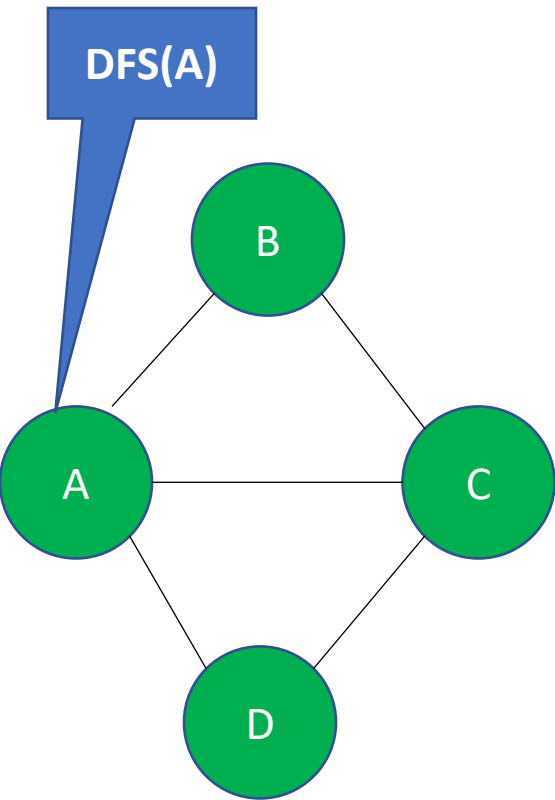
Connected Components using DFS



NCC=0

Visited	Vertex
0	A
0	B
0	C
0	D
0	E
0	F
0	G
0	H
0	I
0	J

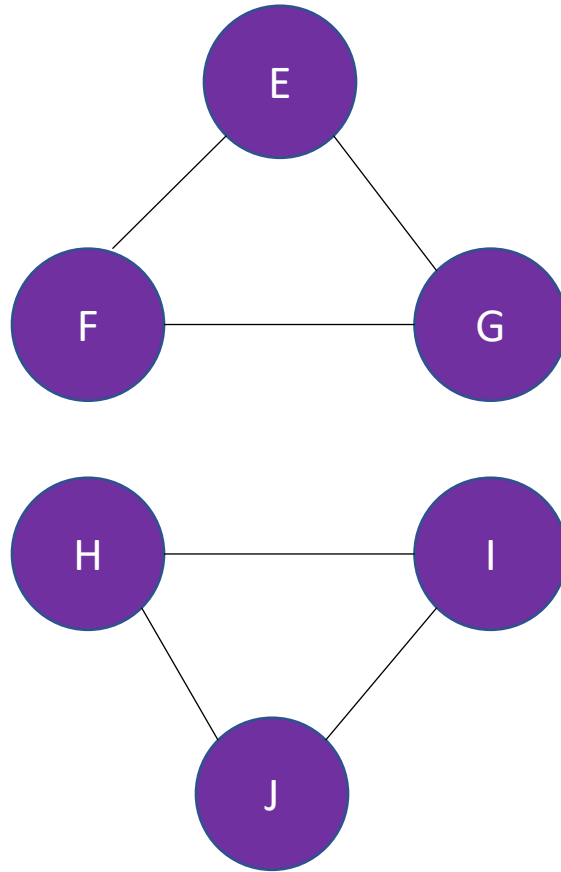
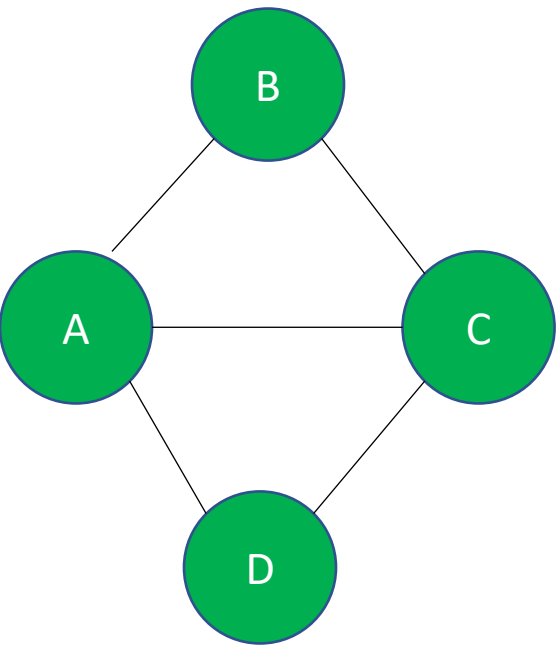
Connected Components using DFS



