
OPERATING SYSTEM: CSET209



READERS-WRITERS PROBLEM

- A data set is shared among a number of concurrent processes
 - Readers – only read the data set; they do **not** perform any updates
 - Writers – can both read and write
- Problem
 - Allow multiple readers to read at the same time
 - Only one single writer can access the shared data at the same time
- Shared Data
 - Data set
 - Semaphore **rw_mutex** initialized to 1
 - Semaphore **mutex** initialized to 1
 - Integer **read_count** initialized to 0

Table 1

CASES	Process 1	Process 2	Allowed/Not allowed
Case 1	Writer	Writer	Not allowed
Case 2	Reader	Writer	Not allowed
Case 3	Writer	Reader	Not allowed
Case 4	Reader	Reader	Allowed

READERS-WRITERS PROBLEM

- The structure of a writer process

```
do {
    wait(rw_mutex);

    ...
    /* writing is performed */
    ...
    signal(rw_mutex);
} while (true);
```

The structure of a reader process

```
do {
    wait(mutex);
    read_count++;
    if (read_count == 1)
        wait(rw_mutex);
    signal(mutex);

    ...
    /* reading is performed */
    ...
    wait(mutex);
    read_count--;
    if (read_count == 0)
        signal(rw_mutex);
    signal(mutex);
} while (true);
```

READERS-WRITERS PROBLEM (PRACTICE QUESTION)

Reader and writer problem

```
int R=0, W=0;
semaphore mutex=1;
void reader(void)
{
    L1: down(mutex);
    if(w==1)
    {
         → 1
        goto L1;
    }
    Else
    {
        R=R+1;
         → 2
    }
     DB
    down(mutex);
    R=R-1;
    up(mutex);
}
```

```
void writer(void)
{
    L2 : down(mutex);
    If (  ) → 3
    {
        up(mutex);
        goto L2;
    }
    W=1;
    up(mutex);
     DB
    down(mutex);
    W=0;
    up(mutex);
}
```

What should be the values of blanks 1, 2, 3 to synchronization classical reader and writer algorithm?

- (a) up(mutex), up(mutex), W = 1.
- (b) down(mutex), up(mutex), W = 1.
- (c) down(mutex), up(mutex), R >= 1 or W = 1.
- (d) up(mutex), up(mutex), R >= 1 or W = 1.

READERS-WRITERS PROBLEM (PRACTICE QUESTION)

Let $m[0] \dots m[4]$ be mutexes (binary semaphores) and $P[0] \dots P[4]$ be processes. Suppose each process $P[i]$ executes the following:

`wait (m[i]);`

`wait(m[(i+1) mode 4]);`

----- CS

`release (m[i]);`

`release (m[(i+1)mod 4]);`

Let initial value of mutex is 1

This could cause: (A) Mutual exclusion is satisfied (B) mutual exclusion is not satisfied (C) deadlock

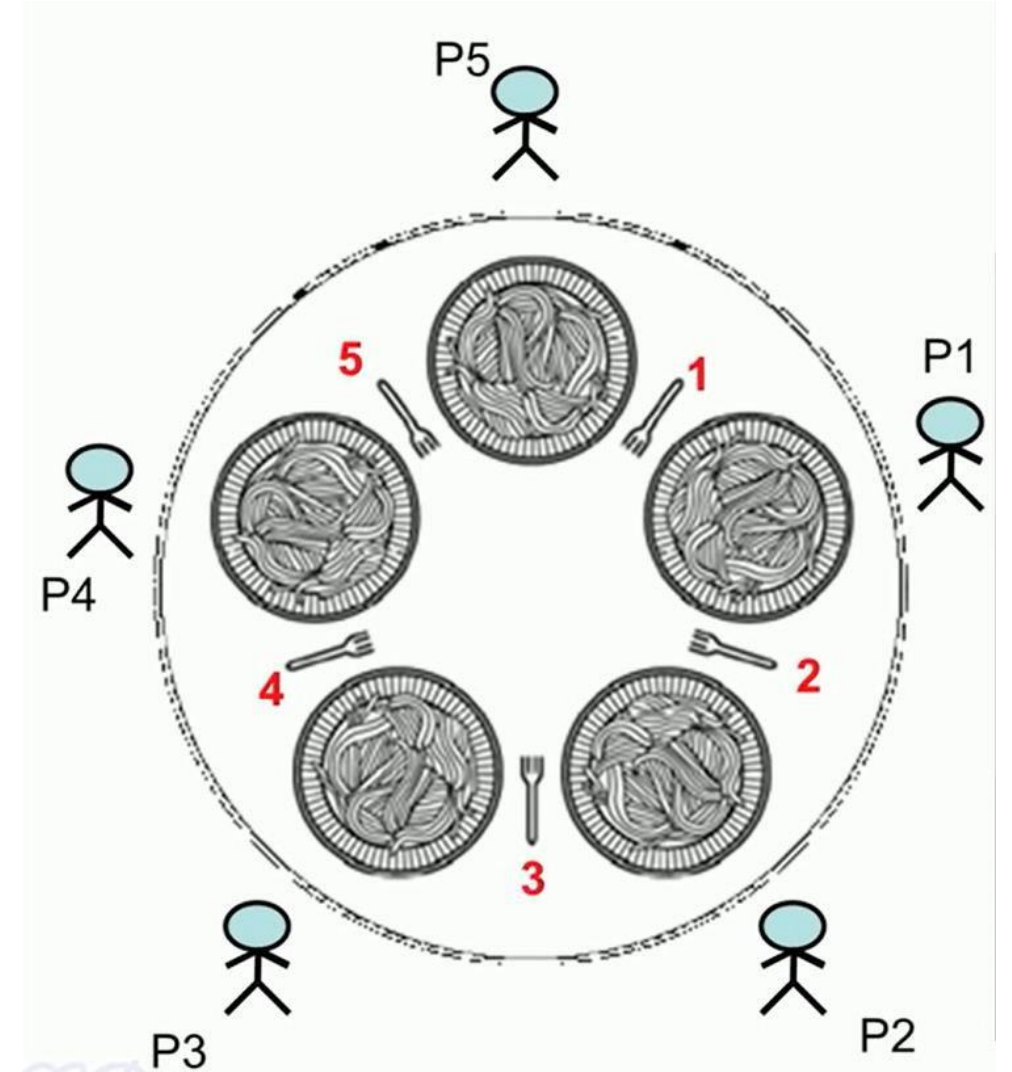
Which of the above are true

- 1) Only A
- 2) Only B
- 3) Only A and C
- 4) Only B and C

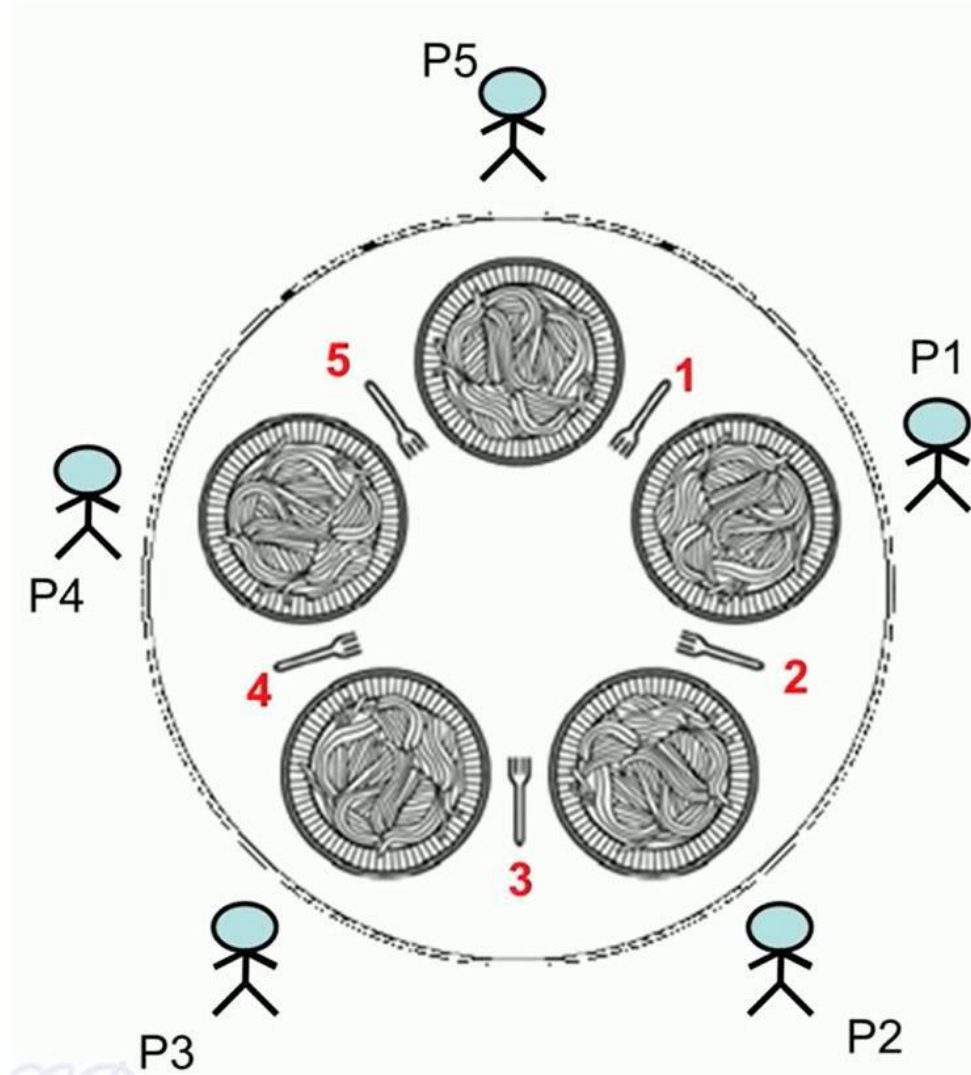
DINING PHILOSOPHERS PROBLEM

The dining philosophers problem is a classic synchronization problem involving the **allocation of limited resources** amongst a group of processes in a **deadlock-free and starvation-free manner**.

- Consider 5 philosophers (processes), sitting around a table.
- Alternating between two activities: eating and thinking.