NCC=1

Visited	Vertex
1	A
1	B
1	C
1	D
0	E
0	F
0	G
0	H
0	I
0	J

Connected Components using DFS

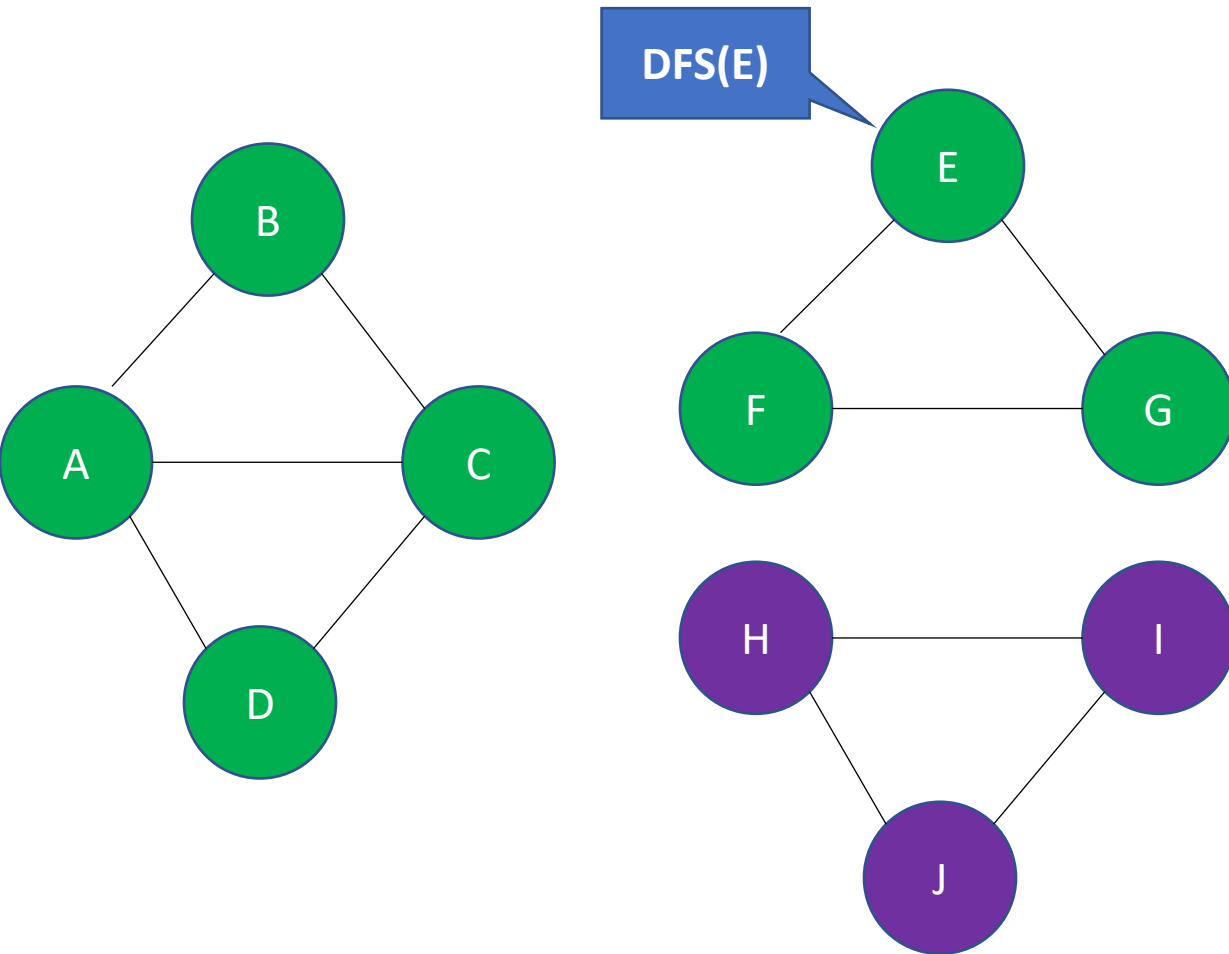


NCC=1

Visited	Vertex
1	A
1	B
1	C
1	D
0	E
0	F
0	G
0	H
0	I
0	J

DFS(E)