- To eat, philosopher needs to **hold both forks** (left and right).
- When a philosopher thinks, it puts down both **forks** (or chopsticks) in their original locations.



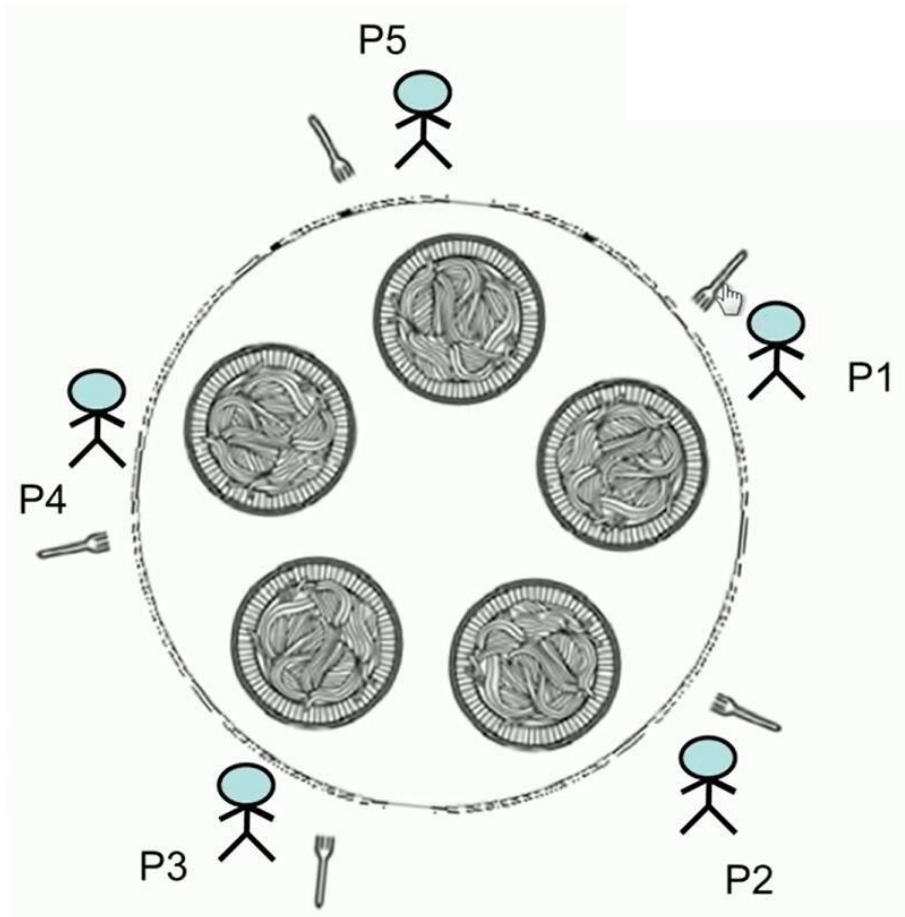
DINING PHILOSOPHERS: FIRST SIMPLE TRY



```
#define N 5
```

```
void philosopher(int i){  
    while(TRUE){  
        think(); // for some_time  
        take_fork(Ri);  
        take_fork(Li);  
        eat();  
        put_fork(Li);  
        put_fork(Ri);  
    }  
}
```