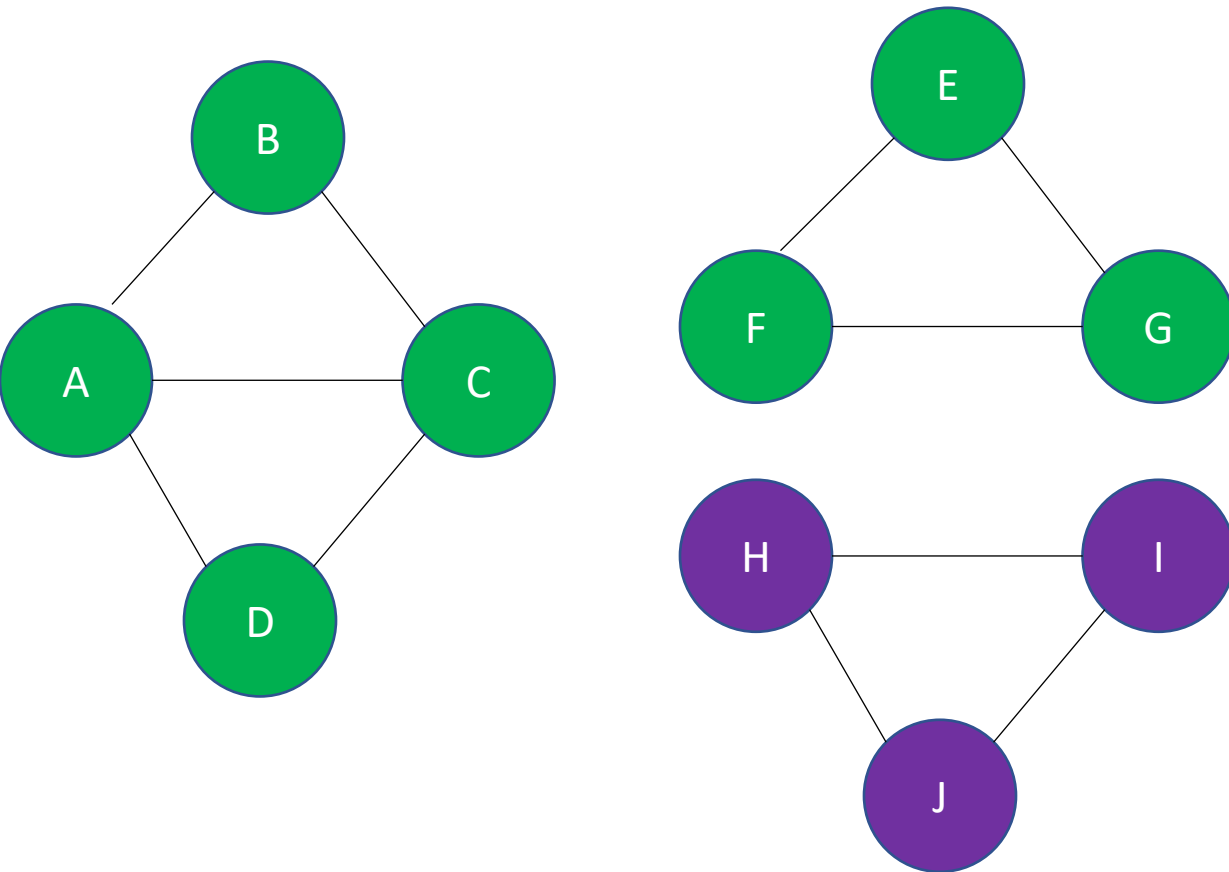
Connected Components using DFS



NCC=1

Visited	Vertex
1	A
1	B
1	C
1	D
1	E
1	F
1	G
0	H
0	I
0	J

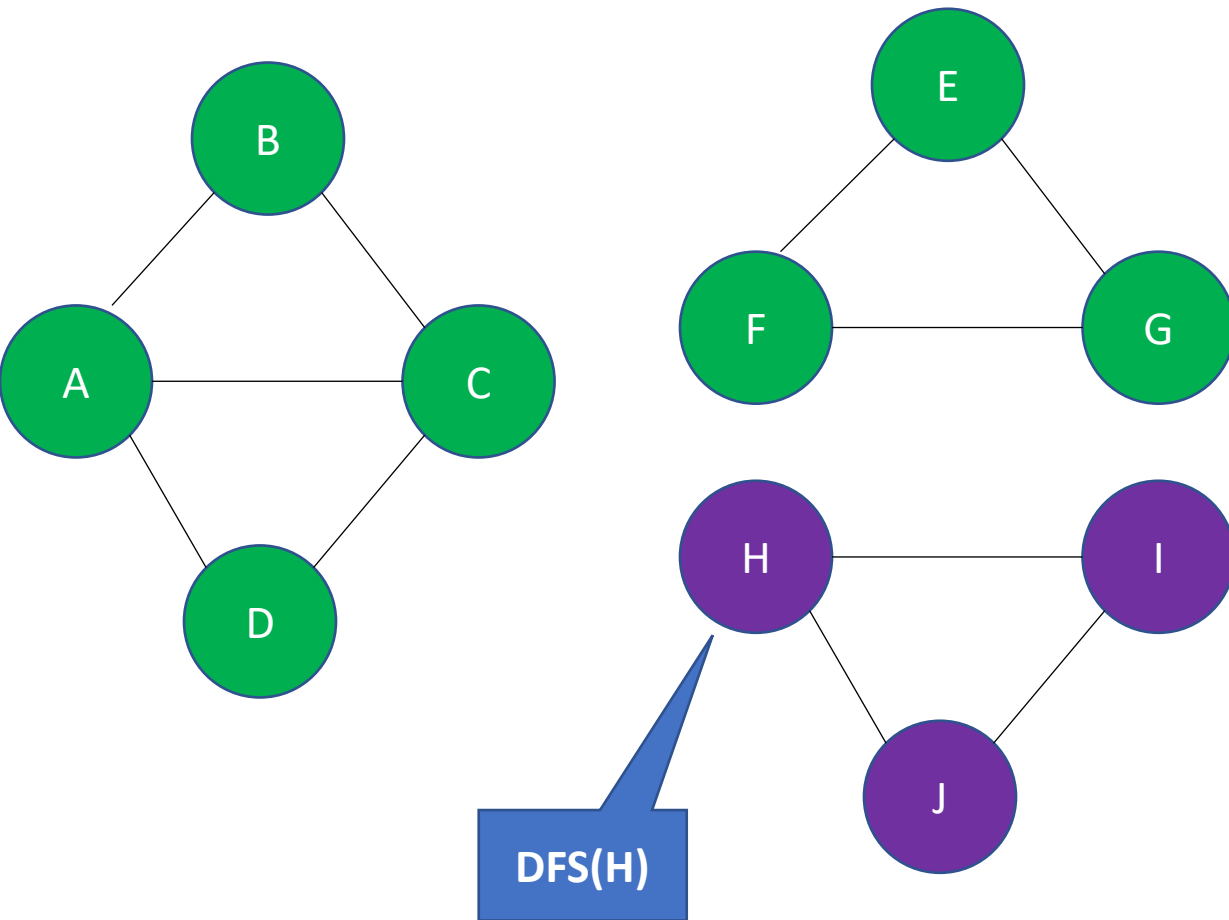
Connected Components using DFS



Visited	Vertex
1	A
1	B
1	C
1	D
1	E
1	F
1	G
0	H
0	I
0	J

DFS(H)