DINING PHILOSOPHERS: FIRST SIMPLE TRY

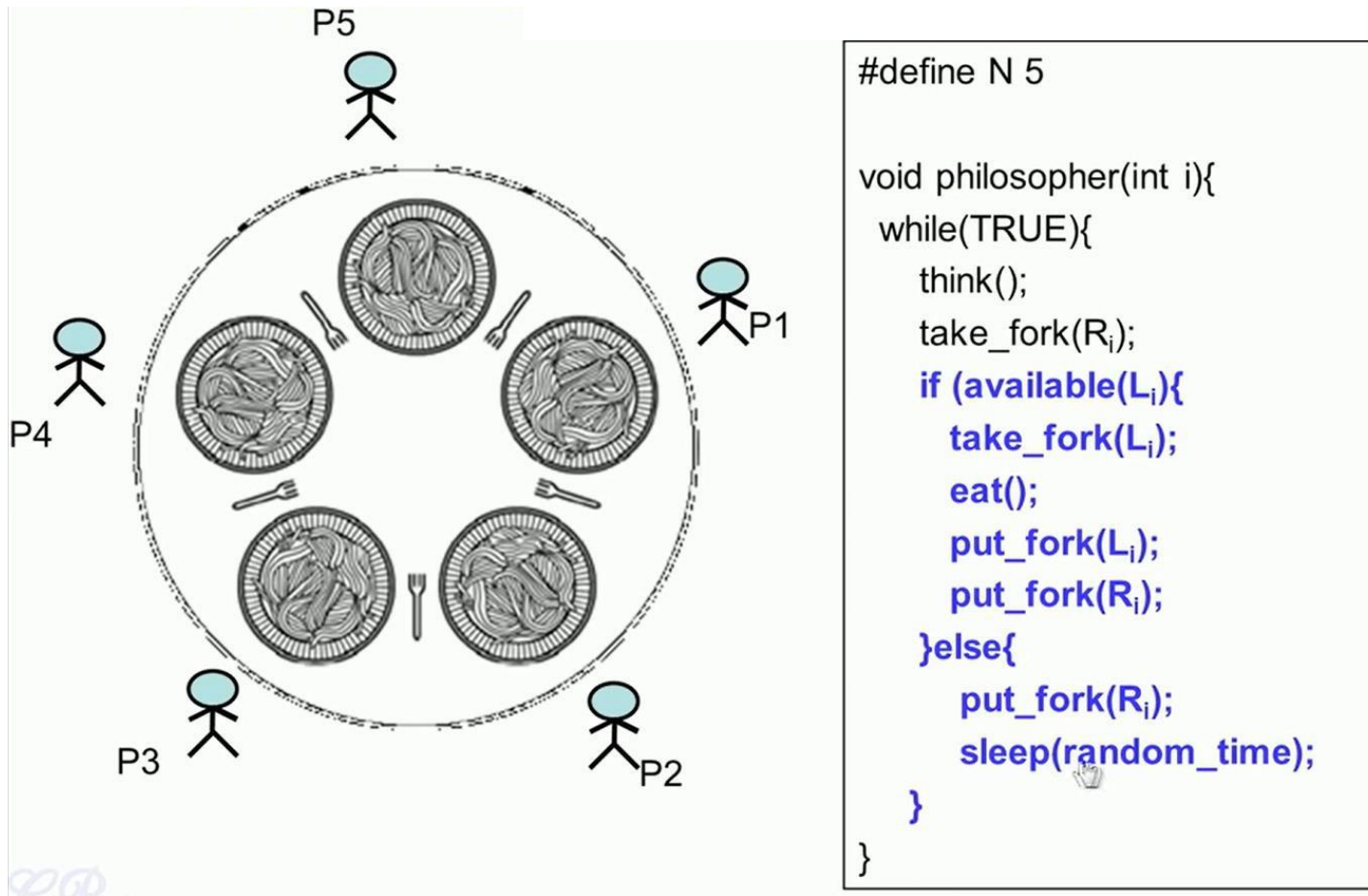


```
#define N 5

void philosopher(int i){
    while(TRUE){
        think(); // for some_time
        take_fork(R_i);
        take_fork(L_i);
        eat();
        put_fork(L_i);
        put_fork(R_i);
    }
}
```

If all the philosophers decide to take their **right fork at the same time**, then **it will be a deadlock** i.e. a situation where processes continue to run indefinitely without making any progress.

DINING PHILOSOPHERS: SECOND TRY



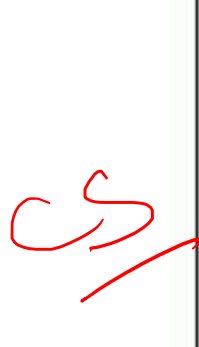
This solution **reduces the possibility** of starvation but does not guarantee it.