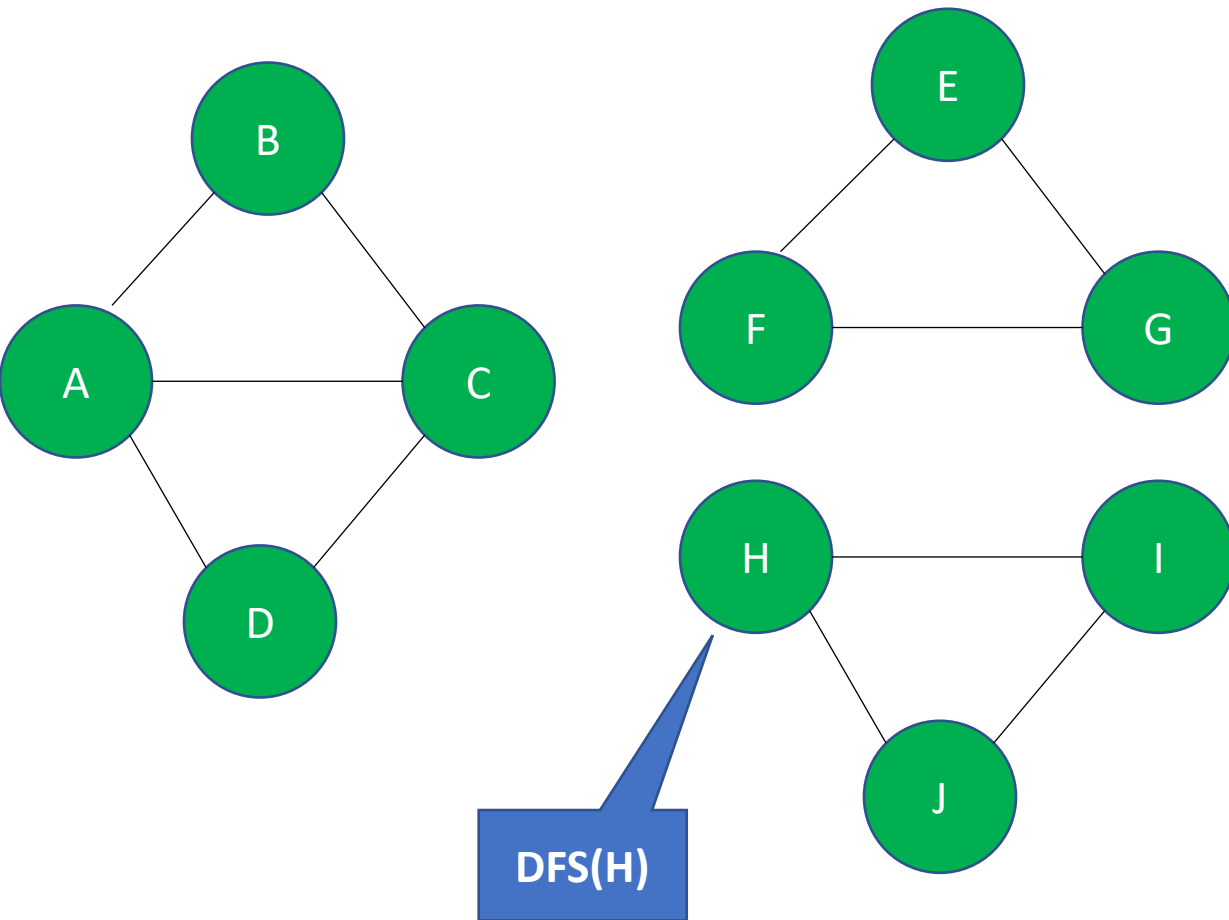
Connected Components using DFS



NCC=3

Visited	Vertex
1	A
1	B
1	C
1	D
1	E
1	F
1	G
0	H
0	I
0	J

Connected Components using DFS



NCC=3

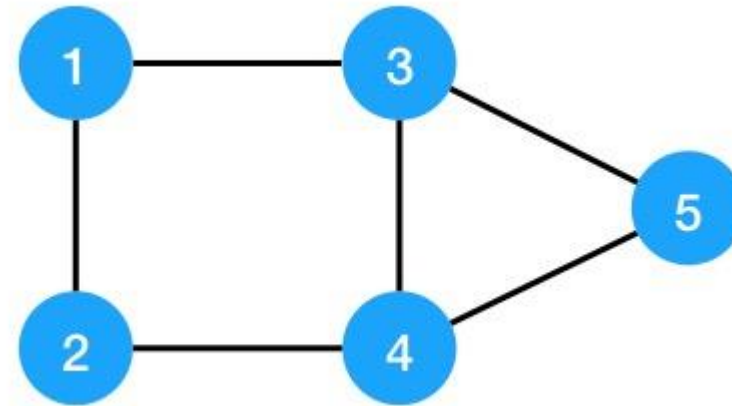
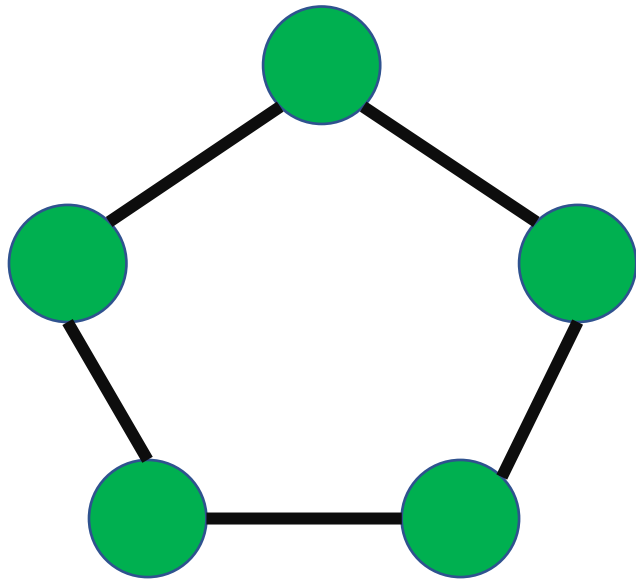
Visited	Vertex
1	A
1	B
1	C
1	D
1	E
1	F
1	G
1	H
1	I
1	J

Connected Components using DFS

Time Complexity = $O(V + E)$ = $O(E)$

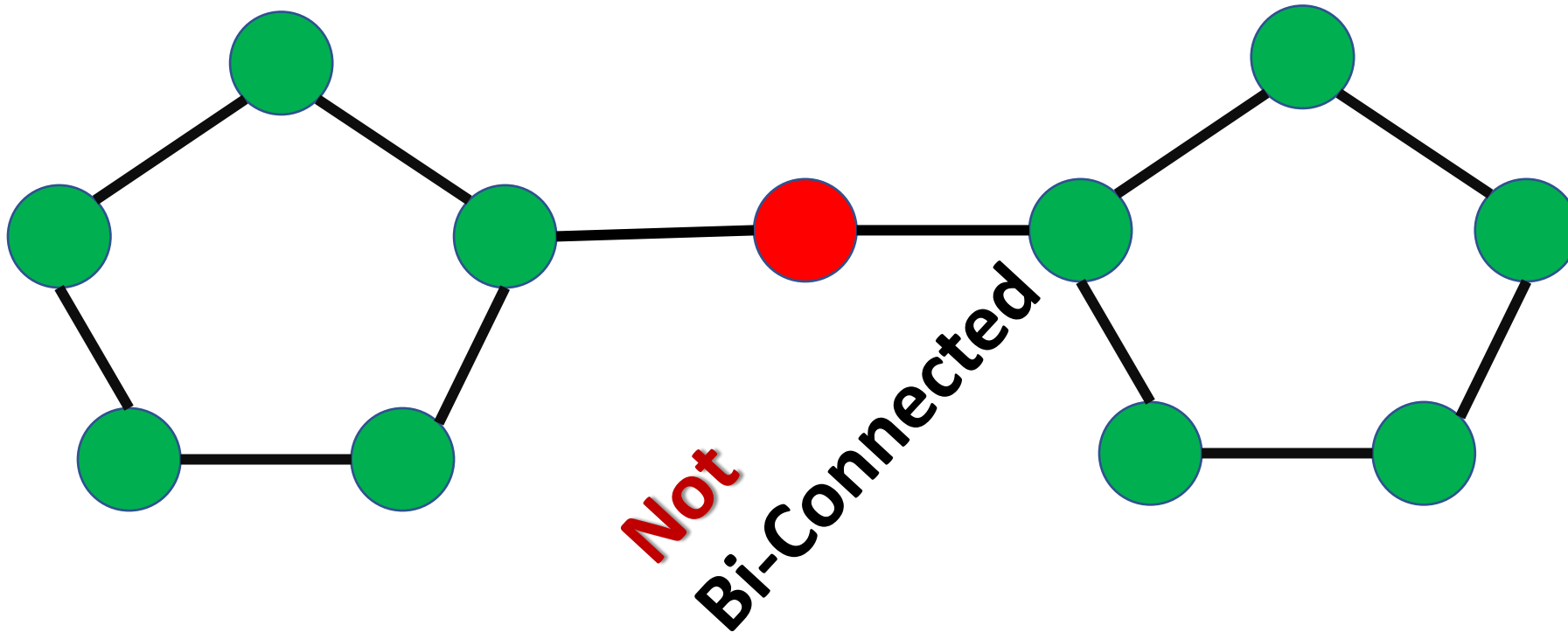
Bi-Connected Graph

Def: A graph G is bi-connected if after removal of any vertex it remains connected



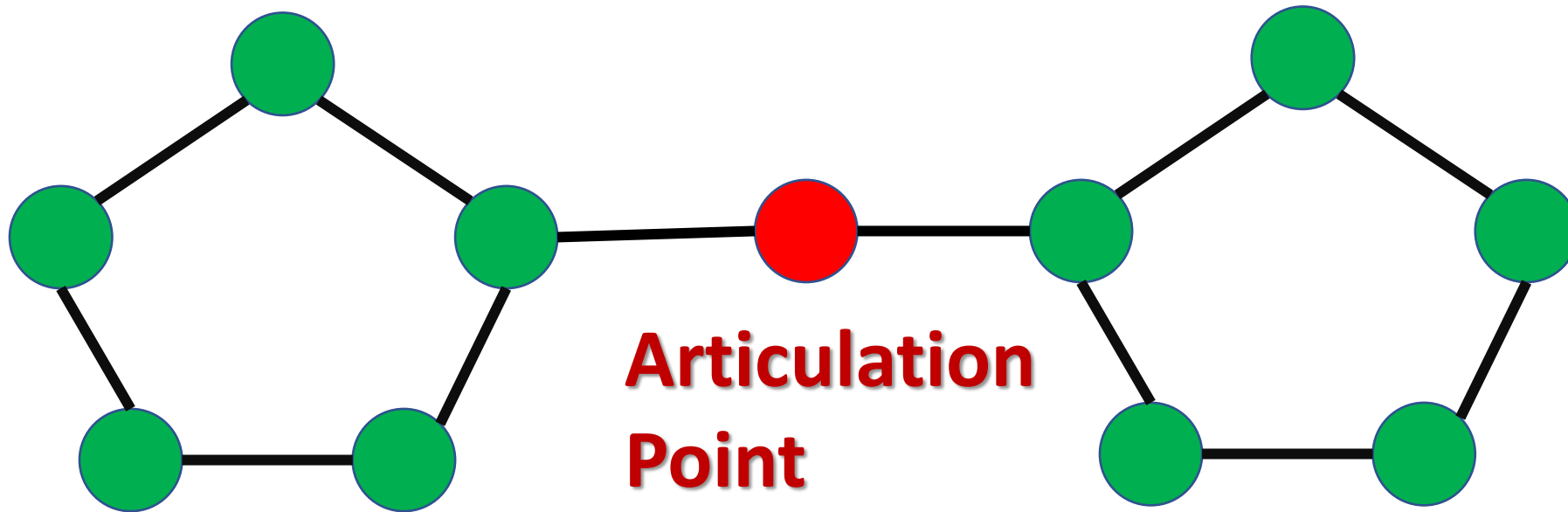
Bi-Connected Graph

Def: A graph G is bi-connected if after removal of any vertex it remains connected



Articulation Point or Cut Vertex

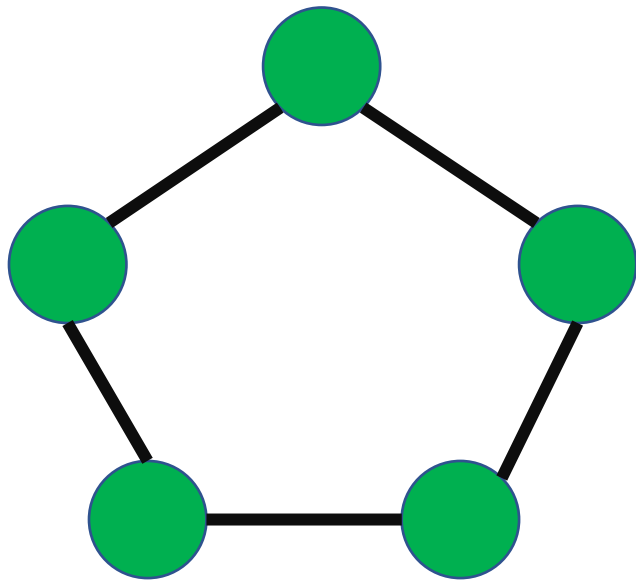
Def: A vertex in graph G whose removal disconnects the graph is known as an **articulation point** or cut vertex in G