DINING PHILOSOPHERS: THIRD TRY

- Protects the critical sections using a **mutex**.
- Is deadlock prevention guaranteed here?
Yes
- Issue involved:
Only one process can eat at a time.

```
#define N 5

void philosopher(int i){
    while(TRUE){
        think(); // for some_time
        lock(mutex);
        take_fork(R_i);
        take_fork(L_i);
        eat();
        put_fork(L_i);
        put_fork(R_i);
        unlock(mutex);
    }
}
```



DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

Uses N semaphores ($s[1], s[2], \dots, s[N]$) all initialized to 0, and a mutex ✓
Philosopher has 3 states: HUNGRY, EATING, THINKING
A philosopher can only move to EATING state if neither neighbor is eating

```
void philosopher(int i){  
    while(TRUE){  
        ✓ think();  
        ✓ take_forks(i);  
        eat();  
        put_forks();  
    }  
}
```

```
void take_forks(int i){  
    lock(mutex); ✓  
    state[i] = HUNGRY;  
    test(i);  
    unlock(mutex);  
    down(s[i]);  
}
```

```
void put_forks(int i){ ✓  
    lock(mutex);  
    state[i] = THINKING;  
    test(LEFT);  
    test(RIGHT);  
    unlock(mutex);  
}
```

```
void test(int i){ ✓  
    if (state[i] = HUNGRY && state[LEFT] != EATING && state[RIGHT] != EATING){  
        state[i] = EATING;  
        up(s[i]);  
    }  
}
```

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

	P1	P2	P3	P4	P5
state	T	T	T	T	T
semaphore	0	0	0	0	0

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

	P1	P2	P3	P4	P5
state	T	T	H	T	T
semaphore	0	0	0	0	0

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

	P1	P2	P3	P4	P5
state	T	T	E	T	T
semaphore	0	0	0	0	0


DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        eat();
        put_forks();
    }
}
```


```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```



	P1	P2	P3	P4	P5
state	T	T	E	T	T
semaphore	0	0	1	0	0



DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

s[i] is 1, so down will not block.
The value of s[i] decrements by 1.

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

	P1	P2	P3	P4	P5
state	T	T	E	T	T
semaphore	0	0	0	0	0

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        → eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

	P1	P2	P3	P4	P5
state	T	T	E	T	T
semaphore	0	0	0	0	0

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        → take_forks(i);
        → eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

	P1	P2	P3	P4	P5
state	T	T	E	T	T
semaphore	0	0	0	0	0

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        → eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

	P1	P2	P3	P4	P5
state	T	T	E	H	T
semaphore	0	0	0	0	0

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        → eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    → down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

blocked

	P1	P2	P3	P4	P5
state	T	T	E	H	T
semaphore	0	0	0	0	0

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

blocked

	P1	P2	P3	P4	P5
state	T	T	E	H	T
semaphore	0	0	0	0	0

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

blocked

	P1	P2	P3	P4	P5
state	T	T	T	H	T
semaphore	0	0	0	0	0

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES

```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

blocked

	P1	P2	P3	P4	P5
state	T	T	T	E	T
semaphore	0	0	0	1	0

P1, P3, P5
P2, P4, P5

DINING PHILOSOPHERS: FINAL SOLUTION WITH SEMAPHORES


```
void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        eat();
        put_forks();
    }
}
```

```
void take_forks(int i){
    lock(mutex);
    state[i] = HUNGRY;
    test(i);
    unlock(mutex);
    down(s[i]);
}
```

```
void put_forks(int i){
    lock(mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    unlock(mutex);
}
```

```
void test(int i){
    if (state[i] = HUNGRY &&
        state[LEFT] != EATING &&
        state[RIGHT] != EATING){
        state[i] = EATING;
        up(s[i]);
    }
}
```

wakeup

P1	P2	P3	P4	P5
T	T	T		T
0	0	0	0	0

MONITORS

- Monitors are a higher-level synchronization construct that simplifies process synchronization by providing a high-level abstraction for data access and synchronization.
- Monitors are implemented as programming language constructs, typically in object-oriented languages, and provide mutual exclusion, condition variables, and data encapsulation in a single construct.
- A monitor is essentially a module that encapsulates a shared resource and provides access to that resource through a set of procedures.
- The procedures provided by a monitor ensure that only one process can access the shared resource at any given time, and that processes waiting for the resource are suspended until it becomes available.

MONITORS

```
Monitor Demo //Name of Monitor
{
variables;
condition variables;

procedure p1 {...}
prodecure p2 {...}

}
```

Syntax of Monitor

Condition Variables: Two different operations are performed on the condition variables of the monitor.

- Wait e.g. x.wait() or wait(x)
- Signal e.g. x.signal() or signal (x)



Thank you