Bi-Connected Graph

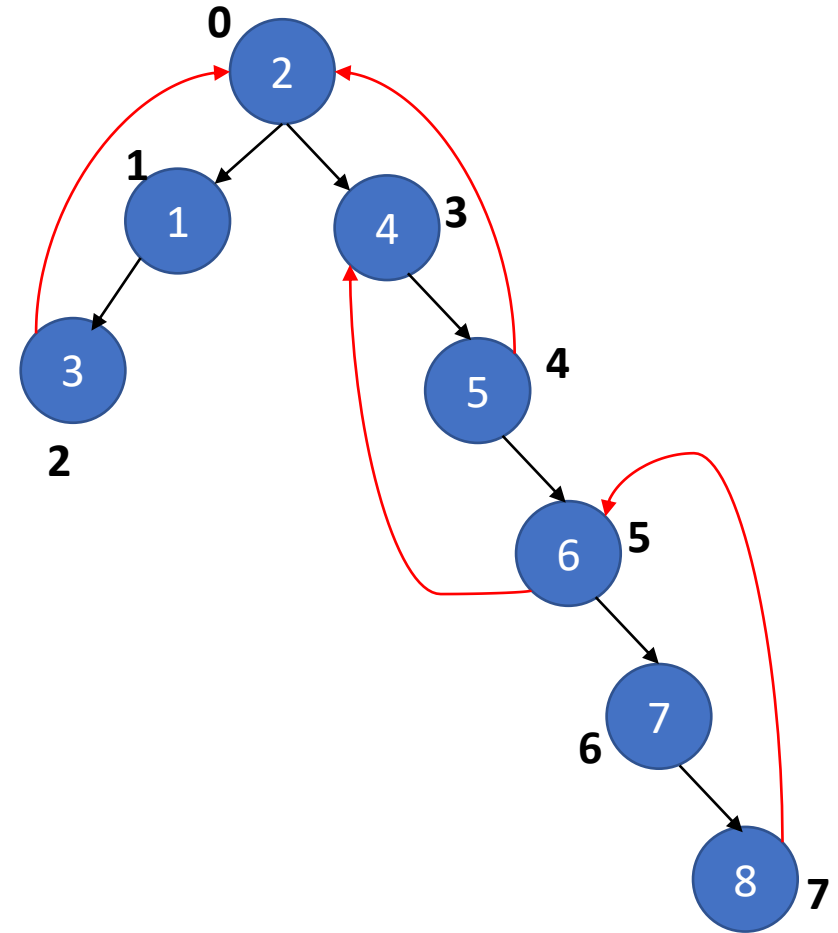
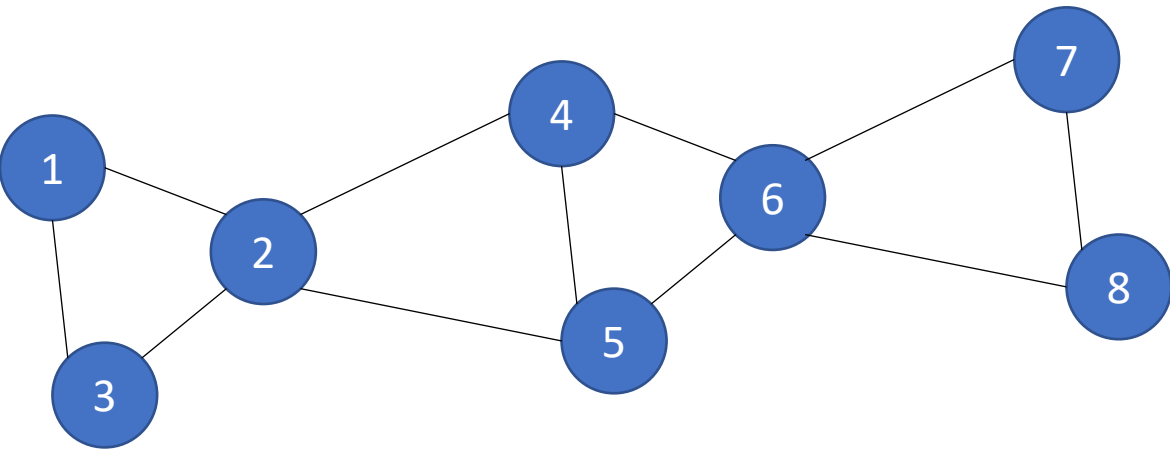
Observation

Graph G is Bi-Connected iff there is NO articulation point in a graph



← **No Articulation Point**

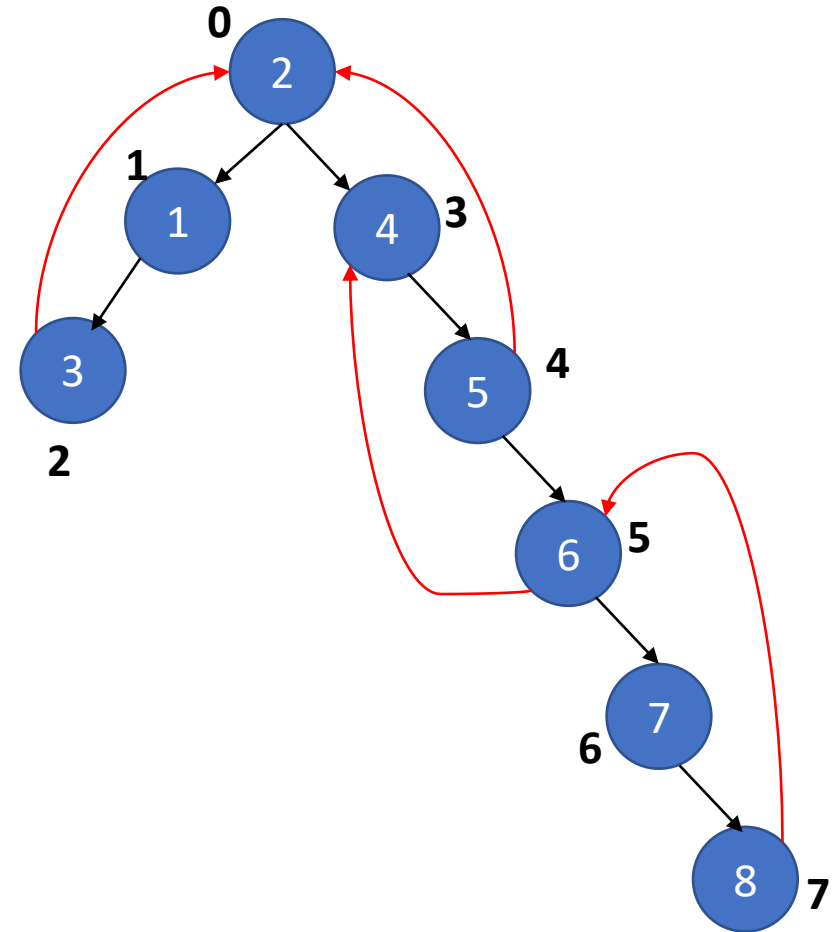
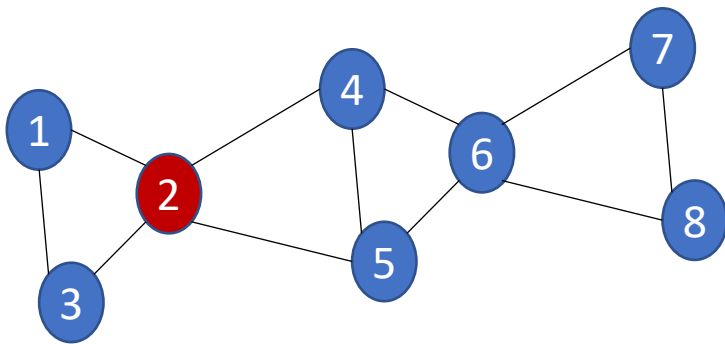
Bi-Connected Graph



Bi-Connected Graph

Observation-1

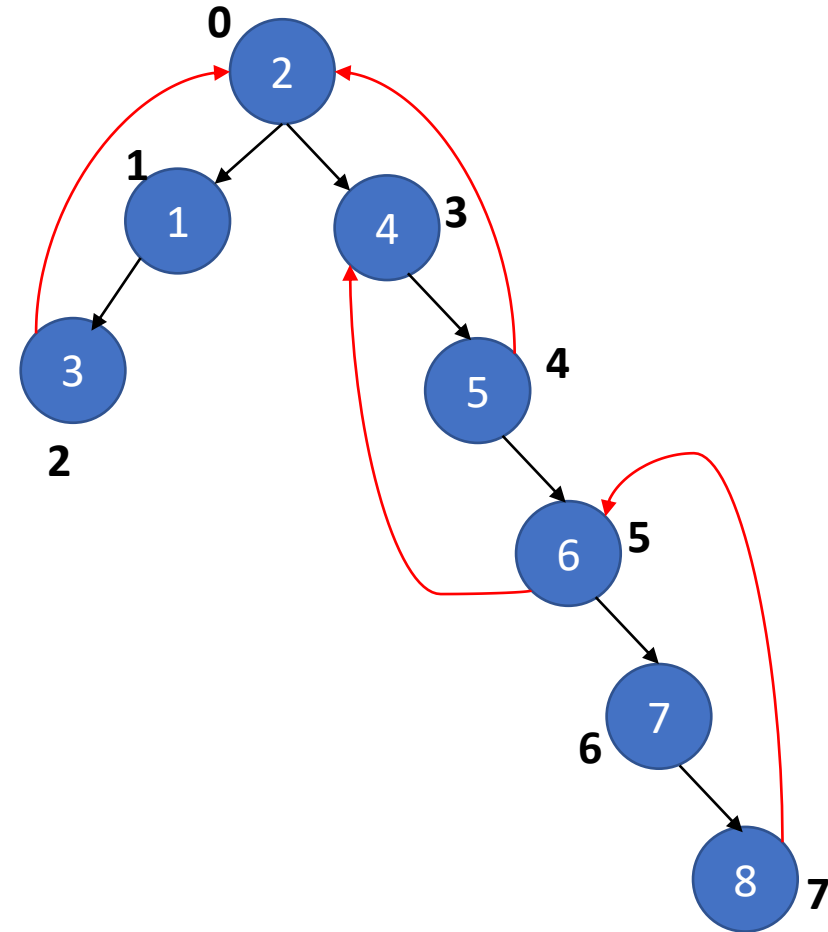
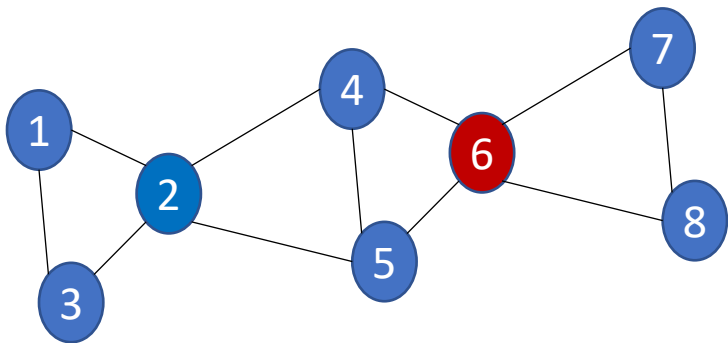
The root of a DFS-tree is an articulation point if and only if it has at least two children.



Bi-Connected Graph

Observation-2

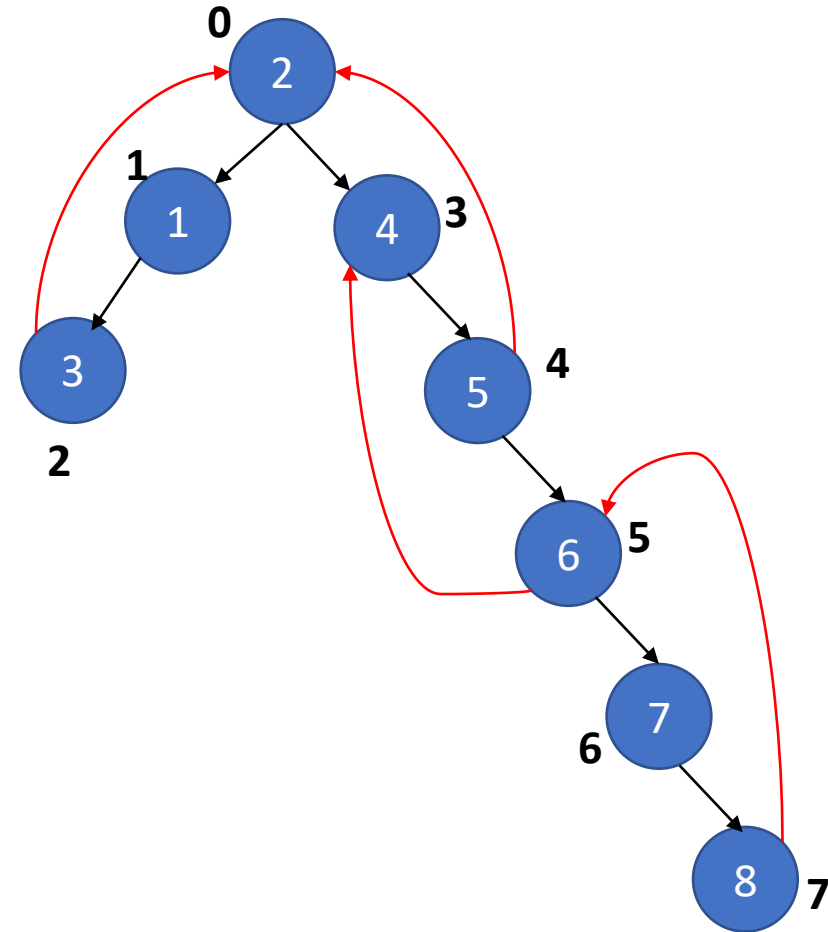
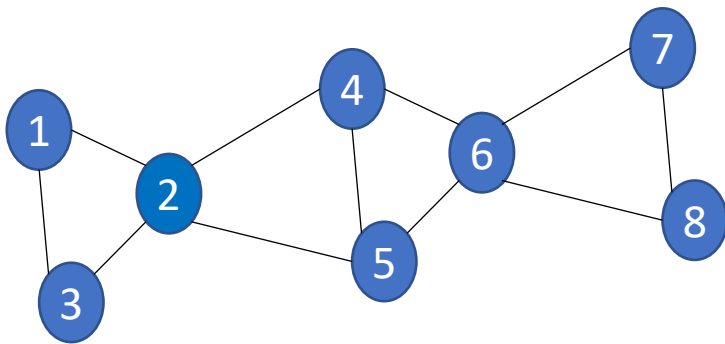
A non-root vertex v of a DFS-tree is an articulation point of G if and only if it has a child s such that there is no back edge from s or any descendant of s to a proper ancestor of v .



Bi-Connected Graph

Observation-2

Leaf of a DFS-tree are **never** articulation points

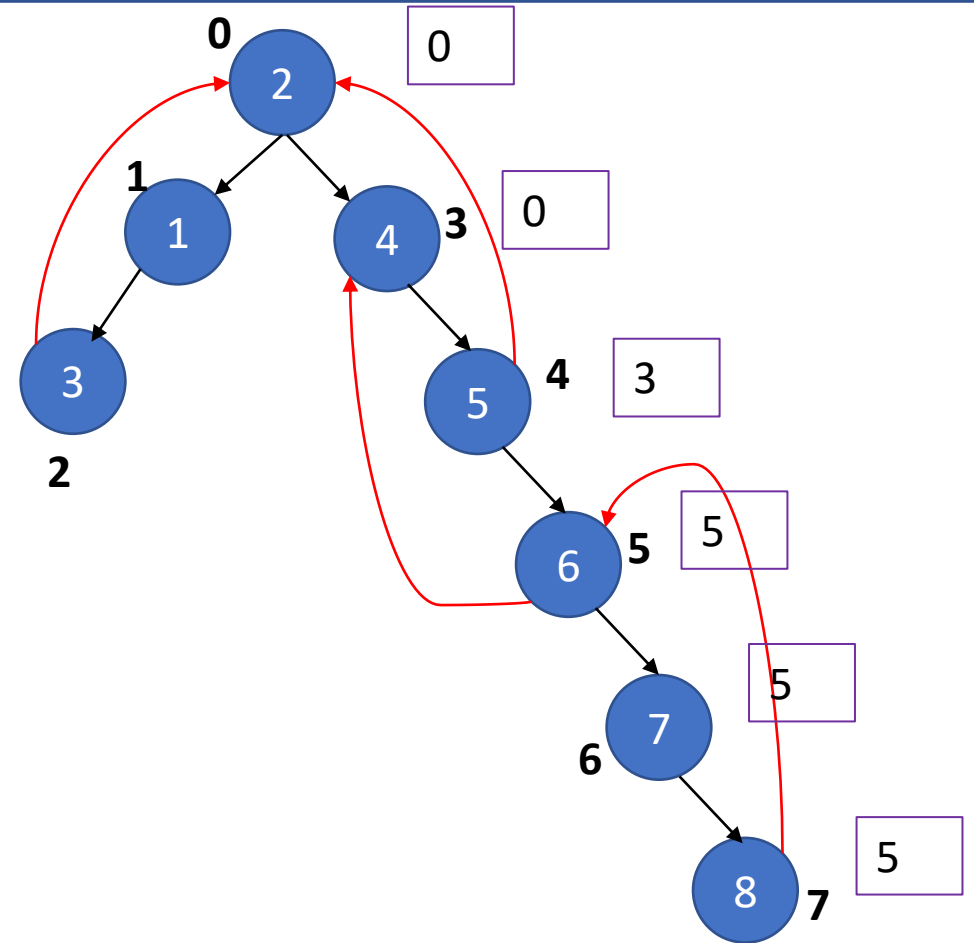


Bi-Connected Graph

Low Function

$LOW(u) =$

the highest ancestor (identified by its smallest discovery time) of u that can be reached from a descendant of u by using back-edges



Bi-Connected Graph

Observation

u is articulation point if it has a descendant v with $LOW(v) \geq u.d$

